

L7 Drive

Designing your future with
LS Mecapion L7 Series.

Your reasonable selection for total solution

The wide range of LS Mecapion line up will satisfy your requirements for the motion system through optimal application and use of the products.

With the excellent functionality, high precision and high-speed control, LS Mecapion AC servo system is customer-friendly and cost-effective.



Moving towards tomorrow

The Best Automation **Brand** in Korea
The World Class Leader in Automation System

LS Mecapion has supplied not only the servo drives and servo motors of high quality and high efficiency but also rotary encoders and actuators for the Korean and Global Industries for the past 20 years.

We are making efforts to provide a variety of products to our customers all over the world to satisfy their requirements. We have provided cutting-edge technologies that consider the needs of our customers by adopting the best functionality as well as innovative ideas.

We have accumulated a deep and wide range of experiences in the field of the control system for years and are venturing into new possibilities to provide the technologies of a higher level to our customers.

We hope that you don't miss the opportunity to use the proven, **world-class products** from **LS Mecapion** to improve the performance and value of your equipment.

We hope that we can provide the best services and partnerships for our customers by utilizing our expertise and technologies.



L7 SERIES SYSTEM

Features of L7 Drive

Compact Size

| Capacity | 400W | | | 1kW | | | 3.5kw | | |
|----------|------|-----|------------|-----|-----|------------|-------|-----|------------|
| Series | L7 | VS | Competitor | L7 | VS | Competitor | L7 | VS | Competitor |
| L [mm] | 38 | 80 | 40 | 58 | 88 | 60 | 88 | 137 | 90 |
| W [mm] | 169 | 187 | 168 | 169 | 210 | 168 | 169 | 256 | 168 |
| H [mm] | 173 | 132 | 170 | 198 | 195 | 195 | 198 | 225 | 195 |

Compared with VS

Slim up to
52%
More

Compared with a representative competitor

Slim up to
5%
More

Ultra-thin 38 mm width (400 W)

Its small footprint allows flexible installation, reducing the size of the equipment.

400W



1kW



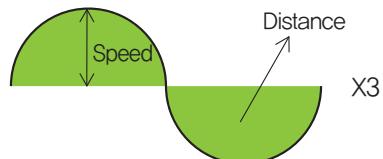
3.5kW



Easy to USE

The automatic inertia detection function for easier gain adjustment.

- Fast and accurate inertia detection
- Off-line tuning
- Parameters for inertia detection (speed and distance) provided



Encoder based on two-way high-speed serial communication

- Automatic recognition for motors and encoders
- BiSS protocol
- Wire-saving system (7-line) for encoder, resistant to noise

BiSS
INTERFACE

Support for various motors and encoders [L7NH and L7P Series]

- Support for standard BiSS encoders as well as other encoders

| Motor | Encoder |
|--------|-----------------------------|
| Rotary | Quadrature / BiSS Interface |
| DD | Tamagawa serial absolute |
| Linear | EnDat 2.2 / Resolver |

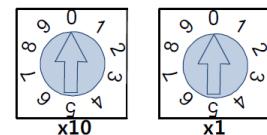
Features of L7 Drive

● Sufficient input/output contacts and various functions

- L7S: Digital input contacts: 10, output contacts: 8 / Analog input contacts: 2 and output contacts: 2
- L7N: Digital input contacts: 6, output contacts: 4 / Analog input contacts: 2 and output contacts: 2
- L7NH: Digital input contacts: 8, output contacts: 4 / Analog input contacts: 1 and output contacts: 2
- L7P: Digital input contacts: 16, output contacts: 8 / Analog input contacts: 2 and output contacts: 2
- PEGASUS: Digital input contacts: 4, output contacts: 2 / Analog input contacts: 1 and output contacts: 1
- Flexible assignment of input/output signals by parameters and contact setting based on the input/output contact type (N.O / N.C contacts)

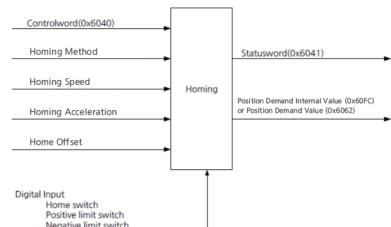
● Using the rotary switch to configure the drive node address [L7NH, L7P, and PEGASUS]

- Using the rotary switch to configure the drive node address conveniently
- L7NH: 0–99, L7P: 0–31, PEGASUS: 0–15



● Various homing functions [L7NH, L7P, and PEGASUS]

- The drive provides the homing function.
- You can specify the speed, acceleration, offset, and homing method.



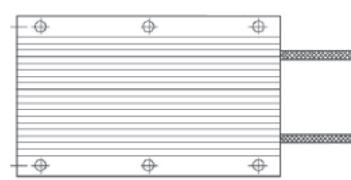
● Easy firmware upgrade [L7NH, L7P, and PEGASUS]

- Supporting the USB OTG function to allow firmware download with a USB memory
- Useful where space is limited or environmentally unfavorable



● Built-in regenerative braking resistance in the drive

- Drive installed inside to improve user convenience (100 W – 3.5 kW)
- Providing the connection for external installation
- Enhanced protection algorithm



● Plug-in type power connector

- Expanded to 100 W – 3.5 kW for improved wiring convenience



L7 SERIES SYSTEM

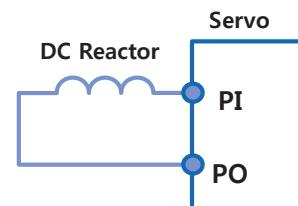
Features of L7 Drive

■ Reliability

- Main capacitor quality improved
 - Long-life type capacitor applied (2.5 times improvement)

- Convenient DC reactor installable

- Power connection to DC-link
 - Easier wiring and smaller size compared to 3-phase AC reactor
 - Connection for DC input (PI, N)



- Stable turn-off function based on the detection of the control power turn-off

- CE certification and RoHS certification



- Enhanced protection function

- Triple protection function for the protection of power module
 - Detection of the main power phase loss
 - Temperature sensor installed in the drive and motor for the prevention of overheat
 - Alarm code grouping and dedicated output contacts (ALO0, ALO1, ALO2)
 - Warning function (Digital output WARN)

■ High Performance

- Serial encoder of high resolution (with Biss C)

- Stability improved during precision position control and low-speed operation

- Stable low-speed properties based on precise speed measurement

- Stable speed measurement at low speed

- Calculation speed improved [L7NH, L7P, and PEGASUS]

- FPU (Floating Point Unit) for reliable precision calculation
 - 16 kHz switching frequency for precision current control
 - 32 bit operation for increased synchronous command processing rate (MIPS)

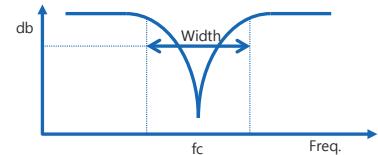
- Dedicated PC program

- L7S, and L7N: LIVE-I.C.E / L7NH, L7P, and PEGASUS: Drive CM
 - PC program for shortened equipment tuning time and debugging
 - Monitoring for speed, torque, current feedback, position values and positional error values and alarm occurrence time

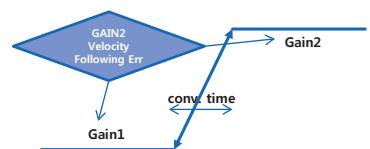
Features of L7 Drive

■ Intelligent Control

- Notch filter for resonance suppression
 - 4-step notch filter
 - 2-step vibration suppression filter at the load position
 - FFT function for real-time frequency analysis



- Various gain switching modes for improved control performance
 - P/PI auto-switching function to reduce overshooting during acceleration/deceleration
 - Various Gain1 ↔ Gain2 switching modes



- Various dynamic brake control modes
 - Configuring the operation mode at stop and after stop

■ Network Based – EtherCAT Network Type

- A wide range of products
 - L7N: EtherCAT communication command type
 - L7NH: All-in-one EtherCAT communication command type
 - PEGASUS: Motor drive-integrated EtherCAT communication command type

Field Bus



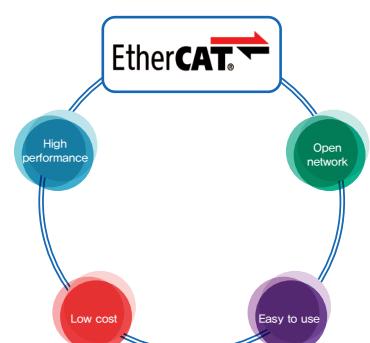
- High performance
 - Synchronization mechanism of high speed, high accuracy, and real-time communication
 - Various Gain1 ↔ Gain2 switching modes

- Open network
 - An international standard network with 1,600 members over the world

- Low cost
 - Standard Ethernet connector and cabling supported and slave–master implemented at a low cost

- Easy to use
 - Various topology types supported and easy diagnosis for devices

- L7 drive with a built-in EtherCAT interface
 - 100BASE-TX (100 Mbps) real-time communication
 - CiA402 (IEC61800-7) drive profile supported
 - Connection with various masters and slaves
 - Up to 100 m connection between nodes
 - Precision synchronization mechanism of 1 us or less



L7 SERIES SYSTEM

Features of L7 Drive

● Various operation modes

- L7N: Using the EtherCAT communication to support Cyclic (P/S/T) and Profile (P/S/T) modes
- L7NH and PEGASUS: Using the EtherCAT communication to support Cyclic & Profile (P/S/T) modes, EOE, COE, and FOE

● Safe torque off function

- Torque-off forced by hardware signals without involvement of the drive CPU and FPGA (ASIC); international standards adopted (IEC61508))

● Flexible I/O setup

- Mapping and level (A/B) setup by parameters

● High-speed position capture

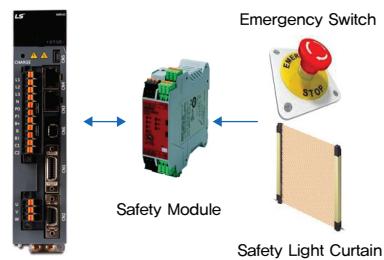
- Touch probe function (PROBE1 and PROBE2)

● Adjustment function linked with XGT series from LSIS

- Inertia detection, position/speed gain manual adjustment, gain switching setup, etc.

● EtherCAT drive compatibility

- Verified by CTT (Conformance Test Tool)

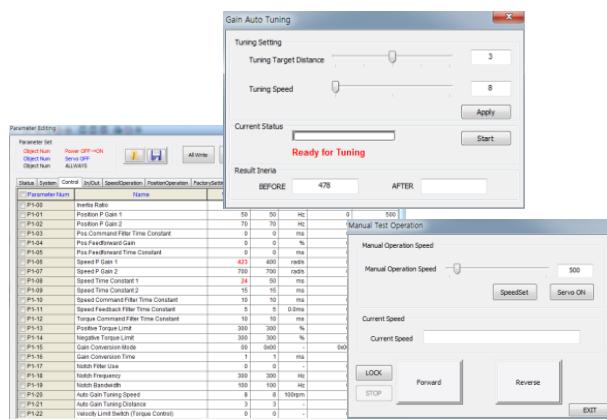
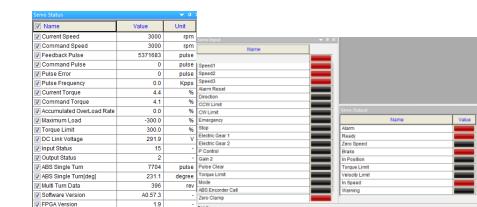
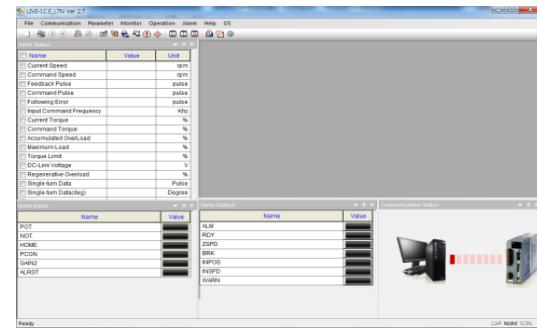


Servo Setup Software

Live-I.C.E : L7S and L7N Series

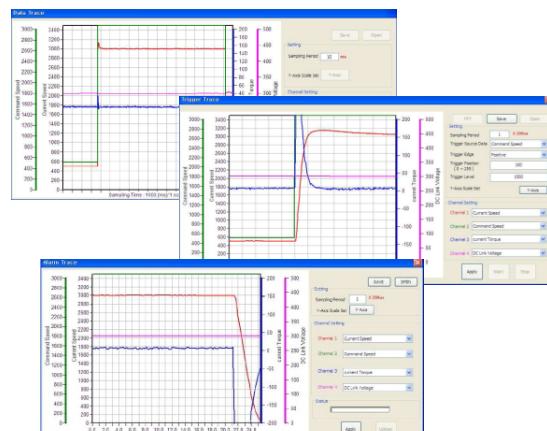
● Monitoring function

- Monitoring for I/O input contact and I/O output contact
- Driving Information monitoring: Monitoring and displaying the parameter values
- Communication connection monitoring : Displaying the current communication connection status using animation in real time



● Setup function

- Using the PC to read and write parameters
- Manual JOG function: Manual jog speed adjustment and forward/reverse test
- Automatic gain tuning
- Alarm history and alarm reset



● Graph function

- Data Trace: Graphic presentation of pre-defined channels in real time
- Trigger Monitoring: Graphic presentation by the channel and trigger settings
- Alarm Trace: Graphic presentation of alarm history for channels



● Download software

- OS Download: Firmware version upgrade software

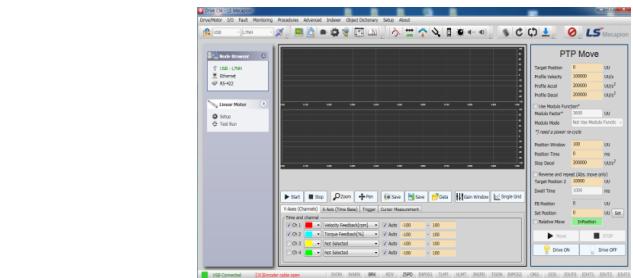
L7 SERIES SYSTEM

Servo Setup Software

Drive CM : L7NH, L7P and PEGASUS Series

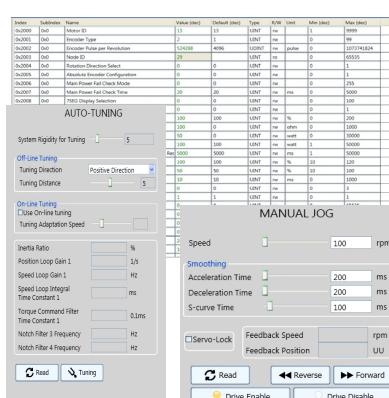
I/O CONFIGURATION

- Setting the output function and its signal level for I/O input contacts and I/O output signal pins
- Limiting the analog input torque and using the analogue voltage to override the speed
- Analog monitoring output for the gain tuning or internal state variables of the drive



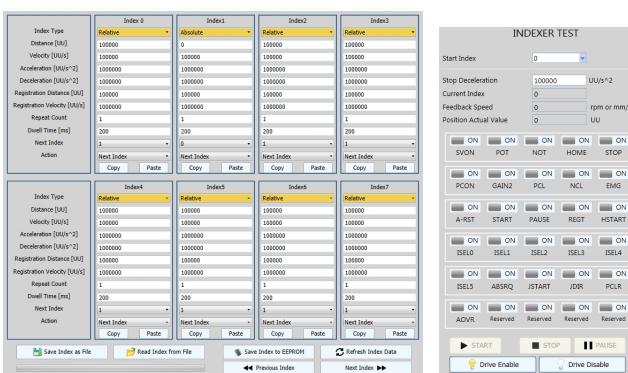
Monitoring function

- Implementation of 4-channel tracer or trigger monitor
- Performing various operations, including Manual Jog, Program Jog, PTP Move, etc., and monitoring the operation state
- Monitoring Zoom or Pan / Mouse Wheel / Rollover or Cursor



Setup function

- Configuring the data structure including parameters, state variables, commands, etc, inside the drive
- Using Manual Jog and Program Jog to carry out the test
- Using Offline Auto Tuning for one-touch adjustment
- Customer convenience functions such as PTP movement, homing, and touch probe



Indexer setup [L7P only]

- Using Index Edit to enter/configure the index parameters
- Using Indexer Test to configure the operation and provide testing function

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L7 SERIES SYSTEM

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L7N Series

EtherCAT Communication Command Type

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L7NH Series

All-in-one EtherCAT Communication Command Type

- Servo Drive Designation _ 31
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L7P Series

Indexer Function Type

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General Pulse Type, Analog Command Type

I L7S Series



■ Servo Drive Designation

| L7 | S | A | 004 | B | AA |
|----------------------|-----------------------|--------------------------|---|--|-----------------------|
| Model Name | Communication | Input Power Supply | Capacity | Encoder Type | Option |
| Servo Series | S : Standard I/O Type | A : 200VAC B : 400VAC | 001 : 100W 002 : 200W 004 : 400W 008 : 750W 010 : 1.0kW 020 : 2.0kW 035 : 3.5kW 050 : 5.0kW 075 : 7.5kW 150 : 15.0kW | A : Quadrature (Pulse Type) B : Serial (Communication Type) | Exclusive Option Code |
| * Range | | | | | |
| · 200V : 0.1kW~5.0kW | | | | | |
| · 400V : 1.0kW~15kW | | | | | |

L7 SERIES SYSTEM

L7S Series

Characteristic

● Easy to USE

- Easy Gain Tuning with Automatic Inertia Estimating Function
- Easy Setting Built-in Panel Operator
- Many I/O Contacts and Various Functions
(Digital Input: 10 contacts, Digital Output: 8 contacts / Analog input, output : 2 contacts)]

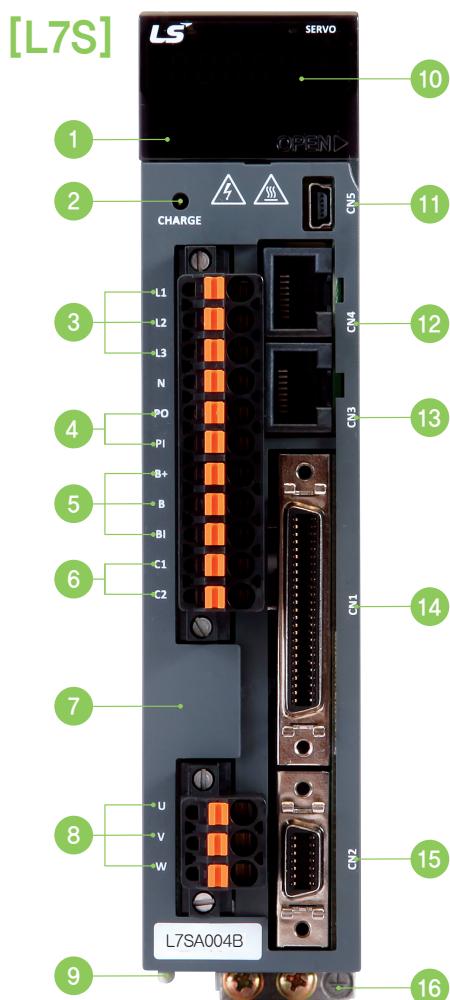
● Reliability for Protection Function

- CE, RoHS Certificated
- Drive Protection Function and Warning Function

● High Response for Precision Control

- High Resolutions Serial type Encoder(19Bit, BiSS)
- Improved Speed Response($\approx 1\text{Khz}$) Frequency

Identifying the Part of L7S



- ① Operation keys (Mode, Up, Down, Set)
- ② Charge Lamp
- ③ Main Power Connector (L1, L2, L3)
- ④ DC Reactor Connector(PO, PI)
 - Short-Circuit when not used
- ⑤ Regenerative resistance connector (B+, B, BI)
 - Short-Circuit B, BI terminals when standard type
 - Use B+, B terminals when using external resistor
- ⑥ Control Power Connector (C1, C2)
- ⑦ Front Cover
- ⑧ Motor Power Cable Connector (U, V, W)
- ⑨ Heat Sink
- ⑩ Display
- ⑪ CN5 : USB Connector
- ⑫ CN4 : RS-422 Communication Connector
- ⑬ CN3 : RS-422 Communication Connector
- ⑭ CN1 : Control Signal Connector
- ⑮ CN2 : Encoder Signal Connector
- ⑯ Ground

L7S Drive Combination Table

■ L7SA Incremental Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder Cable | Power Cable | | |
|-------------------|---------------------|-------------|------------------|------------------|-----------------------|---------------|-------------|---------------|-------|
| | | | | | Quadrature Type | INC | For power | Power + Brake | Brake |
| 3,000 | 5,000 | □40 | SAR3A | L7SA001A | * 2,048 P/R | APCS-E□□□AS | APCS-P□□□GS | APCS-P□□□KB | |
| | | □40 | SAR5A | L7SA001A | | | | | |
| | | □40 | SA01A | L7SA001A | | | | | |
| | | □40 | SA015A | L7SA002A | | | | | |
| | | □60 | SB01A | L7SA002A | APCS-E□□□BS | APCS-P□□□HS | APCS-P□□□NB | | |
| | | □60 | SB02A | L7SA002A | | | | | |
| | | □60 | SB04A | L7SA004A | | | | | |
| | | □80 | SC04A | L7SA004A | | | | | |
| | | □80 | SC06A | L7SA008A | | APCS-P□□□IS | APCS-P□□□PB | | |
| | | □80 | SC08A | L7SA008A | | | | | |
| | | □80 | SC10A | L7SA010A | | | | | |
| | | □130 | SE09A | L7SA008A | APCS-E□□□JS | APCS-P□□□JS | APCS-P□□□LB | | |
| | | □130 | SE15A | L7SA020A | | | | | |
| | | □130 | SE22A | L7SA020A | | | | | |
| | | □130 | SE30A | L7SA035A | | | | | |
| | | □180 | SF30A | L7SA035A | | | | | |
| | | □180 | SF50A | L7SA050A | | | | | |
| 2,000 | 3,000 | □80 | SC03D | L7SA004A | * 3,000 P/R | APCS-E□□□AS | APCS-P□□□GS | APCS-P□□□KB | |
| | | □80 | SC05D | L7SA008A | | | | | |
| | | □80 | SC06D | L7SA008A | | | | | |
| | | □80 | SC07D | L7SA008A | | | | | |
| | | □130 | SE06D | L7SA008A | | APCS-E□□□BS | APCS-P□□□HS | APCS-P□□□NB | |
| | | □130 | SE11D | L7SA010A | | | | | |
| | | □130 | SE16D | L7SA020A | | | | | |
| | | □130 | SE22D | L7SA020A | | | | | |
| | | □180 | SF22D | L7SA020A | | APCS-P□□□IS | APCS-P□□□PB | | |
| | | □180 | LF35D | L7SA035A | | | | | |
| | | □180 | SG55D | L7SA050A | | | | | |
| | | □220 | SG22D | L7SA020A | | | | | |
| | | □220 | LG35D | L7SA035A | APCS-E□□□JS | APCS-P□□□JS | APCS-P□□□SB | | |
| | | □220 | SG55D | L7SA050A | | | | | |
| 1,500 | 3,000 | □130 | SE05G | L7SA008A | | | | | |
| | | □130 | SE09G | L7SA010A | | APCS-E□□□BS | APCS-P□□□HS | APCS-P□□□NB | |
| | | □130 | SE13G | L7SA020A | | | | | |
| | | □130 | SE17G | L7SA020A | | | | | |
| | | □180 | SF20G | L7SA035A | | APCS-P□□□IS | APCS-P□□□PB | | |
| | | 2,700 | □180 | LF30G | L7SA035A | | | | |
| | | 3,000 | □180 | SF44G | L7SA050A | | | | |
| | | 3,000 | □220 | SG20G | L7SA020A | | | | |
| | | 2,700 | □220 | LG30G | L7SA035A | | APCS-P□□□IS | APCS-P□□□SB | |
| | | 3,000 | □220 | SG44G | L7SA050A | | | | |
| | | □130 | SE03M | L7SA004A | APCS-E□□□JS | APCS-P□□□JS | APCS-P□□□NB | | |
| | | □130 | SE06M | L7SA008A | | | | | |
| | | □130 | SE09M | L7SA010A | | | | | |
| | | □130 | SE12M | L7SA020A | | | | | |
| | | □180 | SF12M | L7SA020A | | APCS-P□□□IS | APCS-P□□□PB | | |
| | | □180 | SF20M | L7SA035A | | | | | |
| 1,000 | 2,000 | 1,700 | □180 | LF30M | L7SA035A | APCS-E□□□JS | APCS-P□□□JS | APCS-P□□□LB | |
| | | 2,000 | □180 | SF44M | L7SA050A | | | | |
| | | □220 | SG12M | L7SA020A | APCS-P□□□IS | APCS-P□□□PB | | | |
| | | □220 | SG20M | L7SA035A | | | | | |
| | | 1,700 | □220 | LG30M | | L7SA035A | APCS-P□□□IS | APCS-P□□□LB | |
| | | 2,000 | □220 | SG44M | | L7SA050A | | | |
| | | □130 | SE03M | L7SA004A | APCS-E□□□BS | APCS-P□□□HS | APCS-P□□□SB | | |
| | | □130 | SE06M | L7SA008A | | | | | |
| | | □130 | SE09M | L7SA010A | | | | | |
| | | □130 | SE12M | L7SA020A | | | | | |
| | | □180 | SF12M | L7SA020A | | APCS-P□□□JS | APCS-P□□□JS | APCS-P□□□LB | |
| | | □180 | SF20M | L7SA035A | | | | | |
| 3,000 | 3,500 | □60 | HB01A | L7SA002A | * 1,024 P/R | APCS-E□□□AS | APCS-P□□□GS | APCS-P□□□SB | |
| | | □60 | HB02A | L7SA002A | | | | | |
| | | □60 | HB04A | L7SA004A | | | | | |
| | | □130 | HE09A | L7SA008A | * 2,048 P/R | APCS-E□□□BS | APCS-P□□□HS | APCS-P□□□SB | |
| | | □130 | HE15A | L7SA020A | | | | | |
| | | □130 | HE30A | L7SA050A | | | | | |

L7 SERIES SYSTEM

L7S Drive Combination Table

L7SA Serial Type

| L7S Series | | Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder Cable | | Power Cable | | |
|-------------|-------------|---------------------------|---------------------|---------------|------------------|------------------|-----------------------|---------------|--------------|--------------|--------------|--|
| Serial Type | Single Turn | Multi Turn | For power | Power + Brake | Brake | | | | | | | |
| 3,000 | 5,000 | 19Bit Serial / M-Turn Abs | APCS-E□□□□ES | APCS-E□□□□DS1 | APCS-P□□□□LS | APCS-P□□□□QS | APCS-P□□□□HS | APCS-P□□□□NB | APCS-P□□□□PB | APCS-P□□□□LB | APCS-P□□□□SB | |
| □40 | FALR5A | L7SA001B | | | | | | | | | | |
| □40 | FAL01A | L7SA001B | | | | | | | | | | |
| □40 | FAL015A | L7SA004B | | | | | | | | | | |
| □60 | FBL01A | L7SA001B | | | | | | | | | | |
| □60 | FBL02A | L7SA002B | | | | | | | | | | |
| □60 | FBL04A | L7SA004B | | | | | | | | | | |
| □80 | FCL04A | L7SA004B | | | | | | | | | | |
| □80 | FCL06A | L7SA008B | | | | | | | | | | |
| □80 | FCL08A | L7SA008B | | | | | | | | | | |
| □80 | FCL10A | L7SA010B | | | | | | | | | | |
| □60 | FB01A | L7SA001B | | | | | | | | | | |
| □60 | FB02A | L7SA002B | | | | | | | | | | |
| □60 | FB04A | L7SA004B | | | | | | | | | | |
| □80 | FC04A | L7SA004B | | | | | | | | | | |
| □80 | FC06A | L7SA008B | | | | | | | | | | |
| □80 | FC08A | L7SA008B | | | | | | | | | | |
| □80 | FC10A | L7SA010B | | | | | | | | | | |
| □130 | FE09A | L7SA010B | | | | | | | | | | |
| □130 | FE15A | L7SA020B | | | | | | | | | | |
| □130 | FE22A | L7SA020B | | | | | | | | | | |
| □130 | FE30A | L7SA035B | | | | | | | | | | |
| □180 | FF30A | L7SA035B | | | | | | | | | | |
| □180 | FF50A | L7SA050B | | | | | | | | | | |
| 2,000 | 3,000 | 19Bit Serial / M-Turn Abs | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□LS | APCS-P□□□□QS | APCS-P□□□□HS | APCS-P□□□□NB | APCS-P□□□□PB | APCS-P□□□□LB | APCS-P□□□□SB | |
| □80 | FCL03D | L7SA004B | | | | | | | | | | |
| □80 | FCL05D | L7SA008B | | | | | | | | | | |
| □80 | FCL06D | L7SA008B | | | | | | | | | | |
| □80 | FCL07D | L7SA008B | | | | | | | | | | |
| □80 | FC03D | L7SA004B | | | | | | | | | | |
| □80 | FC05D | L7SA008B | | | | | | | | | | |
| □80 | FC06D | L7SA008B | | | | | | | | | | |
| □80 | FC07D | L7SA008B | | | | | | | | | | |
| □130 | FE06D | L7SA008B | | | | | | | | | | |
| □130 | FE11D | L7SA010B | | | | | | | | | | |
| □130 | FE16D | L7SA020B | | | | | | | | | | |
| □130 | FE22D | L7SA020B | | | | | | | | | | |
| □180 | FF22D | L7SA020B | | | | | | | | | | |
| □180 | FF35D | L7SA035B | | | | | | | | | | |
| □180 | FF55D | L7SA050B | | | | | | | | | | |
| 1,500 | 3,000 | 19Bit Serial / M-Turn Abs | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□LS | APCS-P□□□□QS | APCS-P□□□□HS | APCS-P□□□□NB | APCS-P□□□□PB | APCS-P□□□□LB | APCS-P□□□□SB | |
| □80 | FE05G | L7SA008B | | | | | | | | | | |
| □130 | FE09G | L7SA010B | | | | | | | | | | |
| □130 | FE13G | L7SA020B | | | | | | | | | | |
| □130 | FE17G | L7SA020B | | | | | | | | | | |
| □180 | FF20G | L7SA020B | | | | | | | | | | |
| □180 | FF30G | L7SA035B | | | | | | | | | | |
| □180 | FF44G | L7SA050B | | | | | | | | | | |
| □130 | FG22D | L7SA020B | | | | | | | | | | |
| □220 | FG35D | L7SA035B | | | | | | | | | | |
| □220 | FG55D | L7SA050B | | | | | | | | | | |
| 1,000 | 2,000 | 19Bit Serial / M-Turn Abs | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□LS | APCS-P□□□□QS | APCS-P□□□□HS | APCS-P□□□□NB | APCS-P□□□□PB | APCS-P□□□□LB | APCS-P□□□□SB | |
| □130 | FE03M | L7SA004B | | | | | | | | | | |
| □130 | FE06M | L7SA008B | | | | | | | | | | |
| □130 | FE09M | L7SA010B | | | | | | | | | | |
| □130 | FE12M | L7SA020B | | | | | | | | | | |
| □180 | FF12M | L7SA020B | | | | | | | | | | |
| □180 | FF20M | L7SA020B | | | | | | | | | | |
| □180 | FF30M | L7SA035B | | | | | | | | | | |
| □180 | FF44M | L7SA050B | | | | | | | | | | |
| □220 | FG12M | L7SA020B | | | | | | | | | | |
| □220 | FG20M | L7SA020B | | | | | | | | | | |
| □220 | FG30M | L7SA035B | | | | | | | | | | |
| □220 | FG44M | L7SA050B | | | | | | | | | | |

L7S Drive Combination Table

L7SB Serial Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder Cable | | Power Cable | | |
|-------------------|---------------------|-------------|------------------|------------------|-----------------------|---------------|--------------|-------------|---------------|-------|
| | | | | | Serial Type | Single Turn | Multi Turn | For power | Power + Brake | Brake |
| 3,000 | 5,000 | | □130 | FEP09A | L7SB010B | | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | FEP15A | L7SB020B | | | | | |
| | | | □130 | FEP22A | L7SB035B | | | | | |
| | | | □130 | FEP30A | L7SB035B | | | | | |
| | | | □180 | FFP30A | L7SB035B | | | | | |
| | | | □180 | FFP50A | L7SB050B | | | | | |
| 2,000 | 3,000 | | □130 | FEP06D | L7SB010B | | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | FEP11D | L7SB010B | | | | | |
| | | | □130 | FEP16D | L7SB020B | | | | | |
| | | | □130 | FEP22D | L7SB020B | | | | | |
| | | | □180 | FFP22D | L7SB020B | | | | | |
| | | | □180 | FFP35D | L7SB035B | | | | | |
| | | | □180 | FFP55D | L7SB050B | | | | | |
| | 2,500 | | □180 | FFP75D | L7SB075B | | | APCF-P□□□JS | APCF-P□□□LB | |
| | 3,000 | | □220 | FGP22D | L7SB020B | | | | | |
| | | | □220 | FGP35D | L7SB035B | | | | | |
| | | | □220 | FGP55D | L7SB050B | | | | | |
| | | | □220 | FGP75D | L7SB075B | | | | | |
| 1,500 | 3,000 | | □130 | FEP05G | L7SB010B | APCS-E□□□DS | APCS-E□□□DS1 | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | FEP09G | L7SB010B | | | | | |
| | | | □130 | FEP13G | L7SB020B | | | | | |
| | | | □130 | FEP17G | L7SB020B | | | | | |
| | | | □180 | FFP20G | L7SB020B | | | | | |
| | 2,700 | | □180 | FFP30G | L7SB035B | | | APCF-P□□□JS | APCF-P□□□PB | |
| | 3,000 | | □180 | FFP44G | L7SB050B | | | | | |
| | | | □180 | FFP60G | L7SB075B | | | | | |
| | | | □180 | FFP75G | L7SB075B | | | | | |
| | 2,500 | | □220 | FGP20G | L7SB020B | | | APCF-P□□□MS | APCF-P□□□LB | |
| | | | □220 | FGP30G | L7SB035B | | | | | |
| | | | □220 | FGP44G | L7SB050B | | | | | |
| | | | □220 | FGP60G | L7SB075B | | | | | |
| | | | □220 | FGP85G | L7SB150B | | | | | |
| | 2,000 | | □220 | FGP110G | L7SB150B | | | APCF-P□□□MS | APCF-P□□□SB | |
| | | | □220 | FGP150G | L7SB150B | | | | | |
| 1,000 | 2,000 | | □130 | FEP03M | L7SB010B | | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | FEP06M | L7SB010B | | | | | |
| | | | □130 | FEP09M | L7SB010B | | | | | |
| | | | □130 | FEP12M | L7SB020B | | | | | |
| | | | □180 | FFP12M | L7SB020B | | | | | |
| | | | □180 | FFP20M | L7SB020B | | | | | |
| | 1,700 | | □180 | FFP30M | L7SB035B | | | APCF-P□□□JS | APCF-P□□□LB | |
| | 2,000 | | □180 | FFP44M | L7SB050B | | | | | |
| | | | □220 | FGP12M | L7SB020B | | | | | |
| | | | □220 | FGP20M | L7SB020B | | | | | |
| | | | □220 | FGP30M | L7SB050B | | | | | |
| | | | □220 | FGP44M | L7SB050B | | | | | |
| | | | □220 | FGP60M | L7SB075B | | | | | |

L7S Series
L7N Series
L7NH Series
L7P Series
S Series
F Series
MDM Series
PEGASUS Series
Options

L7 SERIES SYSTEM

L7SA Drive Product Features

| Item | Type Name | L7SA001□ | L7SA002□ | L7SA004□ | L7SA008□ | L7SA010□ | L7SA020□ | L7SA035□ | L7SA050□ |
|---------------------|----------------------|---|--|----------|----------|----------|----------|----------|----------|
| Input Power | Main Power Supply | 3 Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz] | | | | | | | |
| | Control Power Supply | Single Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz] | | | | | | | |
| | Rated Current[A] | 1.4 | 1.7 | 3.0 | 5.2 | 6.75 | 13.5 | 16.7 | 32 |
| | Peak Current[A] | 4.2 | 5.1 | 9.0 | 15.6 | 20.25 | 40.5 | 50.1 | 96 |
| | Encoder Type | Quad. Type Incremental Line Driver Max 6000 [P/R] Serial Type : 18bit(FA type), 19bit, 20bit(MDM series) | | | | | | | |
| Control Performance | Speed Control | Speed Control Range | Maximum 1: 5000 | | | | | | |
| | | Frequency Response | Maximum 1 [kHz] or above (When using 19bit Serial Encoder) | | | | | | |
| | | Speed Command | DC -10 [V]~+10 [V] (Reverse rotation in case of negative voltage) | | | | | | |
| | | Accel/Decel Time | Straight or S-curve acceleration/deceleration (0~10,000 [ms], possible to be set by one [ms] unit) | | | | | | |
| | | Speed Variation Ratio | ±0.01 [%] or lower [when load changes between 0 and 100%] ±0.1[%] or lower [temperature 25 ±10°C] | | | | | | |
| Control Performance | Position Control | Input Frequency | 1[Mpps], Line Driver / 200[kpps], Open Collector | | | | | | |
| | | Input Pulse Type | Symbol + Pulse Series, CW+CCW, A/B Phase | | | | | | |
| | | Electric Gear Ratio | Four digital gear ratios can be set, selected and tuned. | | | | | | |
| | Torque Control | Torque Command | DC -10~+10 [V] (Reverse direction torque in case of negative voltage) | | | | | | |
| | | Speed Limit | DC 0~10 [V], internal speed command within ±1[%] | | | | | | |
| Input/Output Signal | Analog Input | Repetition accuracy | Within ±1[%] | | | | | | |
| | | Input Range | DC -10 ~ 10[V] | | | | | | |
| | Analog Output | Resolution | 12[bit] | | | | | | |
| | | Output Range | DC -10 ~ 10[V] | | | | | | |
| | Digital Input | Resolution | 12[bit] | | | | | | |
| Communication | Digital Input | Total 10 Input Channels(assignment available) SVON, SPD1, SPD2, SPD3, ALMRST, DIR, CCWLIM, CWLIM, EMG, STOP, EGEAR1, EGEAR2, PCON, GAIN2, P_CLR, T_LMT, MODE, ABS_RQ, ZCLAMP Above 19 functions can be used selectively for assignment Signal can be set as positive logic or negative logic | | | | | | | |
| | | Total 5 Channels(assignment available), 3 Channels(set as alarm code) ALARM, READY, ZSPD, BRAKE, INPOS, TLMT, VLMT, INSPD, WARN Above 9 outputs can be used selectively for assignment Signal can be set as positive logic or negative logic | | | | | | | |
| | | Digital Output | | | | | | | |
| | | RS422 | Accessible to PC software and the RS422 server | | | | | | |
| | | USB | Status monitoring, JOG operation, parameter upload/download are available with PC Software | | | | | | |
| Built-in functions | Encoder | Encoder | Serial BiSS encoder and quadrature encoder supported | | | | | | |
| | | Encoder Output Type | Random pre-scale output through FPGA (maximum 6.4 Mpps) | | | | | | |
| | | Dynamic Braking | Standard built-in (activated when the servo alarm goes off or when the servo is off) | | | | | | |
| | | Regenerative Braking | Both default built-in and external installation possible | | | | | | |
| | | Display | Seven segments (5 DIGIT) | | | | | | |
| Environment | Protective Function | Setting Function | Loader (SET, MODE, UP, and [DOWN] keys) | | | | | | |
| | | Additional Function | Auto gain tuning, phase Z detection, manual JOG operation, program JOG operation, automatic analog input calibration | | | | | | |
| | | Protective Function | Overcurrent, overload, overvoltage, insufficient voltage, main power input problem, control power input problem, overspeed, motor cable, overheating(power module overheating, abnormal drive operation's temp), encoder problem, over-regenerative, sensor problem, communication problem | | | | | | |
| | | Temperature | 0 ~ 50[°C] | | | | | | |
| | | Humidity | Below 90[%]RH(avoid dew-condensation) | | | | | | |
| | | Environment | Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust. | | | | | | |

L7S Series

L7N Series

L7NH Series

L7P Series

S Series

F Series

MDM Series

Options

PEGASUS Series

L7SB Drive Product Features

| Item | Type Name | L7SB010B | L7SB020B | L7SB035B | L7SB050B | L7SB075B | L7SB150B |
|---------------------|----------------------|--|--|----------|----------|----------|----------|
| Input Power | Main Power Supply | 3 Phase AC380 ~ 480[V](-15 ~ +10[%]), 50 ~ 60[Hz] | | | | | |
| | Control Power Supply | Single Phase AC380 ~ 480[V](-15 ~ +10[%]), 50 ~ 60[Hz] | | | | | |
| | Rated Current[A] | 3.7 | 8 | 10.1 | 17.5 | 22.8 | 39 |
| | Peak Current[A] | 11.1 | 24 | 30.3 | 52.5 | 57 | 97.5 |
| | Encoder Type | Quad. Type Incremental Line Driver Max 6000 [P/R] Serial Type : 18bit(FA type), 19bit, 20bit(MDM series) | | | | | |
| Control Performance | Speed Control | Speed Control Range | Maximum 1: 5000 | | | | |
| | | Frequency Response | Maximum 1 [kHz] or above (when the 19-bit serial encoder is applied) | | | | |
| | | Speed Command | DC -10 [V]~+10 [V] (Reverse rotation in case of negative voltage) | | | | |
| | | Accel/Decel Time | Straight or S-curve acceleration/deceleration (0~10,000 [ms], possible to be set by one [ms] unit) | | | | |
| | | Speed Variation Ratio | ±0.01 [%] or lower [when load changes between 0 and 100%] ±0.1[%] or lower [temperature 25 ±10°C] | | | | |
| | Position Control | Input Frequency | 1[Mpps], Line Driver / 200[kpps], Open Collector | | | | |
| | | Input Pulse Type | Symbol + pulse series, CW+CCW, A/B phase | | | | |
| | | Electric Gear Ratio | Four digital gear ratios can be set, selected and tuned. | | | | |
| | Torque Control | Torque Command | DC -10~+10 [V] (Reverse direction torque in case of negative voltage) | | | | |
| | | Speed Limit | DC 0~10 [V], internal speed command within ±1[%] | | | | |
| Input/Output Signal | Analog Input | Input Range | DC 0 ~ 10[V] | | | | |
| | | Resolution | 12[bit] | | | | |
| | | Output Range | DC 0 ~ 10[V] | | | | |
| | | Resolution | 12[bit] | | | | |
| | Digital Input | | A total of 10 input channels (allocable) SVON, SPD1, SPD2, SPD3, ALMRST, DIR, CCWLIM, CWLIM, EMG, STOP, EGEAR1, EGEAR2, PCON, GAIN2, P_CLR, T_LMT, MODE, ABS_RQ, ZCLAMP You can selectively allocate a total of 19 functions. You can set the positive/negative logic of the selected signal. | | | | |
| | | | | | | | |
| | | | | | | | |
| | Digital Output | | A total of 5 channels (allocable), 3 channels (fixed with alarm codes) ALARM, READY, ZSPD, BRAKE, INPOS, TLMT, VLMT, INSPD, WARN You can selectively allocate a total of nine kinds of output. You can set the positive/negative logic of the selected signal. | | | | |
| | | | | | | | |
| Communication | RS422 | Accessible to PC software and the RS422 server | | | | | |
| | USB | Status monitoring through PC software, JOG operation, and parameter uploading/downloading are possible. | | | | | |
| | Encoder | Serial BiSS encoder and quadrature encoder supported | | | | | |
| | Encoder Output Type | Random pre-scale output through FPGA (maximum 6.4 Mpps) | | | | | |
| Built-in functions | Dynamic Braking | Standard built-in (activated when the servo alarm goes off or when the servo is off) | | | | | |
| | Regenerative Braking | Both default built-in and external installation possible | | | | | |
| | Display | Seven segments (5 DIGIT) | | | | | |
| | Setting Function | Loader (SET, MODE, UP, and [DOWN] keys) | | | | | |
| | Additional Function | Auto gain tuning, phase Z detection, manual JOG operation, program JOG operation, automatic analog input calibration | | | | | |
| | Protective Function | Overcurrent, overload, overvoltage, voltage lack, main power input error, control power input error, overspeed, motor cable, heating error (power module heating, drive temperature error), encoder error, excessive regeneration, sensor error, communication error | | | | | |
| Environment | Temperature | 0 ~ 50[°C] | | | | | |
| | Humidity | 90[%] RH or lower (no condensation) | | | | | |
| | Environment | Indoors, a place free from corrosive gas or combustible gas, or a place without liquid or conductive dust. | | | | | |

L7S Series

L7N Series

L7NH Series

L7P Series

S Series

F Series

MDM Series

PEGASUS Series

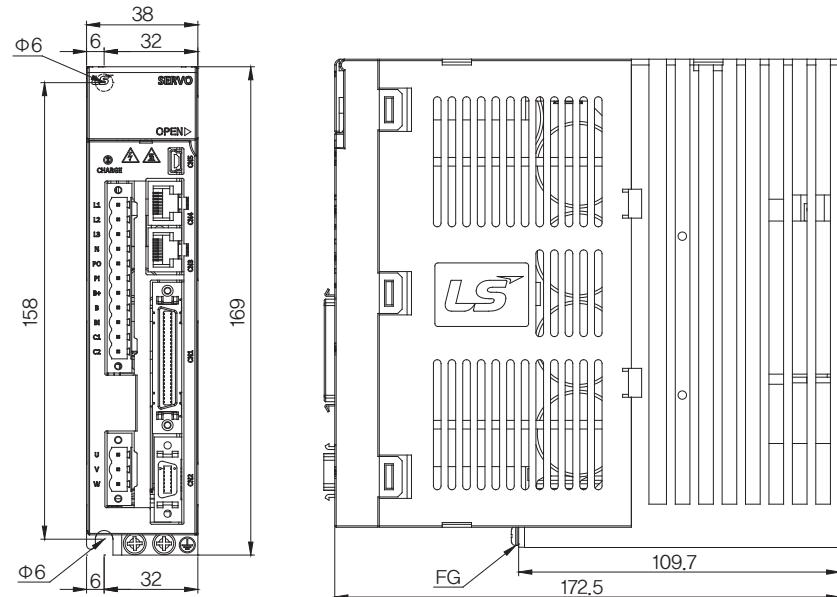
19

L7 SERIES SYSTEM

External Dimensions of L7SA Drive

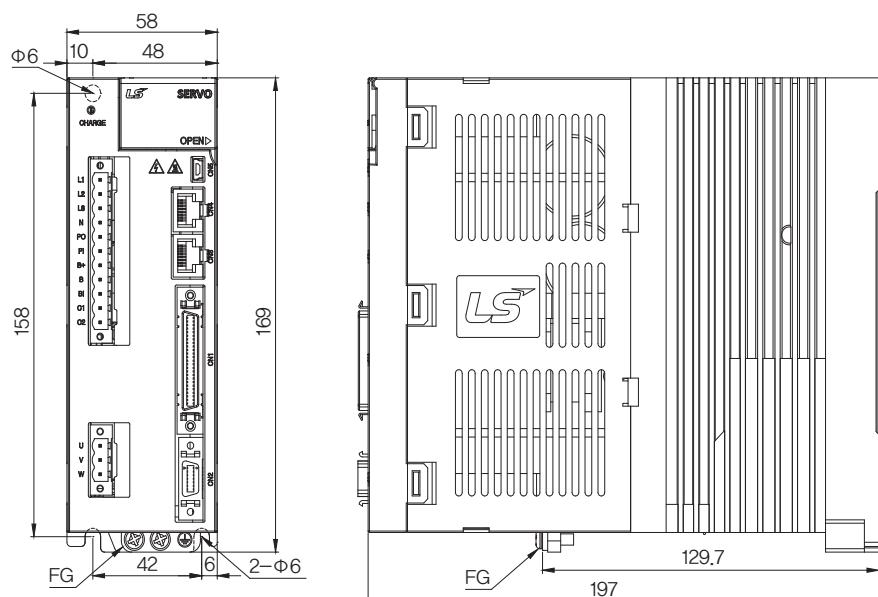
■ L7SA001□ ~ L7SA004□ [Weight : 1.2kg]

* Unit [mm]



■ L7SA008□ ~ L7SA010□ [Weight : 1.5kg(Fan-Cooling included)]

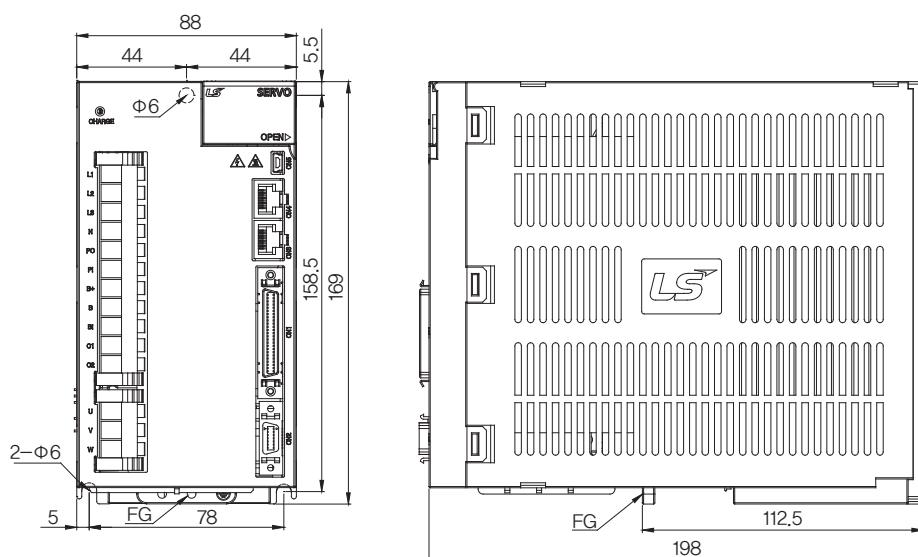
* Unit [mm]



External Dimensions of L7SA Drive

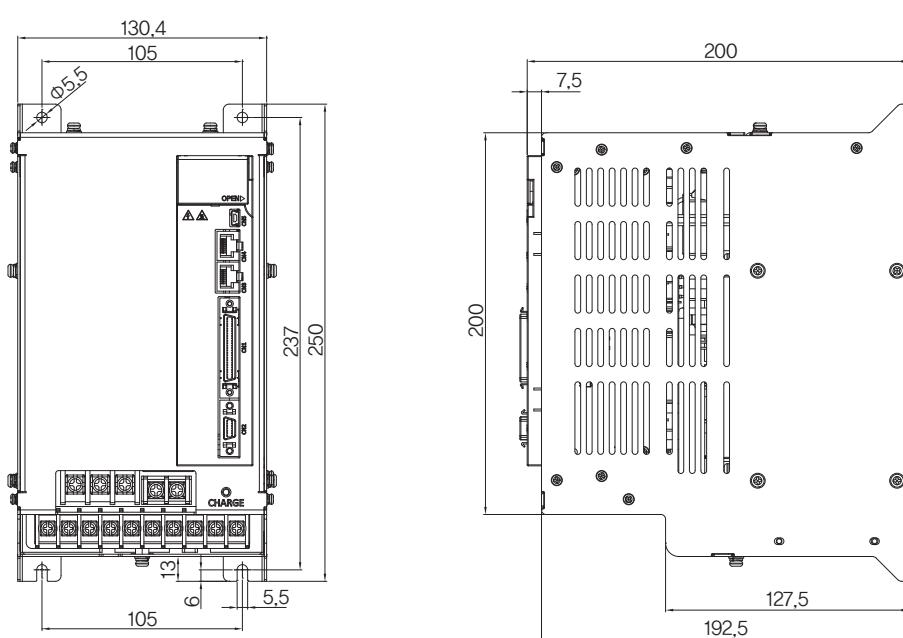
■ L7SA020□ ~ L7SA035□ [Weight : 2.5kg(Fan-Cooling included)]

*Unit [mm]



■ L7SA050□ [Weight : 5.5kg(Fan-Cooling included)]

*Unit [mm]



L7S Series

L7N Series

L7NH Series

L7P Series

F Series

MDM Series

Options

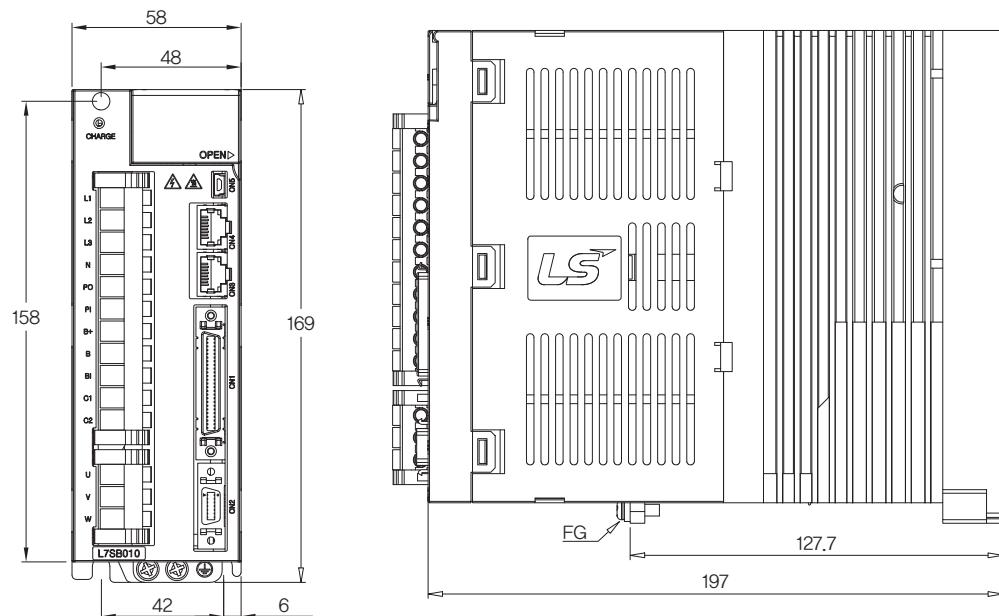
PEGASUS Series

L7 SERIES SYSTEM

External Dimensions of L7SB Drive

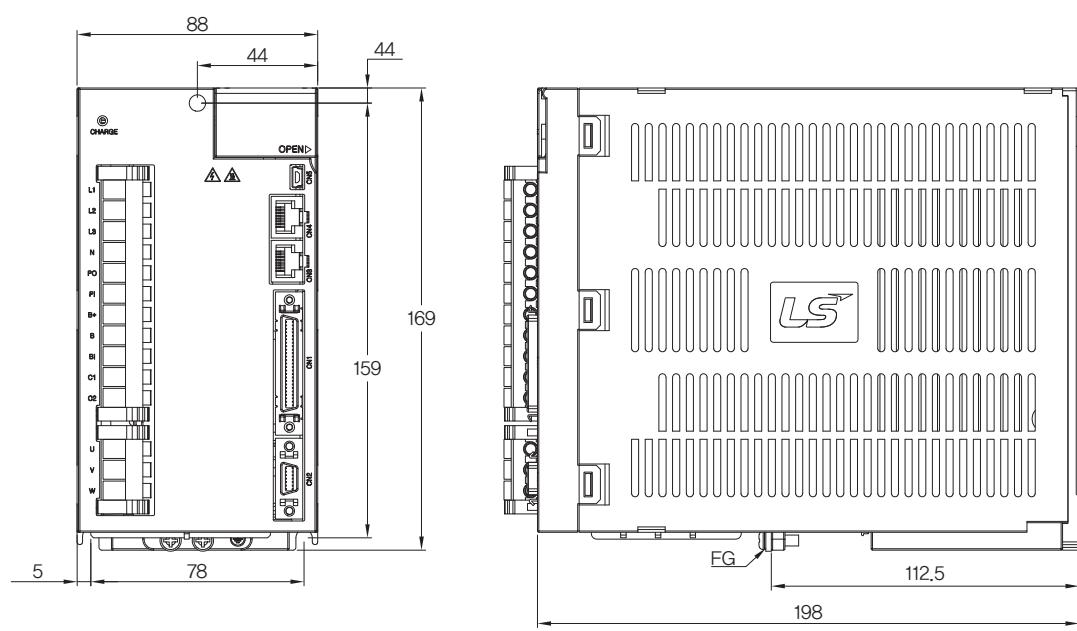
■ L7SB010B [Weight : 1.5kg(Fan–Cooling included)]

* Unit [mm]



■ L7SB020B / L7SB035B [Weight : 2.5kg(Fan–Cooling included)]

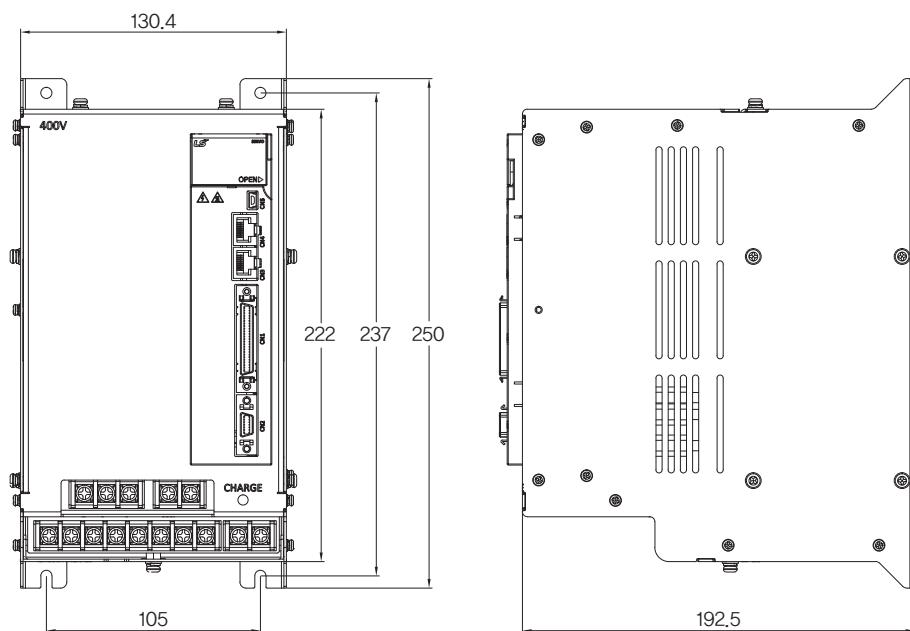
* Unit [mm]



External Dimensions of L7SB Drive

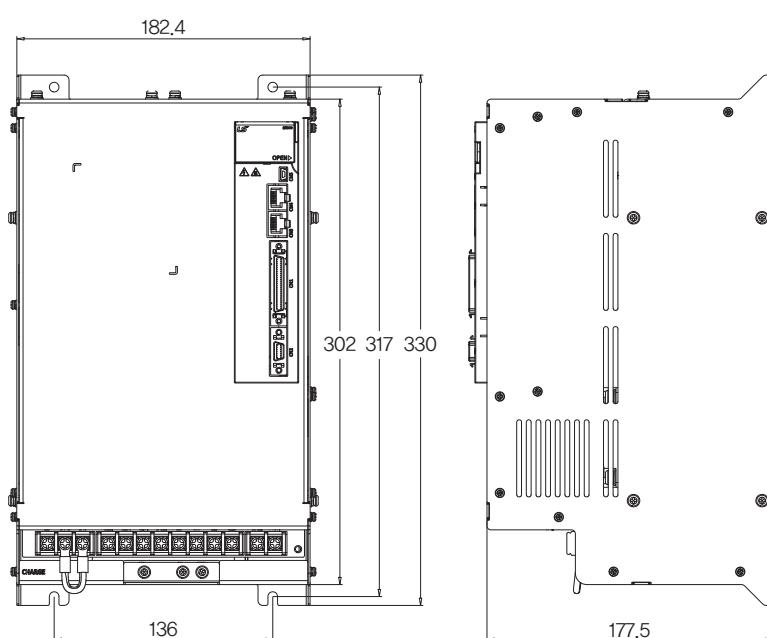
L7SB050B [Weight : 5.5kg(Fan–Cooling included)]

*Unit [mm]



L7SB075B [Weight : 8.5kg(Fan–Cooling included)]

*Unit [mm]



L7S Series

L7N Series

L7NH Series

L7P Series

S Series

F Series

MDM Series

PEGASUS Series

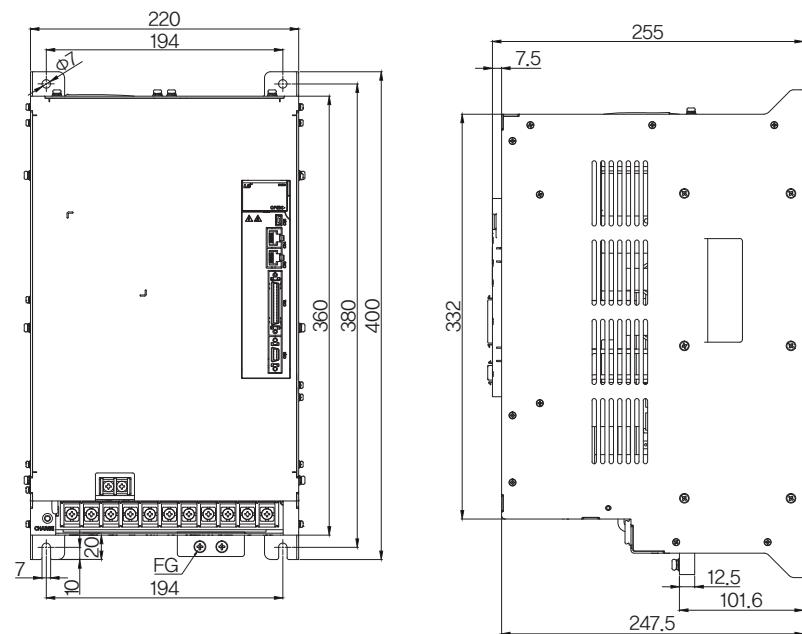
Options

L7 SERIES SYSTEM

External Dimensions of L7SB Drive

■ L7SB150B [Weight : 15.5kg(Fan-Cooling included)]

* Unit [mm]

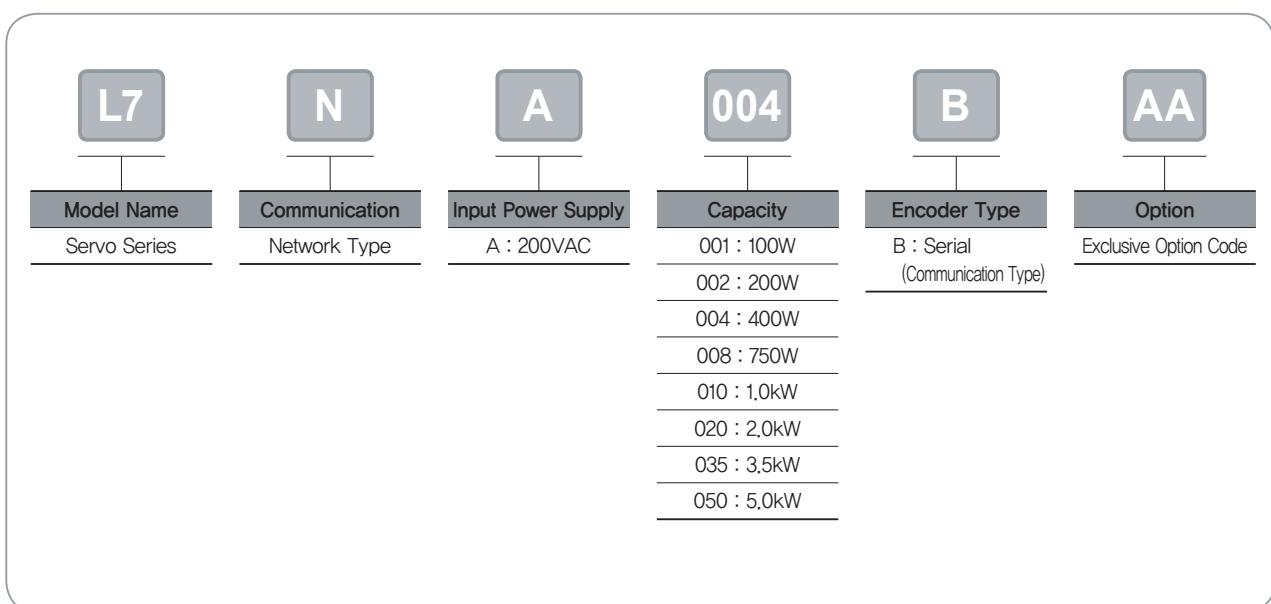


EtherCAT Communication Command Type

I L7N Series



■ Servo Drive Designation



L7S Series

L7N Series

L7NH Series

L7P Series

S Series

F Series

MDM Series

PEGASUS Series

Options

L7 SERIES SYSTEM

L7N Series

Characteristic

Real-time control by EtherCAT

- High speed, Real-time capability and Synchronization mechanism
- 100BASE-TX(100Mbps) EtherNET based real-time communication

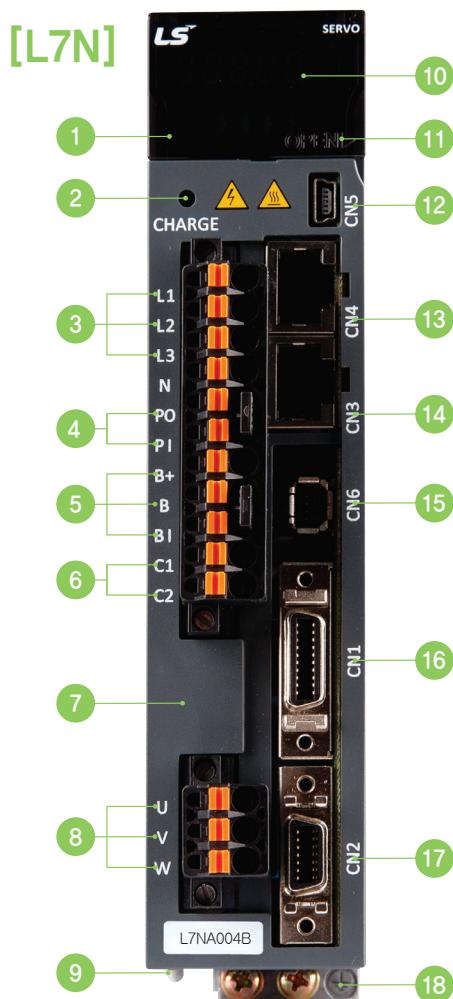
Support Various Operation Mode

- Cyclic(P/S/T) Mode and Profile (P/S/T)Mode, Homming Mode

High Response for Precision Control

- High Resolutions Serial type Encoder(19Bit, BiSS)
- Improved Speed Response(=1Khz) Frequency

Identifying the Part of L7N Drive



- 1 Operation keys (Mode, Up, Down, Set)
- 2 Charge lamp
- 3 Main power connector (L1, L2, L3)
- 4 DC reactor connector(PO, PI)
 - Short circuit when not used
- 5 Regenerative Resistor Connector (B+, B, BI)
 - Short-Circuit B, BI terminals when standard type
 - Use B+, B terminals when using external resistor
- 6 Control Power Connector (C1, C2)
- 7 Front cover
- 8 Servo Motor Connecting Terminals (U, V, W)
- 9 Heat Sink
- 10 Display
- 11 Status LED
- 12 CN5:USB connector
- 13 CN4:EtherCAT Communication Port (IN)
- 14 CN3:EtherCAT Communication Port (OUT)
- 15 CN6 : STO Connector
- 16 CN1 : Control Signal Connector
- 17 CN2 : Encoder Signal Connector
- 18 PE(Protective Earth)

L7N Drive Combination Table

L7N Serial Type

| Rated Speed (rpm) | Maximum speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder Cable | | Power Cable | | | | | | |
|-------------------|---------------------|---|--|------------------|-----------------------|---------------|-------------|-------------|-------------|---------------|-------------|-------------|-------------|-------------|
| | | | | | | Serial Type | Single Turn | Multi Turn | For power | Power + Brake | Brake | | | |
| 3,000 | 5,000 | <input type="checkbox"/> 40 FALR5A L7NA001B <input type="checkbox"/> 40 FAL01A L7NA001B <input type="checkbox"/> 40 FAL015A L7NA004B <input type="checkbox"/> 60 FBL01A L7NA001B <input type="checkbox"/> 60 FBL02A L7NA002B <input type="checkbox"/> 60 FBL04A L7NA004B <input type="checkbox"/> 80 FCL04A L7NA004B <input type="checkbox"/> 80 FCL06A L7NA008B <input type="checkbox"/> 80 FCL08A L7NA008B <input type="checkbox"/> 80 FCL10A L7NA010B <input type="checkbox"/> 60 FB01A L7NA001B <input type="checkbox"/> 60 FB02A L7NA002B <input type="checkbox"/> 60 FB04A L7NA004B <input type="checkbox"/> 80 FC04A L7NA004B <input type="checkbox"/> 80 FC06A L7NA008B <input type="checkbox"/> 80 FC08A L7NA008B <input type="checkbox"/> 80 FC10A L7NA010B <input type="checkbox"/> 130 FE09A L7NA010B <input type="checkbox"/> 130 FE15A L7NA020B <input type="checkbox"/> 130 FE22A L7NA020B <input type="checkbox"/> 130 FE30A L7NA035B <input type="checkbox"/> 180 FF30A L7NA035B <input type="checkbox"/> 180 FF50A L7NA050B | <small>* 18Bit Serial / M-Turn Abs</small> | APCS-E□□□ES | APCS-E□□□ESI | APCS-P□□□LS | APCS-B□□□QS | APCS-P□□□FS | APCS-P□□□HS | APCS-P□□□NB | APCS-P□□□IS | APCS-P□□□PB | APCS-P□□□JS | APCS-P□□□LB |
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| 2,000 | 3,000 | <input type="checkbox"/> 80 FCL03D L7NA004B <input type="checkbox"/> 80 FCL05D L7NA008B <input type="checkbox"/> 80 FCL06D L7NA008B <input type="checkbox"/> 80 FCL07D L7NA008B <input type="checkbox"/> 80 FC03D L7NA004B <input type="checkbox"/> 80 FC05D L7NA008B <input type="checkbox"/> 80 FC06D L7NA008B <input type="checkbox"/> 80 FC07D L7NA008B <input type="checkbox"/> 130 FE06D L7NA008B <input type="checkbox"/> 130 FE11D L7NA010B <input type="checkbox"/> 130 FE16D L7NA020B <input type="checkbox"/> 130 FE22D L7NA020B <input type="checkbox"/> 180 FF22D L7NA020B <input type="checkbox"/> 180 FF35D L7NA035B <input type="checkbox"/> 180 FF55D L7NA050B | <small>* 19Bit Serial / M-Turn Abs</small> | APCS-E□□□ES | APCS-E□□□ESI | APCS-P□□□LS | APCS-B□□□QS | APCS-P□□□FS | APCS-P□□□HS | APCS-P□□□NB | APCS-P□□□IS | APCS-P□□□PB | APCS-P□□□JS | APCS-P□□□LB |
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| 1,500 | 3,000 | <input type="checkbox"/> 130 FE05G L7NA008B <input type="checkbox"/> 130 FE09G L7NA010B <input type="checkbox"/> 130 FE13G L7NA020B <input type="checkbox"/> 130 FE17G L7NA020B <input type="checkbox"/> 180 FF20G L7NA020B <input type="checkbox"/> 180 FF30G L7NA035B <input type="checkbox"/> 180 FF44G L7NA050B | <small>* 19Bit Serial / M-Turn Abs</small> | APCS-E□□□DS | APCS-E□□□DSI | APCS-P□□□LS | APCS-B□□□QS | APCS-P□□□FS | APCS-P□□□HS | APCS-P□□□NB | APCS-P□□□IS | APCS-P□□□PB | APCS-P□□□JS | APCS-P□□□LB |
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| 1,000 | 2,000 | <input type="checkbox"/> 130 FE03M L7NA004B <input type="checkbox"/> 130 FE06M L7NA008B <input type="checkbox"/> 130 FE09M L7NA010B <input type="checkbox"/> 130 FE12M L7NA020B <input type="checkbox"/> 180 FF12M L7NA020B <input type="checkbox"/> 180 FF20M L7NA020B <input type="checkbox"/> 180 FF30M L7NA035B <input type="checkbox"/> 180 FF44M L7NA050B | <small>* 19Bit Serial / M-Turn Abs</small> | APCS-E□□□DS | APCS-E□□□DSI | APCS-P□□□LS | APCS-B□□□QS | APCS-P□□□FS | APCS-P□□□HS | APCS-P□□□NB | APCS-P□□□IS | APCS-P□□□PB | APCS-P□□□JS | APCS-P□□□LB |
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L7 SERIES SYSTEM

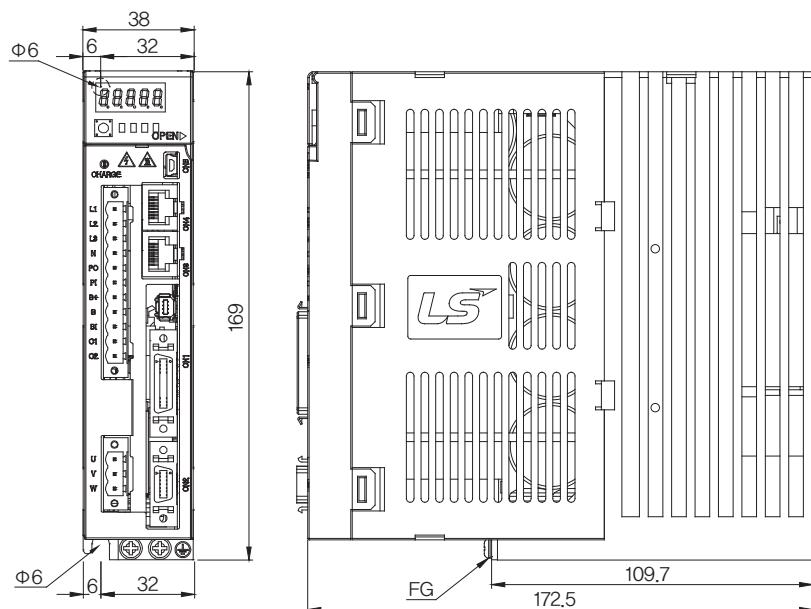
L7N Drive Product Features

| Item | Type Name | L7NA001B | L7NA002B | L7NA004B | L7NA008B | L7NA010B | L7NA020B | L7NA035B | L7NA050B |
|-----------------------------------|---------------------------------------|--|----------|----------|----------|----------|----------|----------|----------|
| Input Power | Main Power Supply | 3 Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz] | | | | | | | |
| | Control Power Supply | Single Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz] | | | | | | | |
| | Rated Current[A] | 1.4 | 1.7 | 3.0 | 5.2 | 6.75 | 13.5 | 16.7 | 32 |
| | Peak Current[A] | 4.2 | 5.1 | 9.0 | 15.6 | 20.25 | 40.5 | 50.1 | 96 |
| | Encoder Type | Serial Type : 18 bit(FA type), 19bit, 20bit(MDM series) | | | | | | | |
| Control Performance | Speed Control Range | Maximum 1: 5000 | | | | | | | |
| | Frequency Response | Maximum 1 kHz or more (when the 19-bit serial encoder is applied) | | | | | | | |
| | Speed Variation Ratio | ±0.01[%] or lower(When the load changes between 0 and 100%) ±0.1[%] or less(Temperature of 25°C[±10]) | | | | | | | |
| | Torque Control Repetition Accuracy | Within ±1% | | | | | | | |
| Supported Drive Modes (CiA402) | | Profile Position Mode Profile Velocity Mode Profile Torque Mode Interpolated Position Mode Cyclic Synchronous Position Mode Cyclic Synchronous Velocity Mode Cyclic Synchronous Torque Mode Homing Mode | | | | | | | |
| Digital Input/Output | Digital Input | Total 6 input channels (allocable) PCON, GAIN2, ALMRST, HOME, P-OT, N-OT Above 6 functions can be used selectively for assignment. Signal can be set as positive logic or negative logic. | | | | | | | |
| | Touch Probe Input | There are 2 input channels, Provides rising and falling edge detection functions for each channel. | | | | | | | |
| | Digital Output | Total 4 channels (allocable) ALARM, READY, ZSPD, BRAKE, INPOS, INSPD, WARN Above 7 outputs can be used selectively for assignment. Signal can be set as positive logic or negative logic. | | | | | | | |
| Additional Communication | USB | Program download is available with USB Communication. | | | | | | | |
| Built-in Functions | Dynamic Braking | Built-in type(operates when Servo alarm or Servo off) | | | | | | | |
| | Regenerative Braking | Built-in type, and also external connection is available | | | | | | | |
| | Display | 7 segments(5DIGIT) | | | | | | | |
| | Setting Function | Loder(SET), (MODE) | | | | | | | |
| | Additional Function | Auto gain tuning function | | | | | | | |
| | Protective Function | Overcurrent, overload, overvoltage, insufficient voltage, main power input problem, control power input problem, overspeed, motor cable, overheat(power module overheat, abnormal drive operation's temp), encoder problem, over-regenerative, sensor problem, communication problem | | | | | | | |
| Operation Environment | Temperature | 0 ~ 50[°C] | | | | | | | |
| | Humidity | Below 90[%]RH(avoid dew-condensation) | | | | | | | |
| | Environment | Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust. | | | | | | | |

External Dimensions of L7SN Drive

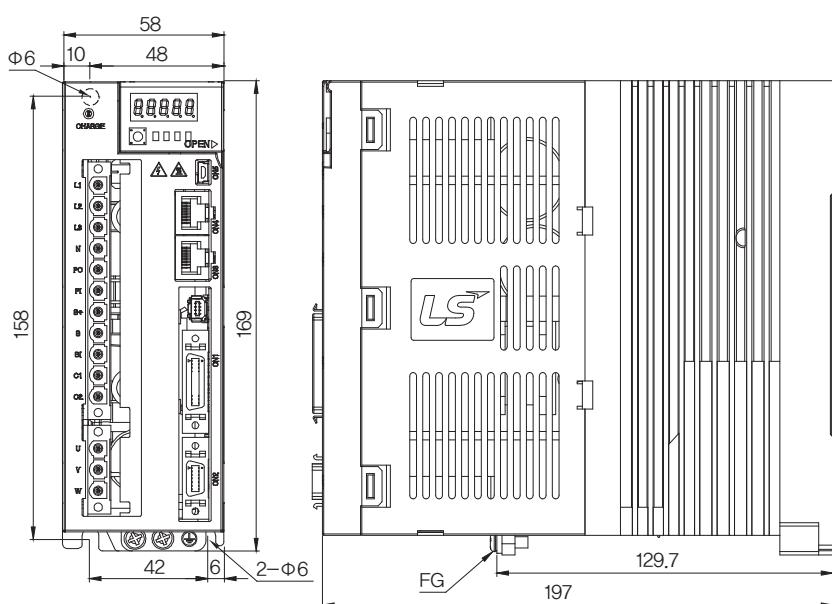
L7NA001B ~ L7NA004B [Weight : 1.0kg]

*Unit [mm]



L7NA008B / L7NA010B [Weight : 1.5kg(Fan-Cooling included)]

*Unit [mm]

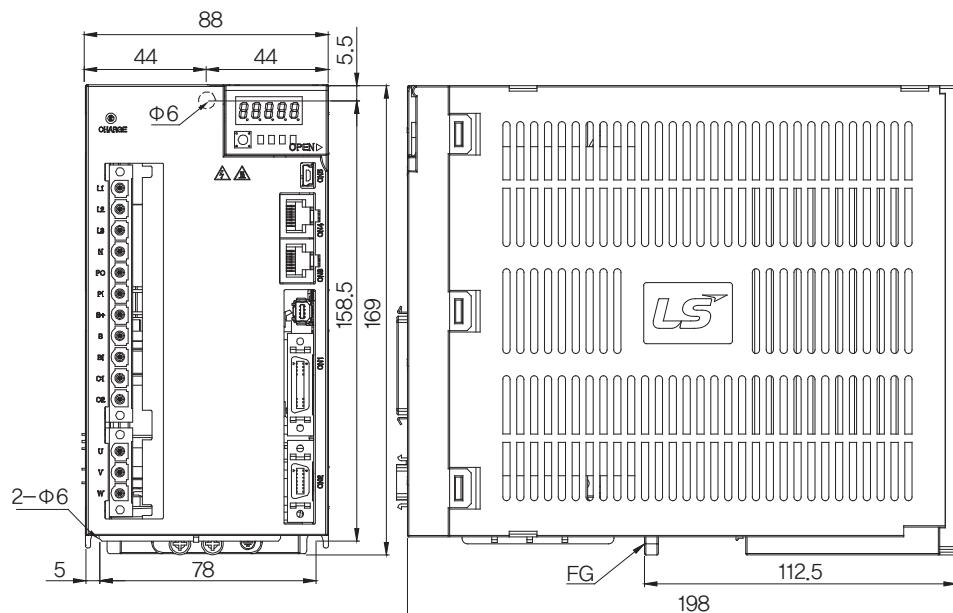


L7 SERIES SYSTEM

External Dimensions of L7SN Drive

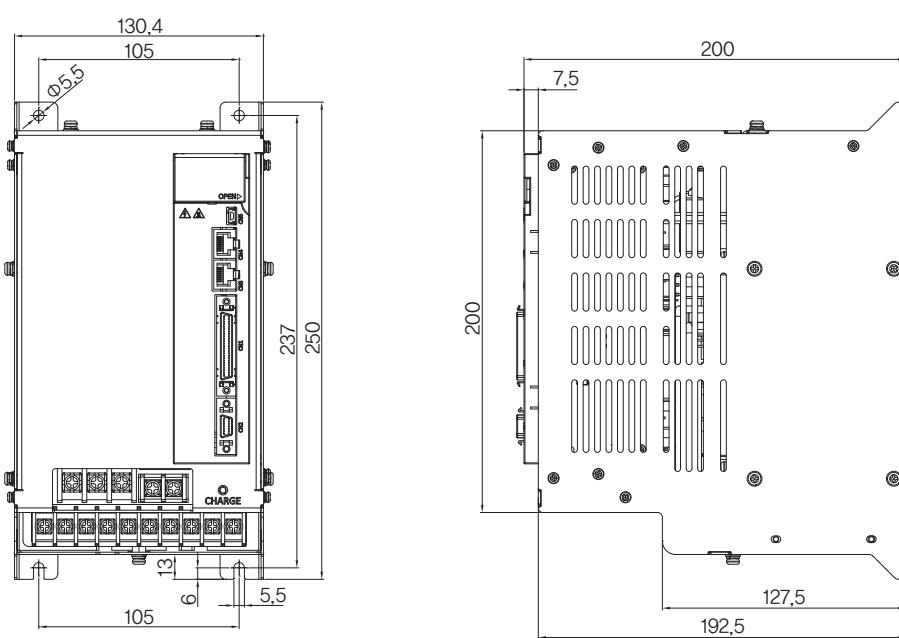
■ L7NA020B / L7NA035B [Weight : 2.5kg(Fan-Cooling included)]

* Unit [mm]



■ L7NA050B [Weight : 5.5kg(Fan-Cooling included)]

* Unit [mm]



All-in-one EtherCAT Communication Command Type

L7NH Series



Servo Drive Designation

| L7 | NH | A | 004 | U | AA |
|--------------|------------------------------|--------------------------|---|---------------|-----------------------|
| Model Name | Communication | Input Power Supply | Capacity | Encoder Type | Option |
| Servo Series | Network / All-in-One Type | A : 200VAC B : 400VAC | 001 : 100W 002 : 200W 004 : 400W 008 : 750W 010 : 1.0kW 020 : 2.0kW 035 : 3.5kW 050 : 5.0kW 075 : 7.5kW 150 : 15kW | U : Universal | Exclusive Option Code |
| | | | | | |

* Range

- 200V : 0.1kW~15kW
- 400V : 1.0kW~15kW

L7S Series

L7NH Series

L7P Series

S Series

F Series

MDM Series

Options

PEGASUS Series

L7 SERIES SYSTEM

L7NH Series

Characteristic

Real-time control through EtherCAT

- High speed, Real-time capability and Synchronization mechanism
- Improved EtherCAT communication speed(min. 250us, DC support)
- Supporting CoE, EoE and FoE
- Improved Speed Response(=1.6Khz) Frequency

Improved Control Performance

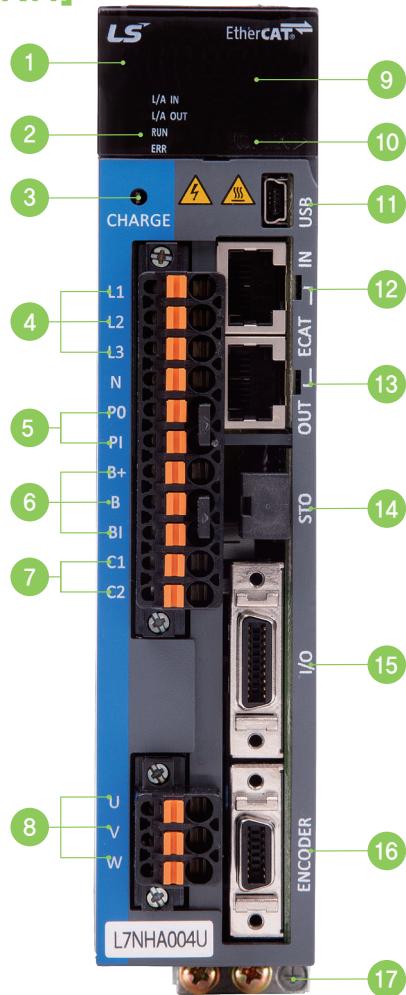
- Improved Control bandwidth
- Providing 4-step Notch-Filter
- Vibration control by Real-time FFT
- Real-time gain tuning function

Support various motor and Encoder drive

- Supporting Rotary, DD and Motor drive (supporting3rd party motor)
- Quadrature, BiSS-C, Tamagawa serial abs, EnDat 2,2

Identifying the Part of L7NH Drive

[L7NH]



- 1 Display
- 2 State LED
- 3 Charge Lamp
- 4 Main Power Connector (L1, L2, L3)
- 5 DC Reactor Connector (PO, PI)
- 6 Regenerative Resistance Connector (B+, B, BI)
 - Short-Circuit B, BI terminals when standard type
 - Use B+, B terminals when using external resistor
- 7 Control Power Connector (C1, C2)
- 8 Servo Motor Connecting Terminal (U,V,W)
- 9 Connector for Analog Monitor
- 10 Node Address Setting Switch
- 11 USB Connector
- 12 EtherCAT Communication Port (IN)
- 13 EtherCAT Communication Port (OUT)
- 14 Safety Torque off Connector
- 15 Input / Output signal /Connector
- 16 Encoder Connector (ENCODER)
- 17 PE(Protective Earth)

L7NHA Drive Combination Table

L7NHA Incremental Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder cable | Power Cable | | |
|-------------------|---------------------|-------------|------------------|------------------|-----------------------|---------------|-------------|---------------|-------------|
| | | | | | Quadrature Type | INC | For power | Power + Brake | Brake |
| 3,000 | 5,000 | | □40 | SAR3A | L7NHA001U | * 2,048 P/R | APCS-E□□□AS | APCS-P□□□GS | APCS-P□□□KB |
| | | | □40 | SAR5A | L7NHA001U | | | | |
| | | | □40 | SA01A | L7NHA001U | | | | |
| | | | □40 | SA015A | L7NHA002U | | | | |
| | | | □60 | SB01A | L7NHA002U | | | | |
| | | | □60 | SB02A | L7NHA002U | | | | |
| | | | □60 | SB04A | L7NHA004U | | | | |
| | | | □80 | SC04A | L7NHA004U | | | | |
| | | | □80 | SC06A | L7NHA008U | | | | |
| | | | □80 | SC08A | L7NHA008U | | | | |
| | | | □80 | SC10A | L7NHA010U | | | | |
| | | | □130 | SE09A | L7NHA008U | | | | |
| | | | □130 | SE15A | L7NHA020U | | | | |
| | | | □130 | SE22A | L7NHA020U | | | | |
| | | | □130 | SE30A | L7NHA035U | | | | |
| | | | □180 | SF30A | L7NHA035U | | | | |
| | | | □180 | SF50A | L7NHA050U | | | | |
| 2,000 | 3,000 | | □80 | SC03D | L7NHA004U | * 3,000 P/R | APCS-E□□□AS | APCS-P□□□GS | APCS-P□□□KB |
| | | | □80 | SC05D | L7NHA008U | | | | |
| | | | □80 | SC06D | L7NHA008U | | | | |
| | | | □80 | SC07D | L7NHA008U | | | | |
| | | | □130 | SE06D | L7NHA008U | | | | |
| | | | □130 | SE11D | L7NHA010U | | | | |
| | | | □130 | SE16D | L7NHA020U | | | | |
| | | | □130 | SE22D | L7NHA020U | | | | |
| | | | □180 | SF22D | L7NHA020U | | | | |
| | | | □180 | LF35D | L7NHA035U | | | | |
| | | | □180 | SF55D | L7NHA050U | | | | |
| | | | □180 | SF75D | L7NHA075U | | | | |
| | 2,500 | | □220 | SG22D | L7NHA020U | | | | |
| | | | □220 | LG35D | L7NHA035U | | | | |
| 1,500 | 3,000 | | □220 | SG55D | L7NHA050U | * 3,000 P/R | APCS-E□□□BS | APCS-P□□□HS | APCS-P□□□NB |
| | | | □220 | SG75D | L7NHA075U | | | | |
| | | | □220 | SG110D | L7NHA150U | | | | |
| | | | □130 | SE05G | L7NHA008U | | | | |
| | | | □130 | SE09G | L7NHA010U | | | | |
| | | | □130 | SE13G | L7NHA020U | | | | |
| | | | □130 | SE17G | L7NHA020U | | | | |
| | | | □180 | SF20G | L7NHA035U | | | | |
| | | | □180 | SF44G | L7NHA050U | | | | |
| | 2,500 | | □180 | SF60G | L7NHA075U | | | | |
| | | | □220 | SF75G | L7NHA150U | | | | |
| 1,000 | 2,000 | | □180 | LF30G | L7NHA035U | APCS-E□□□BS | APCS-P□□□HS | APCS-P□□□NB | APCS-P□□□SB |
| | | | □220 | SG20G | L7NHA020U | | | | |
| | | | □220 | LG30G | L7NHA035U | | | | |
| | | | □220 | SG60G | L7NHA075U | | | | |
| | | | □220 | SG85G | L7NHA150U | | | | |
| | | | □220 | SG110G | L7NHA150U | | | | |
| | | | □220 | SG150G | L7NHA150U | | | | |
| | 1,700 | | □130 | SE03M | L7NHA004U | | | | |
| | | | □130 | SE06M | L7NHA008U | | | | |
| 3,000 | 3,500 | | □130 | SE09M | L7NHA010U | * 1,048 P/R | APCS-E□□□AS | APCS-P□□□GS | APCS-P□□□SB |
| | | | □130 | SE12M | L7NHA020U | | | | |
| | | | □180 | SF12M | L7NHA020U | | | | |
| | | | □180 | SF20M | L7NHA035U | | | | |
| | | | □180 | LF30M | L7NHA035U | | | | |
| | 2,000 | | □180 | SF44M | L7NHA050U | | | | |
| | | | □220 | SG12M | L7NHA020U | | | | |
| | 1,700 | | □220 | LG30M | L7NHA035U | | | | |
| | | | □220 | SG44M | L7NHA050U | | | | |
| | | | □220 | SG60M | L7NHA075U | | | | |
| | 2,000 | | □60 | HB01A | L7NHA002U | * 2,048 P/R | APCS-E□□□BS | APCS-P□□□HS | APCS-P□□□SB |
| | | | □60 | HB02A | L7NHA002U | | | | |
| | | | □60 | HB04A | L7NHA004U | | | | |
| | | | □130 | HE09A | L7NHA008U | | | | |
| | | | □130 | HE15A | L7NHA020U | | | | |
| | | | □130 | HE30A | L7NHA050U | | | | |

L7 SERIES SYSTEM

L7NHA Drive Combination Table

L7NHA Serial Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder cable | | Power Cable | | |
|-------------------|---------------------|-----------------------------|------------------|------------------|-----------------------|---------------|---------------|--------------|--------------|---------------|
| | | | | | | Serial Type | Single Turn | Multi Turn | For power | Power + Brake |
| 3,000 | 5,000 | * 18Bit Serial / M-Turn Abs | □40 | FALR5A | L7NHA001U | APCS-E□□□□ES | APCS-E□□□□ES1 | APCS-P□□□□LS | APCS-B□□□□QS | |
| | | | □40 | FAL01A | L7NHA001U | | | | | |
| | | | □40 | FAL015A | L7NHA004U | | | | | |
| | | | □60 | FBL01A | L7NHA001U | | | | | |
| | | | □60 | FBL02A | L7NHA002U | | | | | |
| | | | □60 | FBL04A | L7NHA004U | | | | | |
| | | | □80 | FCL04A | L7NHA004U | | | | | |
| | | | □80 | FCL06A | L7NHA008U | | | | | |
| | | | □80 | FCL08A | L7NHA008U | | | | | |
| | | | □80 | FCL10A | L7NHA010U | | | | | |
| | | | □60 | FB01A | L7NHA001U | | | | | |
| | | | □60 | FB02A | L7NHA002U | | | | | |
| | | | □60 | FB04A | L7NHA004U | | | | | |
| | | | □80 | FC04A | L7NHA004U | | | | | |
| | | | □80 | FC06A | L7NHA008U | | | | | |
| | | | □80 | FC08A | L7NHA008U | | | | | |
| | | | □80 | FC10A | L7NHA010U | | | | | |
| | | | □130 | FE09A | L7NHA010U | | | | | |
| | | | □130 | FE15A | L7NHA020U | | | | | |
| | | | □130 | FE22A | L7NHA020U | | | | | |
| | | | □130 | FE30A | L7NHA035U | | | | | |
| | | | □180 | FF30A | L7NHA035U | | | | | |
| | | | □180 | FF50A | L7NHA050U | | | | | |
| 2,000 | 3,000 | * 19Bit Serial / M-Turn Abs | □80 | FCL03D | L7NHA004U | APCS-E□□□□ES | APCS-E□□□□ES1 | APCS-P□□□□LS | APCS-B□□□□QS | |
| | | | □80 | FCL05D | L7NHA008U | | | | | |
| | | | □80 | FCL06D | L7NHA008U | | | | | |
| | | | □80 | FCL07D | L7NHA008U | | | | | |
| | | | □80 | FC03D | L7NHA004U | | | | | |
| | | | □80 | FC05D | L7NHA008U | | | | | |
| | | | □80 | FC06D | L7NHA008U | | | | | |
| | | | □80 | FC07D | L7NHA008U | | | | | |
| | | | □130 | FE06D | L7NHA008U | | | | | |
| | | | □130 | FE11D | L7NHA010U | | | | | |
| | | | □130 | FE16D | L7NHA020U | | | | | |
| | | | □130 | FE22D | L7NHA020U | | | | | |
| | | | □180 | FF22D | L7NHA020U | | | | | |
| | | | □180 | FF35D | L7NHA035U | | | | | |
| | | | □180 | FF55D | L7NHA050U | | | | | |
| 1,500 | 3,000 | * 19Bit Serial / M-Turn Abs | □180 | FF75D | L7NHA075U | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□HS | APCS-B□□□□SB | |
| | | | □220 | FG22D | L7NHA020U | | | | | |
| | | | □220 | FG35D | L7NHA035U | | | | | |
| | | | □220 | FG55D | L7NHA050U | | | | | |
| | | | □220 | FG75D | L7NHA075U | | | | | |
| | | | □220 | FG11D | L7NHA150U | | | | | |
| | | | □130 | FE05G | L7NHA008U | | | | | |
| | | | □130 | FE09G | L7NHA010U | | | | | |
| | | | □130 | FE13G | L7NHA020U | | | | | |
| | | | □130 | FE17G | L7NHA020U | | | | | |
| | | | □180 | FF20G | L7NHA020U | | | | | |
| | | | □180 | FF30G | L7NHA035U | | | | | |
| | | | □180 | FF44G | L7NHA050U | | | | | |
| | | | □180 | FF60G | L7NHA075U | | | | | |
| | | | □220 | FG20G | L7NHA020U | | | | | |
| 1,000 | 2,000 | * 19Bit Serial / M-Turn Abs | □220 | FG30G | L7NHA035U | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□VS | APCS-P□□□□SB | |
| | | | □220 | FG44G | L7NHA050U | | | | | |
| | | | □220 | FG60G | L7NHA075U | | | | | |
| | | | □180 | FF75G | L7NHA075U | | | | | |
| | | | □220 | FG10G | L7NHA150U | | | | | |
| | | | □220 | FG150G | L7NHA150U | | | | | |
| | | | □130 | FE03M | L7NHA004U | | | | | |
| | | | □130 | FE06M | L7NHA008U | | | | | |
| | | | □130 | FE09M | L7NHA010U | | | | | |
| | | | □130 | FE12M | L7NHA020U | | | | | |
| 1,700 | 2,000 | * 19Bit Serial / M-Turn Abs | □180 | FF12M | L7NHA020U | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□VS | APCS-P□□□□SB | |
| | | | □180 | FF20M | L7NHA020U | | | | | |
| | | | □180 | FF30M | L7NHA035U | | | | | |
| | | | □180 | FF44M | L7NHA050U | | | | | |
| | | | □220 | FG12M | L7NHA020U | | | | | |
| 1,700 | 2,000 | * 19Bit Serial / M-Turn Abs | □220 | FG20M | L7NHA020U | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□VS | APCS-P□□□□SB | |
| | | | □220 | FG30M | L7NHA035U | | | | | |
| | | | □220 | FG44M | L7NHA050U | | | | | |
| | | | □220 | FG60M | L7NHA075U | | | | | |

L7NHB Drive Combination Table

L7NHB Incremental Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder cable | Power Cable | | |
|-------------------|---------------------|-------------|------------------|------------------|-----------------------|---------------|-------------|---------------|-------------|
| | | | | | Quadrature Type | INC | For power | Power + Brake | Brake |
| 3,000 | 5,000 | | □130 | SEP09A | L7NHB010U | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | SEP15A | L7NHB020U | | | | |
| | | | □130 | SEP22A | L7NHB020U | | | | |
| | | | □130 | SEP30A | L7NHB035U | | | | |
| | | | □180 | SFP30A | L7NHB035U | | | | |
| | | | □180 | SFP50A | L7NHB050U | | | | |
| 2,000 | 3,000 | | □130 | SEP06D | L7NHB010U | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | SEP11D | L7NHB010U | | | | |
| | | | □130 | SEP16D | L7NHB020U | | | | |
| | | | □130 | SEP22D | L7NHB020U | | | | |
| | | | □180 | SFP22D | L7NHB020U | | | | |
| | | | □180 | SFP35D | L7NHB035U | | | | |
| | | | □180 | SFP55D | L7NHB050U | | APCF-P□□□JS | APCF-P□□□LB | APCF-P□□□SB |
| | | | □180 | SFP75D | L7NHB075U | | | | |
| | | | □220 | SGP22D | L7NHB020U | | | | |
| | | | □220 | SGP35D | L7NHB035U | | | | |
| | | | □220 | SGP55D | L7NHB050U | | | | |
| | | | □220 | SGP75D | L7NHB075U | | | | |
| 1,500 | 3,000 | | □130 | SEP05G | L7NHB010U | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | SEP09G | L7NHB010U | | | | |
| | | | □130 | SEP13G | L7NHB020U | | | | |
| | | | □130 | SEP17G | L7NHB020U | | | | |
| | | | □180 | SFP20G | L7NHB020U | | APCF-P□□□IS | APCF-P□□□PB | |
| | | | □180 | SFP30G | L7NHB050U | | | | |
| | | | □180 | SFP44G | L7NHB050U | | | | |
| | | | □180 | SFP60G | L7NHB075U | | | | |
| | | | □180 | SFP75G | L7NHB075U | | APCF-P□□□JS | APCF-P□□□LB | APCF-P□□□SB |
| | | | □220 | SGP20G | L7NHB020U | | | | |
| | | | □220 | SGP30G | L7NHB050U | | | | |
| | | | □220 | SGP44G | L7NHB050U | | | | |
| | | | □220 | SGP60G | L7NHB075U | | APCF-P□□□MS | | |
| | | | □220 | SGP85G | L7NHB150U | | | | |
| 1,000 | 2,000 | | □220 | SGP10G | L7NHB150U | | | | |
| | | | □220 | SGP15G | L7NHB150U | | | | |
| | | | □130 | SEP03M | L7NHB010U | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | SEP06M | L7NHB010U | | | | |
| | | | □130 | SEP09M | L7NHB010U | | | | |
| | | | □130 | SEP12M | L7NHB020U | | APCF-P□□□IS | APCF-P□□□PB | APCF-P□□□SB |
| | | | □180 | SFP12M | L7NHB020U | | | | |
| | | | □180 | SFP20M | L7NHB020U | | | | |
| | | | □180 | SFP30M | L7NHB035U | | | | |
| | | | □180 | SFP44M | L7NHB050U | | | | |
| | | | □220 | SGP12M | L7NHB020U | | | | |
| | | | □220 | SGP20M | L7NHB020U | | APCF-P□□□JS | APCF-P□□□LB | |
| | | | □220 | SGP30M | L7NHB050U | | | | |
| | | | □220 | SGP44M | L7NHB050U | | | | |
| | | | □220 | SGP60M | L7NHB075U | | | | |

L7S Series
L7N Series
L7NH Series
L7P Series
S Series
F Series
MDM Series
PEGASUS Series
Options

L7 SERIES SYSTEM

L7NHB Drive Combination Table

L7NHB Serial Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder cable | | Power Cable | | |
|-------------------|---------------------|-------------|------------------|------------------|---|--|---|-------------|-------------|---------------|
| | | | | | | Serial Type | Single Turn | Multi Turn | For power | Power + Brake |
| 3,000 | 5,000 | □130 | FEP09A | L7NHB010U | APCS-E□□□DS1 19Bit Serial / M-Turn Abs | APCF-P□□□HS APCF-P□□□IS APCF-P□□□JS APCF-P□□□MS | APCF-P□□□NB APCF-P□□□PB APCF-P□□□LB | APCF-P□□□SB | APCF-P□□□SB | APCF-P□□□SB |
| | | | FEP15A | L7NHB020U | | | | | | |
| | | | FEP22A | L7NHB035U | | | | | | |
| | | | FEP30A | L7NHB035U | | | | | | |
| | | | FFF30A | L7NHB035U | | | | | | |
| | | | FFF50A | L7NHB050U | | | | | | |
| | 3,000 | □130 | FEP06D | L7NHB010U | | | | | | |
| | | | FEP11D | L7NHB010U | | | | | | |
| | | | FEP16D | L7NHB020U | | | | | | |
| | | | FEP22D | L7NHB020U | | | | | | |
| | | | FFF22D | L7NHB020U | | | | | | |
| | | | FFF35D | L7NHB035U | | | | | | |
| 2,000 | 2,500 | □180 | FFF55D | L7NHB050U | | | | | | |
| | | | FFF75D | L7NHB075U | | | | | | |
| | | | FGP22D | L7NHB020U | | | | | | |
| | | | FGP35D | L7NHB035U | | | | | | |
| | | | FGP55D | L7NHB050U | | | | | | |
| | | | FGP75D | L7NHB075U | | | | | | |
| | 3,000 | □220 | FGP10D | L7NHB150U | | | | | | |
| | | | FGP05G | L7NHB010U | | | | | | |
| | | | FGP09G | L7NHB010U | | | | | | |
| | | | FGP13G | L7NHB020U | | | | | | |
| 1,500 | 2,200 | □180 | FGP17G | L7NHB020U | | | | | | |
| | | | FGP20G | L7NHB020U | | | | | | |
| | | | FGP30G | L7NHB035U | | | | | | |
| | | | FGP44G | L7NHB050U | | | | | | |
| | | | FGP60G | L7NHB075U | | | | | | |
| | | | FGP75G | L7NHB075U | | | | | | |
| | 2,500 | □220 | FGP20G | L7NHB020U | | | | | | |
| | | | FGP30G | L7NHB035U | | | | | | |
| | | | FGP44G | L7NHB050U | | | | | | |
| | | | FGP60G | L7NHB075U | | | | | | |
| 1,000 | 2,000 | □180 | FGP85G | L7NHB150U | | | | | | |
| | | | FGP10G | L7NHB150U | | | | | | |
| | | | FGP15G | L7NHB150U | | | | | | |
| | | | FGP03M | L7NHB010U | | | | | | |
| | | | FGP06M | L7NHB010U | | | | | | |
| | | | FGP09M | L7NHB010U | | | | | | |
| | 1,700 | □180 | FGP12M | L7NHB020U | | | | | | |
| | | | FGP12M | L7NHB020U | | | | | | |
| | | | FGP20M | L7NHB020U | | | | | | |
| | | | FGP30M | L7NHB035U | | | | | | |
| PEGASUS Series | 2,000 | □180 | FGP44M | L7NHB050U | | | | | | |
| | | | FGP12M | L7NHB020U | | | | | | |
| | | | FGP20M | L7NHB020U | | | | | | |
| | | | FGP30M | L7NHB050U | | | | | | |
| | | | FGP44M | L7NHB050U | | | | | | |
| | | | FGP60M | L7NHB075U | | | | | | |

L7NHA Drive Product Features

| Item | Type Name | L7NHA001U | L7NHA002U | L7NHA004U | L7NHA008U | L7NHA010U | L7NHA020U | L7NHA035U | L7NHA050U | L7NHA075U | L7NHA150U |
|---------------------------------------|------------------------------------|--|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| Input Power | Main Power Supply | 3-Phase AC 200~230 [V] (-15~10[%]), 50~60 [Hz] | | | | | | | | | |
| | Control Power Supply | Single-Phase AC 200~230 [V] (-15~10[%]), 50~60 [Hz] | | | | | | | | | |
| | Rated Current[A] | 1.4 | 1.7 | 3.0 | 5.2 | 6.75 | 13.5 | 16.7 | 32 | 39.4 | 76 |
| | Peak Current[A] | 4.2 | 5.1 | 9.0 | 15.6 | 20.25 | 40.5 | 50.1 | 90.88 | 98.5 | 190 |
| | Encoder Type | Quadrature(Incremental) BISS-B, BISS-C(Absolute, Incremental) Tamagawa Serial(Absolute, Incremental) EnDat 2.2 Sinusoidal, Analog Hall | | | | | | | | | |
| Control Performance | Speed Control Range | Maximum 1: 5000 | | | | | | | | | |
| | Frequency Response | Maximum 1[kHz] or above(When the 19-bit Serial Encoder is applied) | | | | | | | | | |
| | Speed Variation Ratio | ±0.01[%] or lower(When the load changes between 0 and 100%) ±0.1[%] or less(Temperature of 25°C[±10]) | | | | | | | | | |
| | Torque Control Repetition Accuracy | Within ±1% | | | | | | | | | |
| EtherCAT Communication Specifications | Communication Standard | FoE (Firmware download) EoE (Parameter setting by UDP, Tuning, Secondary function, Parameter copy) CoE (IEC 61158 Type12, IEC 61800-7 CIA 402 Drive profile) | | | | | | | | | |
| | Physical Layer | 100BASE-TX(IEEE802.3) | | | | | | | | | |
| | Connector | RJ45 x 2 | | | | | | | | | |
| | Communication distance | Within connection between nodes 100[m] | | | | | | | | | |
| | DC (Distributed Clock) | By DC mode synchronism, minimum DC cycle: 250[us] | | | | | | | | | |
| | LED Display | LinkAct IN, LinkAct OUT, RUN, ERR | | | | | | | | | |
| | Cia402 Drive Profile | Profile Position Mode Profile Velocity Mode Profile Torque Mode Cyclic Synchronous Position Mode Cyclic Synchronous Velocity Mode Cyclic Synchronous Torque Mode Homing Mode | | | | | | | | | |
| Digital Input/Output | Digital Input | Input Voltage range : DC 12[V] ~ DC 24[V] Total 8 input channels (allocable) Above 12 functions can be used selectively for assignment. (*POT, *NOT, *HOME, *STOP, *PCON, *GAIN2, *P_CL, *N_CL, PROBE1, PROBE2, EMG, A_RST) *Basic allocation signal | | | | | | | | | |
| | Digital Output | Service rating: DC 24[V] ±10%, 120[mA] Total 4 input channels (allocable) Above 11 functions can be used selectively for assignment. (*BRAKE±, *ALARM±, *READY±, *ZSPD±, INPOS±, TLMT±, VLMT±, INSPD±, WARN±, TGON±, INPOS2±) *Basic allocation signal | | | | | | | | | |
| | Safety Function | 2 Input Channels (STO1, STO2), 1 Output Channels (EDM±) | | | | | | | | | |
| USB Communication | Fuction | Firmware download, Parameter setting, Tuning, Secondary function, Parameter copy | | | | | | | | | |
| | Communication Standard | USB 2.0 Full Speed (applies standard) | | | | | | | | | |
| | Connect | PC or USB storing medium | | | | | | | | | |
| Internal Function | Dynamic Braking | Standard built-in brake (activated when the servo alarm goes off or when the servo is off). | | | | | | | | | |
| | Regenerative Braking | Both the default built-in brake and an externally installed brake are possible. | | | | | | | | | |
| | Display Function | 7 segments(5DIGIT) | | | | | | | | | |
| | Self-setting Function | Possible to set the drive node address by using Rotary Switch | | | | | | | | | |
| | Additional Function | Auto gain tuning function | | | | | | | | | |
| | Protection Function | Overcurrent, overload, overvoltage, insufficient voltage, main power input problem, control power input problem, overspeed, motor cable, overheating(power module overheating, abnormal drive operation's temp), encoder problem, over-regenerative, sensor problem, communication problem | | | | | | | | | |
| Environment | Temperature | 0 ~ +50[°C] / -20~ +70[°C] | | | | | | | | | |
| | Humidity | Below 90[%]RH(avoid dew-condensation) | | | | | | | | | |
| | Environment | Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust. | | | | | | | | | |

L7S Series

L7NH Series

L7P Series

S Series

F Series

PEGASUS Series

Options

L7 SERIES SYSTEM

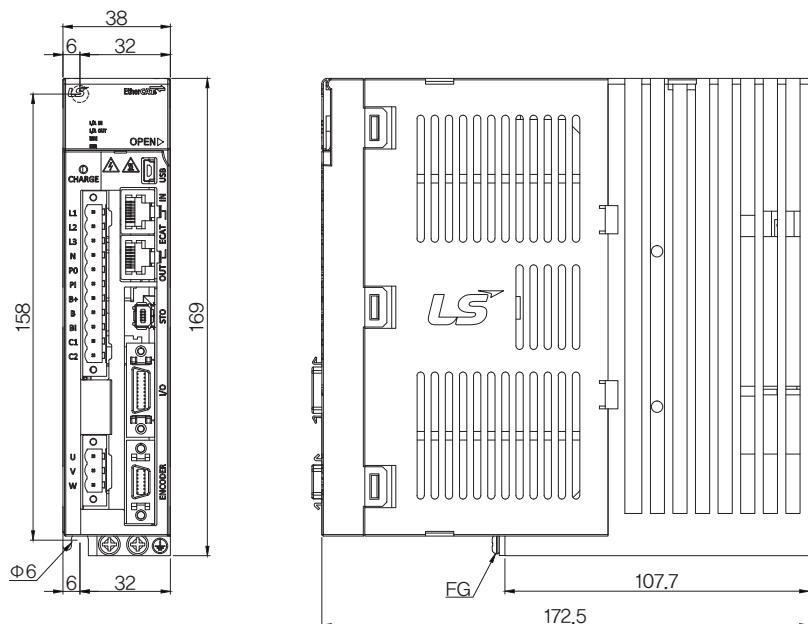
L7NHB Drive Product Features

| Item | Type Name | L7NHB010U | L7NHB020U | L7NHB035U | L7NHB050U | L7NHB075U | L7NHB150U |
|---------------------------------------|------------------------------------|--|-----------|-----------|-----------|-----------|-----------|
| Input Power | Main Power Supply | 3-Phase AC 380~480 [V] (-15~10[%]), 50~60 [Hz] | | | | | |
| | Control Power Supply | Single-Phase AC 380~480 [V] (-15~10[%]), 50~60 [Hz] | | | | | |
| | Rated Current[A] | 3.7 | 8 | 10.1 | 17.5 | 22.8 | 39 |
| | Peak Current[A] | 11.1 | 24 | 30.3 | 47.25 | 57 | 97.5 |
| | Encoder Type | Quadrature(Incremental) BISS-B, BISS-C(Absolute, Incremental) Tamagawa Serial(Absolute, Incremental) EnDat 2.2 | | | | | |
| Control Performance | Speed Control Range | Maximum 1: 5000 | | | | | |
| | Frequency Response | Maximum 1[kHz] or above(When the 19-bit Serial Encoder is applied) | | | | | |
| | Speed Variation Ratio | ±0.01[%] or lower(When the load changes between 0 and 100%) ±0.1[%] or less(Temperature of 25°C[±10]) | | | | | |
| | Torque Control Repetition Accuracy | Within ±1% | | | | | |
| EtherCAT Communication Specifications | Communication Standard | FoE (Firmware download) EoE (Parameter setting by UDP, Tuning, Secondary function, Parameter copy) CoE (IEC 61158 Type12, IEC 61800-7 CIA 402 Drive profile) | | | | | |
| | Physical Layer | 100BASE-TX(IEEE802.3) | | | | | |
| | Connector | RJ45 x 2 | | | | | |
| | Communication distance | Within connection between nodes 100[m] | | | | | |
| | DC (Distributed Clock) | By DC mode synchronism, minimum DC cycle: 250[us] | | | | | |
| | LED Display | LinkAct IN, LinkAct OUT, RUN, ERR | | | | | |
| | Cia402 Drive Profile | Profile Position Mode Profile Velocity Mode Profile Torque Mode Cyclic Synchronous Position Mode Cyclic Synchronous Velocity Mode Cyclic Synchronous Torque Mode Homing Mode | | | | | |
| Digital Input/Output | Digital Input | Input Voltage range : DC 12[V] ~ DC 24[V] Total 8 input channels (allocable) Above 12 functions can be used selectively for assignment. (*POT, *NOT, *HOME, *STOP, *PCON, *GAIN2, *P_CL, *N_CL, PROBE1, PROBE2, EMG, A_RST) *Basic allocation signal | | | | | |
| | Digital Output | Service rating: DC 24[V] ±10%, 120[mA] Total 4 input channels (allocable) Above 11 functions can be used selectively for assignment. (*BRAKE±, *ALARM±, *READY±, *ZSPD±, INPOS±, TLMT±, VLMT±, INSPD±, WARN±, TGON±, INPOS2±) *Basic allocation signal | | | | | |
| | Analog Monitor | There are 2 input channels. Above 15 functions can be used selectively for assignment. | | | | | |
| | Safety Function | 2 Input Channels (STO1, STO2), 1 Output Channels (EDM±) | | | | | |
| USB Communication | Fuction | Firmware download, Parameter setting, Tuning, Secondary function, Parameter copy | | | | | |
| | Communication Standard | USB 2.0 Full Speed (applies standard) | | | | | |
| | Connect | PC or USB storing medium | | | | | |
| USB Communication | Dynamic Braking | Standard built-in brake (activated when the servo alarm goes off or when the servo is off). | | | | | |
| | Regenerative Braking | Both the default built-in brake and an externally installed brake are possible. | | | | | |
| | Display Function | 7 segments(5DIGIT) | | | | | |
| | Self-setting Function | Possible to set the drive node address by using Rotary Switch | | | | | |
| | Additional Function | Auto gain tuning function | | | | | |
| | Protection Function | Overcurrent, overload, overvoltage, insufficient voltage, main power input problem, control power input problem, overspeed, motor cable, overheated(power module overheat, abnormal drive operation's temp), encoder problem, over-regenerative, sensor problem, communication problem | | | | | |
| Operation Environment | Temperature | 0 ~ +50[°C] / -20~ +70[°C] | | | | | |
| | Humidity | Below 90[%]RH(avoid dew-condensation) | | | | | |
| | Other | Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust. | | | | | |

External Dimensions of L7NHA Drive

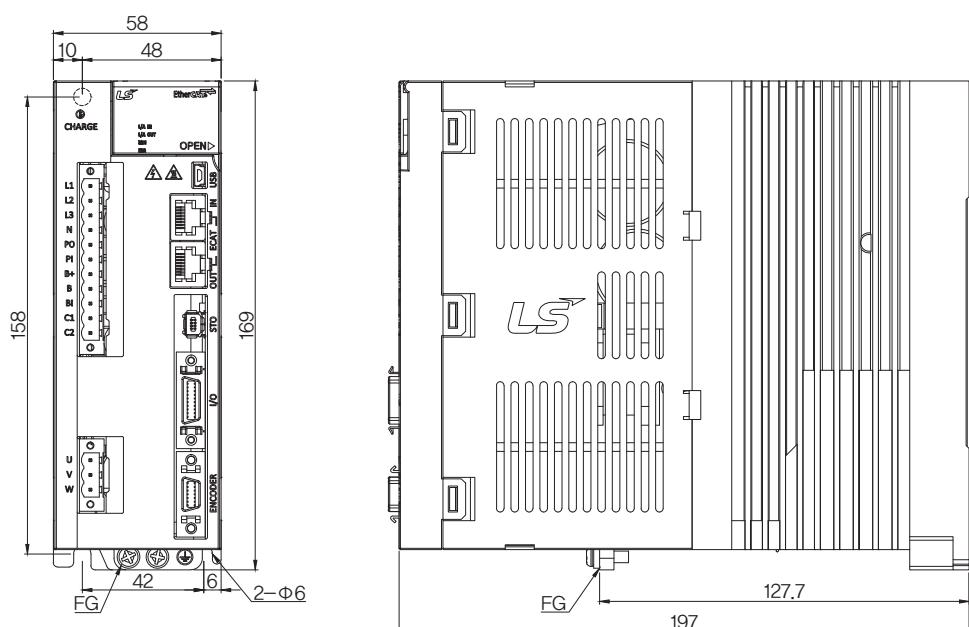
■ L7NHA001U ~ L7NHA004U [Weight : 1.0kg]

*Unit [mm]



■ L7NHA008U / L7NHA010U [Weight : 1.5kg(Fan-Cooling included)]

*Unit [mm]

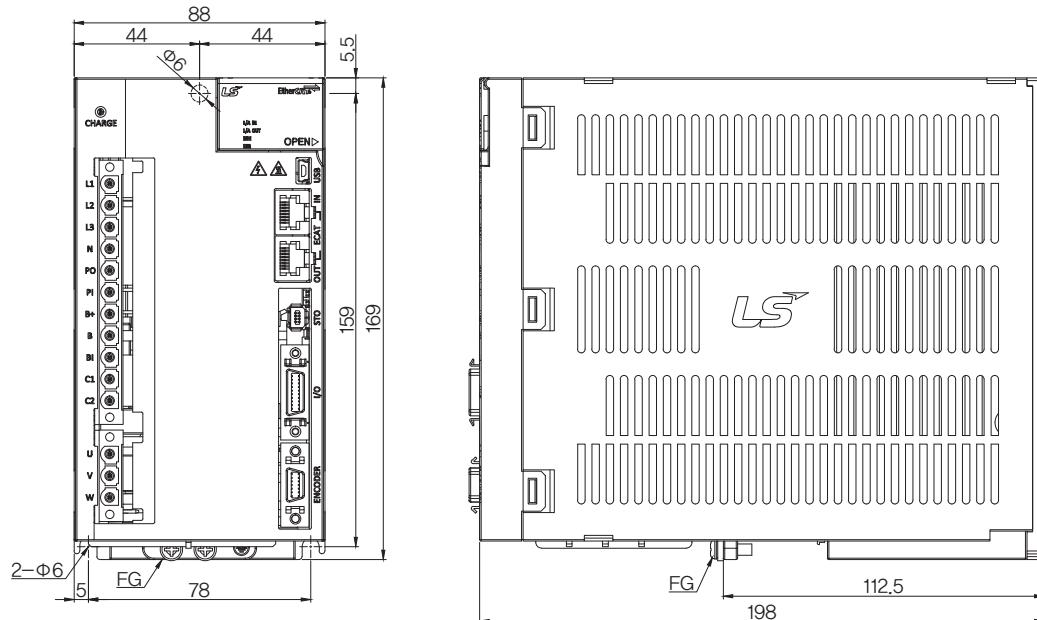


L7 SERIES SYSTEM

External Dimensions of L7NHA Drive

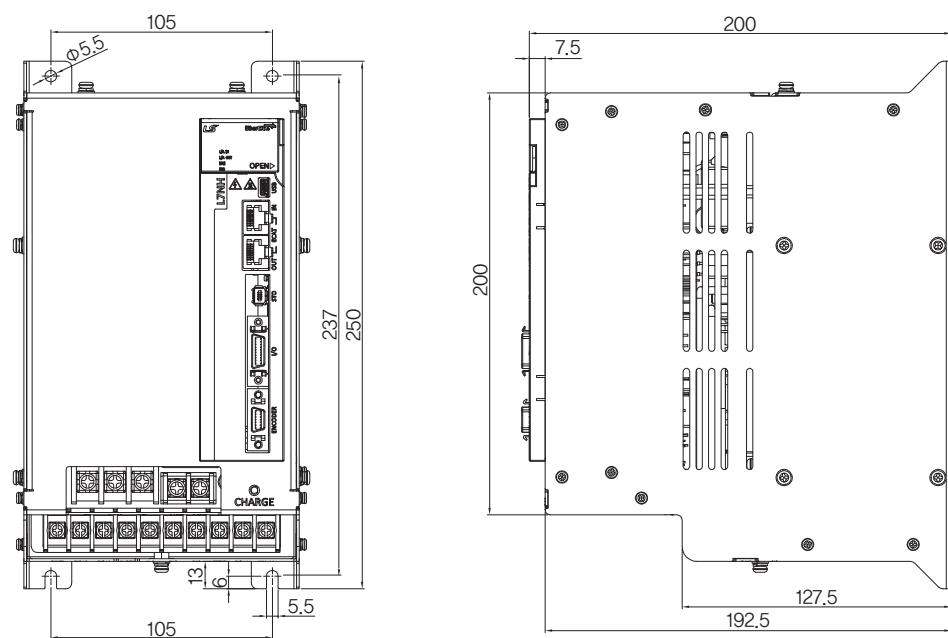
L7NHA020U / L7NHA035U [Weight : 2.5kg(Fan–Cooling included)]

* Unit [mm]



L7NHA050U [Weight : 5.5kg(Fan–Cooling included)]

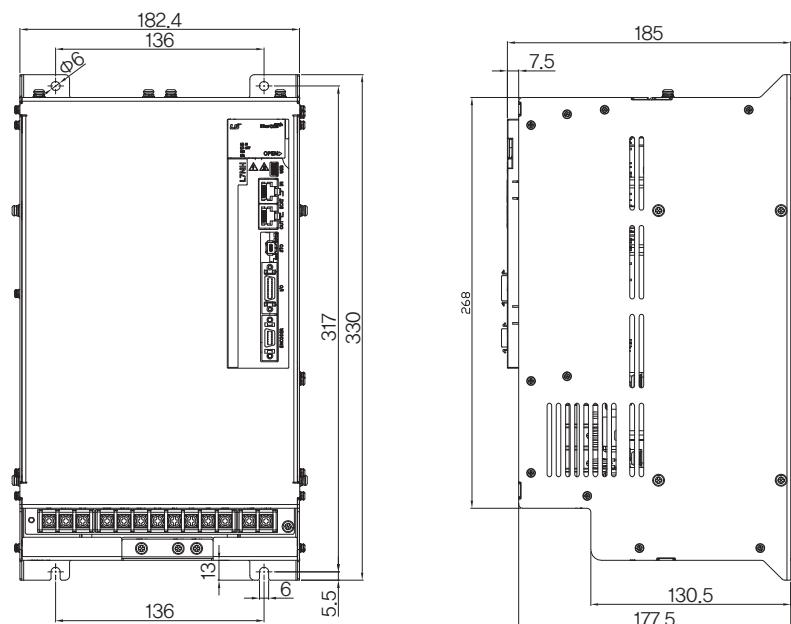
* Unit [mm]



External Dimensions of L7NHA Drive

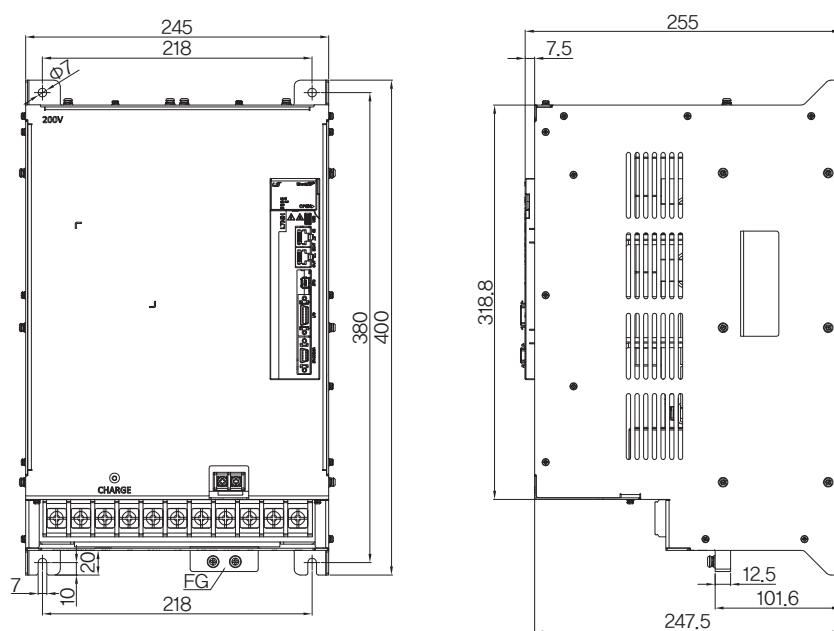
L7NHA075U [Weight : 8.5kg(Fan–Cooling included)]

*Unit [mm]



L7NHA150U [Weight : 16.2kg(Fan–Cooling included)]

*Unit [mm]

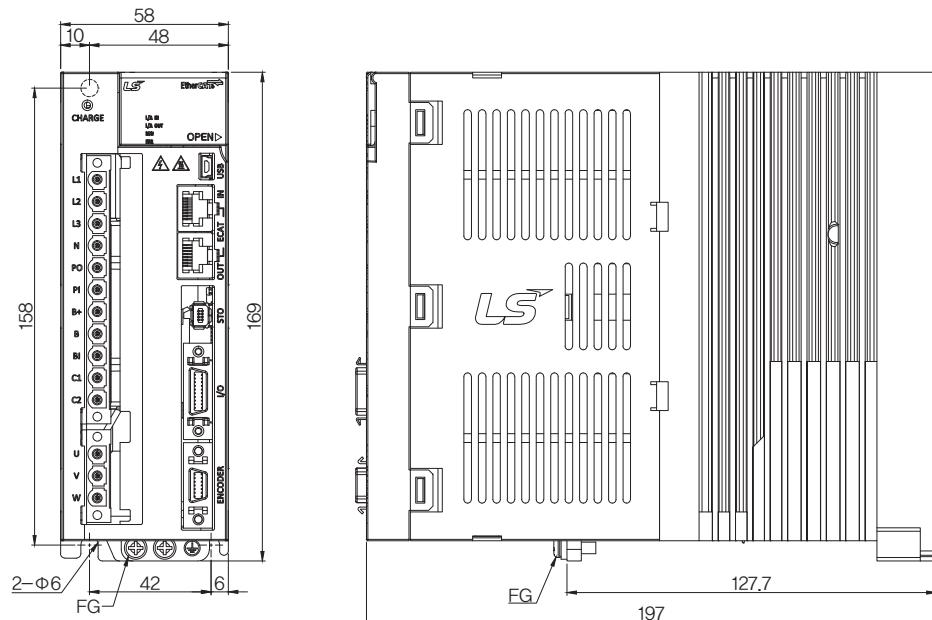


L7 SERIES SYSTEM

External Dimensions of L7NHB Drive

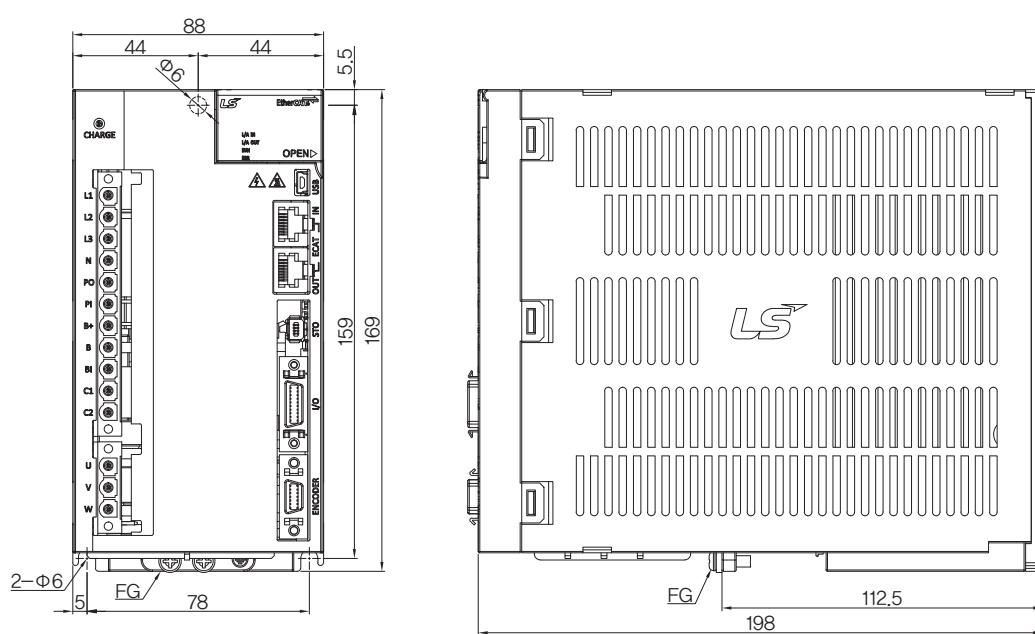
L7NHB010U [Weight : 1.5kg(Fan-Cooling included)]

* Unit [mm]



L7NHB020U / L7NHB035U [Weight : 2.5kg(Fan-Cooling included)]

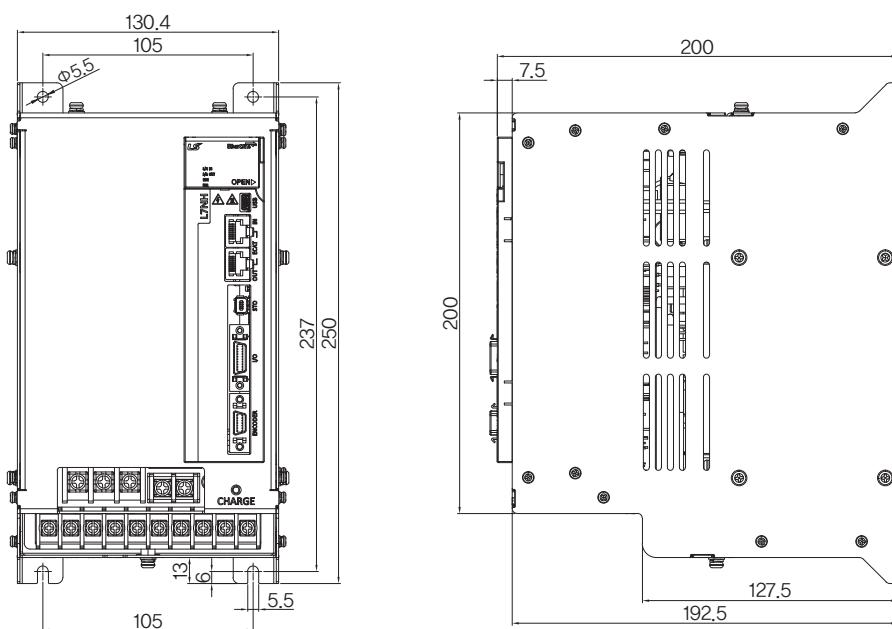
* Unit [mm]



External Dimensions of L7NHB Drive

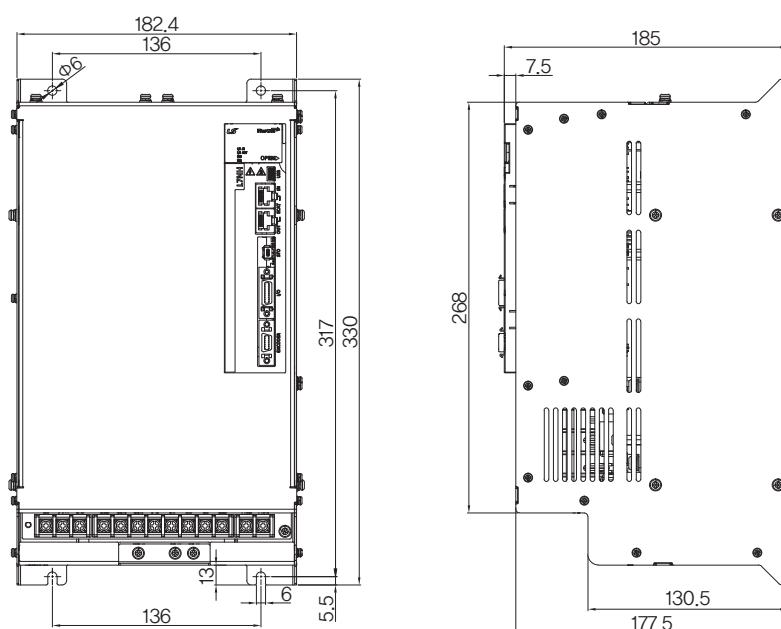
L7NHB050U [Weight : 5.5kg(Fan–Cooling included)]

*Unit [mm]



L7NHB075U [Weight : 8.5kg(Fan–Cooling included)]

*Unit [mm]



L7S Series

L7NH Series

L7P Series

S Series

F Series

MDM Series

PEGASUS Series

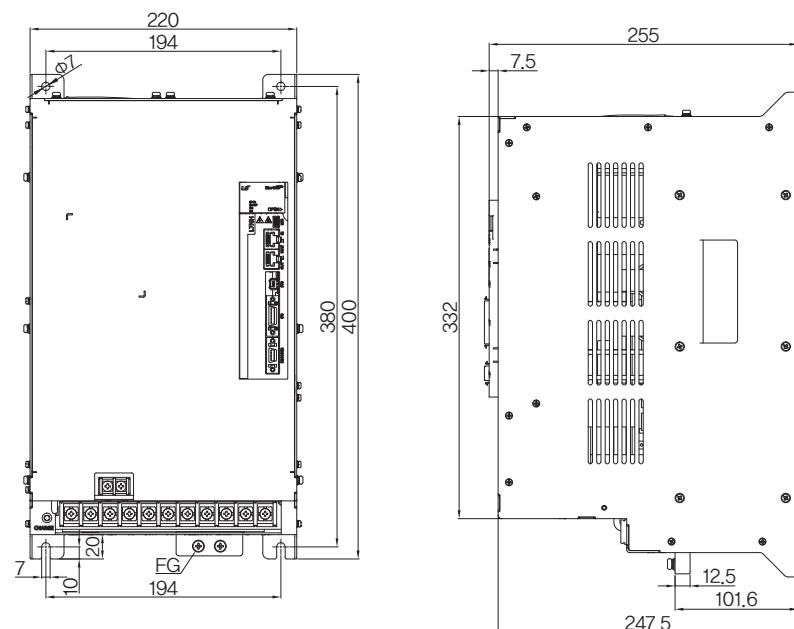
Options

L7 SERIES SYSTEM

External Dimensions of L7NHB Drive

■ **L7NHB150U** [Weight : 15.5kg(Fan-Cooling included)]

* Unit [mm]



Indexer Function Type

L7P Series



Servo Drive Designation

| L7 | P | A | 004 | U | AA |
|--|------------------------|--------------------------|---|---------------|-----------------------|
| Model Name | Communication | Input Power Supply | Capacity | Encoder Type | Option |
| Servo Series | Stand I/O & Index Type | A : 200VAC B : 400VAC | 001 : 100W 002 : 200W 004 : 400W 008 : 750W 010 : 1.0kW 020 : 2.0kW 035 : 3.5kW | U : Universal | Exclusive Option Code |
| * Range | | | | | |
| <ul style="list-style-type: none"> · 200V : 0.1kW~15kW · 400V : 1.0kW~15kW | | | | | |

L7 SERIES SYSTEM

L7P Series

Characteristic

● Providing Program Function built-in single axis position determination module

- Supporting position control mode by pulse input
- Position control mode
- Possible to use without upper controller
- Modbus RTU Protocol (RS-422)

● Improved Control Performance

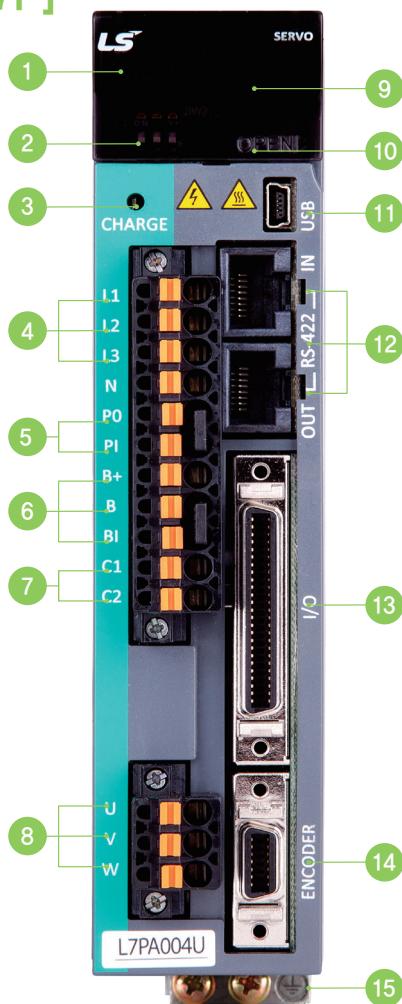
- Improved Control bandwidth
- Providing 4-step Notch-Filter
- Vibration control by Real-time FFT
- Real-time gain tuning function

● Support various motor and Encoder drive

- Supporting Rotary, DD and Motor drive (supporting 3rd party motor)
- Quadrature, BiSS-C, Tamagawa serial abs, EnDat 2.2

Identifying the Part of L7P Drive

[L7P]



- ① Display
- ② Dip Switch
- ③ Charge Lamp
- ④ Main Power Connector (L1, L2, L3)
- ⑤ DC Reactor Connector (PO, PI) Short-Circuit When Not used
- ⑥ Regenerative Resistor Connector (B+, B, BI)
 - Short-Circuit B, BI terminals when standard type
 - Use B+, B terminals when using external resistor
- ⑦ Control Power connector (C1, C2)
- ⑧ Motor power connector (U, V, W)
- ⑨ Connector for analogue monitor
- ⑩ Switch for nod address setting
- ⑪ USB connector (USB)
- ⑫ RS-422 communication connector (In / Out)
- ⑬ Control signal connector (I/O)
- ⑭ Encoder Connector (ENCODER)
- ⑮ PE(Protective Earth)

L7PA Drive Combination Table

L7PA Incremental Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder cable | Power Cable | | |
|-------------------|---------------------|--|--|--|-----------------------|---------------|-------------|-------------|---------------|
| | | | | | Quadrature Type | | INC | For power | Power + Brake |
| 3,000 | 5,000 | <input type="checkbox"/> 40 <input type="checkbox"/> 40 <input type="checkbox"/> 40 <input type="checkbox"/> 40 <input type="checkbox"/> 60 <input type="checkbox"/> 60 <input type="checkbox"/> 60 <input type="checkbox"/> 80 <input type="checkbox"/> 130 <input type="checkbox"/> 130 <input type="checkbox"/> 130 <input type="checkbox"/> 130 <input type="checkbox"/> 130 <input type="checkbox"/> 180 <input type="checkbox"/> 180 | L7PA001U L7PA001U L7PA001U L7PA002U L7PA002U L7PA004U L7PA004U L7PA006U L7PA008U L7PA008U L7PA010U L7PA008U L7PA020U L7PA020U L7PA020U L7PA035U L7PA035U L7PA050U | SAR3A SAR5A SA01A SA015A SB01A SB02A SB04A SC04A SC06A SC08A SC10A SE09A SE15A SE22A SE30A SF30A SF50A | * 2,048 P/R | APCS-E□□□AS | APCS-P□□□GS | APCS-B□□□QS | |
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L7 SERIES SYSTEM

L7PA Drive Combination Table

L7PA Serial Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder cable | | Power Cable | | |
|-------------------|---------------------|--------------------|------------------|------------------|-----------------------|---------------|---------------|--------------|--------------|---------------|
| | | | | | | Serial Type | Single Turn | Multi Turn | For power | Power + Brake |
| 3,000 | 5,000 | * 18Bit Serial Abs | □40 | FALR5A | L7PA001U | APCS-E□□□□ES | APCS-E□□□□ES1 | APCS-P□□□□LS | APCS-P□□□□QS | |
| | | | □40 | FAL01A | L7PA001U | | | | | |
| | | | □40 | FAL015A | L7PA004U | | | | | |
| | | | □60 | FBL01A | L7PA001U | | | | | |
| | | | □60 | FBL02A | L7PA002U | | | | | |
| | | | □60 | FBL04A | L7PA004U | | | | | |
| | | | □80 | FCL04A | L7PA004U | | | | | |
| | | | □80 | FCL06A | L7PA008U | | | | | |
| | | | □80 | FCL08A | L7PA008U | | | | | |
| | | | □80 | FCL10A | L7PA010U | | | | | |
| | | | □60 | FB01A | L7PA001U | | | | | |
| | | | □60 | FB02A | L7PA002U | | | | | |
| | | | □60 | FB04A | L7PA004U | | | | | |
| | | | □80 | FC04A | L7PA004U | | | | | |
| | | | □80 | FC06A | L7PA008U | | | | | |
| | | | □80 | FC08A | L7PA008U | | | | | |
| | | | □80 | FC10A | L7PA010U | | | | | |
| | | | □130 | FE09A | L7PA010U | | | | | |
| | | | □130 | FE15A | L7PA020U | | | | | |
| | | | □130 | FE22A | L7PA020U | | | | | |
| | | | □130 | FE30A | L7PA035U | | | | | |
| | | | □180 | FF30A | L7PA035U | | | | | |
| | | | □180 | FF50A | L7PA050U | | | | | |
| 2,000 | 3,000 | * 19Bit Serial Abs | □80 | FCL03D | L7PA004U | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□HS | APCS-P□□□□NB | APCS-P□□□□QS |
| | | | □80 | FCL05D | L7PA008U | | | | | |
| | | | □80 | FCL06D | L7PA008U | | | | | |
| | | | □80 | FCL07D | L7PA008U | | | | | |
| | | | □80 | FC03D | L7PA004U | | | | | |
| | | | □80 | FC05D | L7PA008U | | | | | |
| | | | □80 | FC06D | L7PA008U | | | | | |
| | | | □80 | FC07D | L7PA008U | | | | | |
| | | | □130 | FE06D | L7PA008U | | | | | |
| | | | □130 | FE11D | L7PA010U | | | | | |
| | | | □130 | FE16D | L7PA020U | | | | | |
| | | | □130 | FE22D | L7PA020U | | | | | |
| | | | □180 | FF22D | L7PA020U | | | | | |
| | | | □180 | FF35D | L7PA035U | | | | | |
| | | | □180 | FF55D | L7PA050U | | | | | |
| | | | □180 | FF75D | L7PA075U | | | | | |
| 1,500 | 3,000 | * 19Bit Serial Abs | □220 | FG22D | L7PA020U | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□HS | APCS-P□□□□NB | APCS-P□□□□QS |
| | | | □220 | FG35D | L7PA035U | | | | | |
| | | | □220 | FG55D | L7PA050U | | | | | |
| | | | □220 | FG75D | L7PA075U | | | | | |
| | | | □220 | FG11D | L7PA150U | | | | | |
| | | | □130 | FE05G | L7PA008U | | | | | |
| | | | □130 | FE09G | L7PA010U | | | | | |
| | | | □130 | FE13G | L7PA020U | | | | | |
| | | | □130 | FE17G | L7PA020U | | | | | |
| | | | □180 | FF20G | L7PA020U | | | | | |
| | | | □180 | FF30G | L7PA035U | | | | | |
| | | | □180 | FF44G | L7PA050U | | | | | |
| | | | □180 | FF60G | L7PA075U | | | | | |
| | | | □220 | FG20G | L7PA020U | | | | | |
| | | | □220 | FG30G | L7PA035U | | | | | |
| | | | □220 | FG44G | L7PA050U | | | | | |
| 1,000 | 2,000 | * 19Bit Serial Abs | □220 | FG60G | L7PA075U | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□HS | APCS-P□□□□NB | APCS-P□□□□QS |
| | | | □220 | FG85G | L7PA150U | | | | | |
| | | | □220 | FG11G | L7PA150U | | | | | |
| | | | □220 | FG15G | L7PA150U | | | | | |
| | | | □130 | FE03M | L7PA004U | | | | | |
| | | | □130 | FE06M | L7PA008U | | | | | |
| | | | □130 | FE09M | L7PA010U | | | | | |
| | | | □130 | FE12M | L7PA020U | | | | | |
| | | | □180 | FF12M | L7PA020U | | | | | |
| | | | □180 | FF20M | L7PA020U | | | | | |
| 1,700 | 2,000 | * 19Bit Serial Abs | □180 | FF30M | L7PA035U | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□HS | APCS-P□□□□NB | APCS-P□□□□QS |
| | | | □180 | FF44M | L7PA050U | | | | | |
| | | | □220 | FG12M | L7PA020U | | | | | |
| | | | □220 | FG20M | L7PA020U | | | | | |
| | | | □220 | FG30M | L7PA035U | | | | | |
| | | | □220 | FG44M | L7PA050U | | | | | |
| 1,700 | 2,000 | * 19Bit Serial Abs | □220 | FG60M | L7PA075U | APCS-E□□□□DS | APCS-E□□□□DS1 | APCS-P□□□□JS | APCS-P□□□□SB | APCS-P□□□□QS |

L7PB Drive Combination Table

L7PB Incremental Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder cable | Power Cable | | |
|-------------------|---------------------|-------------|------------------|------------------|-----------------------|---------------|-------------|---------------|-------|
| | | | | | Quadrature Type | INC | For power | Power + Brake | Brake |
| 3,000 | 5,000 | | □130 | SEP09A | L7PB010U | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | SEP15A | L7PB020U | | APCF-P□□□IS | | |
| | | | □130 | SEP22A | L7PB020U | | APCF-P□□□JS | | |
| | | | □130 | SEP30A | L7PB035U | | APCF-P□□□IS | | |
| | | | □180 | SFP30A | L7PB035U | | APCF-P□□□JS | | |
| | | | □180 | SFP50A | L7PB050U | | APCF-P□□□IS | | |
| 2,000 | 3,000 | | □130 | SEP06D | L7PB010U | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | SEP11D | L7PB010U | | APCF-P□□□IS | | |
| | | | □130 | SEP16D | L7PB020U | | APCF-P□□□JS | | |
| | | | □130 | SEP22D | L7PB020U | | APCF-P□□□IS | | |
| | | | □180 | SFP22D | L7PB020U | | APCF-P□□□JS | | |
| | | | □180 | SFP35D | L7PB035U | | APCF-P□□□IS | | |
| | | | □180 | SFP55D | L7PB050U | | APCF-P□□□JS | | |
| | | | □180 | SFP75D | L7PB075U | | APCF-P□□□IS | | |
| | | | □220 | SGP22D | L7PB020U | | APCF-P□□□JS | | |
| | | | □220 | SGP35D | L7PB035U | | APCF-P□□□MS | APCF-P□□□SB | |
| 1,500 | 3,000 | | □180 | SGP55D | L7PB050U | | APCF-P□□□JS | | |
| | | | □220 | SGP75D | L7PB075U | | APCF-P□□□MS | | |
| | | | □220 | SGP10D | L7PB150U | | APCF-P□□□IS | | |
| | | | □130 | SEP05G | L7PB010U | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | SEP09G | L7PB010U | | APCF-P□□□IS | | |
| | | | □130 | SEP13G | L7PB020U | | APCF-P□□□JS | | |
| | | | □130 | SEP17G | L7PB020U | | APCF-P□□□MS | | |
| 1,000 | 2,500 | | □180 | SFP20G | L7PB020U | | APCF-P□□□IS | APCF-P□□□PB | |
| | | | □180 | SFP30G | L7PB050U | | APCF-P□□□JS | | |
| | | | □180 | SFP44G | L7PB050U | | APCF-P□□□MS | | |
| | | | □180 | SFP60G | L7PB075U | | APCF-P□□□IS | | |
| | | | □180 | SFP75G | L7PB075U | | APCF-P□□□JS | | |
| | | | □220 | SGP20G | L7PB020U | | APCF-P□□□MS | | |
| | | | □220 | SGP30G | L7PB050U | | APCF-P□□□IS | APCF-P□□□LB | |
| 1,000 | 3,000 | | □220 | SGP44G | L7PB050U | | APCF-P□□□JS | | |
| | | | □220 | SGP60G | L7PB075U | | APCF-P□□□MS | | |
| | | | □220 | SGP85G | L7PB150U | | APCF-P□□□IS | | |
| | | | □220 | SGP110G | L7PB150U | | APCF-P□□□JS | | |
| | | | □220 | SGP150G | L7PB150U | | APCF-P□□□MS | | |
| | | | □130 | SEP03M | L7PB010U | | APCF-P□□□HS | APCF-P□□□NB | |
| | | | □130 | SEP06M | L7PB010U | | APCF-P□□□IS | | |
| 1,000 | 2,000 | | □130 | SEP09M | L7PB010U | | APCF-P□□□JS | | |
| | | | □130 | SEP12M | L7PB020U | | APCF-P□□□IS | APCF-P□□□PB | |
| | | | □180 | SFP12M | L7PB020U | | APCF-P□□□JS | | |
| | | | □180 | SFP20M | L7PB020U | | APCF-P□□□MS | APCF-P□□□LB | |
| | | | □180 | SFP30M | L7PB035U | | APCF-P□□□IS | | |
| | | | □180 | SFP44M | L7PB050U | | APCF-P□□□JS | | |
| | | | □220 | SGP12M | L7PB020U | | APCF-P□□□MS | | |
| 1,000 | 1,700 | | □220 | SGP20M | L7PB020U | | APCF-P□□□IS | | |
| | | | □220 | SGP30M | L7PB050U | | APCF-P□□□JS | | |
| | | | □220 | SGP44M | L7PB050U | | APCF-P□□□MS | APCF-P□□□SB | |
| | | | □220 | SGP60M | L7PB075U | | APCF-P□□□IS | | |
| | | | □220 | SGP10G | L7PB150U | | APCF-P□□□JS | | |
| | | | □220 | SGP150G | L7PB150U | | APCF-P□□□MS | | |
| | | | □180 | SFP30M | L7PB035U | | APCF-P□□□IS | | |
| 1,000 | 2,000 | | □180 | SFP44M | L7PB050U | | APCF-P□□□JS | APCF-P□□□LB | |
| | | | □220 | SGP12M | L7PB020U | | APCF-P□□□MS | | |
| | | | □220 | SGP20M | L7PB020U | | APCF-P□□□IS | | |
| | | | □220 | SGP30M | L7PB050U | | APCF-P□□□JS | | |
| | | | □220 | SGP44M | L7PB050U | | APCF-P□□□MS | | |
| | | | □220 | SGP60M | L7PB075U | | APCF-P□□□IS | APCF-P□□□SB | |
| | | | □220 | SGP10G | L7PB150U | | APCF-P□□□JS | | |

L7 SERIES SYSTEM

L7PB Drive Combination Table

■ L7PB Serial Type

| Rated Speed (rpm) | Maximum Speed (rpm) | Flange Size | Applicable Motor | Applicable Drive | Standard Encoder Type | Encoder cable | | Power Cable | | | |
|-------------------|---------------------|-------------|------------------|------------------|-----------------------|---------------|-------------|-------------|------------|---------------|-------------|
| | | | | | | Serial Type | Single Turn | Multi Turn | For power | Power + Brake | Brake |
| 3,000 | 5,000 | □130 | FEP09A | L7PB010U | * 19Bit Serial Abs | APCS-E□□□DS1 | APCF-P□□□HS | APCF-P□□□NB | APCF-P□□□S | APCF-P□□□PB | APCF-P□□□JS |
| | | | FEP15A | L7PB020U | | | | | | | |
| | | | FEP22A | L7PB035U | | | | | | | |
| | | | FEP30A | L7PB035U | | | | | | | |
| | | | FFP30A | L7PB035U | | | | | | | |
| | | | FFP50A | L7PB050U | | | | | | | |
| 2,000 | 3,000 | □130 | FEP06D | L7PB010U | | | | | | | |
| | | | FEP11D | L7PB010U | | | | | | | |
| | | | FEP16D | L7PB020U | | | | | | | |
| | | | FEP22D | L7PB020U | | | | | | | |
| | | | FFP22D | L7PB020U | | | | | | | |
| | | | FFP35D | L7PB035U | | | | | | | |
| 1,500 | 2,500 | □180 | FFP55D | L7PB050U | | | | | | | |
| | | | FFP75D | L7PB075U | | | | | | | |
| | | | FGP22D | L7PB020U | | | | | | | |
| | | | FGP35D | L7PB035U | | | | | | | |
| | | | FGP55D | L7PB050U | | | | | | | |
| | | | FGP75D | L7PB075U | | | | | | | |
| 1,000 | 2,000 | □220 | FEP10D | L7PB150U | | | | | | | |
| | | | FEP05G | L7PB010U | | | | | | | |
| | | | FEP09G | L7PB010U | | | | | | | |
| | | | FEP13G | L7PB020U | | | | | | | |
| | | | FEP17G | L7PB020U | | | | | | | |
| | | | FFP20G | L7PB020U | | | | | | | |
| 1,700 | 2,000 | □180 | FFP30G | L7PB035U | | | | | | | |
| | | | FFP44G | L7PB050U | | | | | | | |
| | | | FFP60G | L7PB075U | | | | | | | |
| | | | FFP75G | L7PB075U | | | | | | | |
| | | | FGP20G | L7PB020U | | | | | | | |
| | | | FGP30G | L7PB035U | | | | | | | |
| 2,000 | 2,000 | □220 | FGP44G | L7PB050U | | | | | | | |
| | | | FGP60G | L7PB075U | | | | | | | |
| | | | FGP85G | L7PB150U | | | | | | | |
| | | | FGP110G | L7PB150U | | | | | | | |
| | | | FGP150G | L7PB150U | | | | | | | |
| | | | FEP03M | L7PB010U | | | | | | | |
| 1,700 | 2,000 | □130 | FEP06M | L7PB010U | | | | | | | |
| | | | FEP09M | L7PB010U | | | | | | | |
| | | | FEP12M | L7PB020U | | | | | | | |
| | | | FFP12M | L7PB020U | | | | | | | |
| | | | FFP20M | L7PB020U | | | | | | | |
| | | | FFP30M | L7PB035U | | | | | | | |
| 2,000 | 2,000 | □180 | FFP44M | L7PB050U | | | | | | | |
| | | | FGP12M | L7PB020U | | | | | | | |
| | | | FGP20M | L7PB020U | | | | | | | |
| | | | FGP30M | L7PB050U | | | | | | | |
| | | | FGP44M | L7PB050U | | | | | | | |
| | | | FGP60M | L7PB075U | | | | | | | |

L7PA Drive Product Features

| Item | Type Name | L7PA001U | L7PA002U | L7PA004U | L7PA008U | L7PA010U | L7PA020U | L7PA035U | L7PA050U | L7PA075U | L7PA150U |
|------------------------------------|------------------------------|---|----------|----------|----------|----------|----------|----------|----------|----------|----------|
| Input Power | Main Power Supply | 3-Phase AC 200~230[V](-15~10[%]), 50~60[Hz] | | | | | | | | | |
| | Control Power Supply | Single-Phase AC 200~230[V](-15~10[%]), 50~60[Hz] | | | | | | | | | |
| | Rated Current[A] | 1.4 | 1.7 | 3.0 | 5.2 | 6.75 | 13.5 | 16.7 | 32 | 39.4 | 76 |
| | Peak Current[A] | 4.2 | 5.1 | 9.0 | 15.6 | 20.25 | 40.5 | 50.1 | 90.88 | 98.5 | 190 |
| | Encoder Type | Quadrature(Incremental) BISS-B, BISS-C(Absolute, Incremental) Tamagawa Serial(Absolute, Incremental) EnDat 2.2 | | | | | | | | | |
| Control Performance | Speed Control Range | Maximum 1: 5000 | | | | | | | | | |
| | Frequency Response | Maximum 1 [kHz] or above (When using 19bit Serial Encoder) | | | | | | | | | |
| | Speed Variation Ratio | $\pm 0.01 [\%]$ or lower [when load changes between 0 and 100%] $\pm 0.1 [\%]$ or lower [temperature 25 $\pm 10^\circ\text{C}$] | | | | | | | | | |
| | Accel/Decel Time | Straight or S-curveacceleration/deceleration (0~10,000[ms], 0~1,000[ms] Unitconfigurable) | | | | | | | | | |
| | Input Frequency | 1[Mpps], line drive / 200[kpps], Open Collectorpr | | | | | | | | | |
| | Input Pulse Type | Symbol + Pulse Series, CW+CCW, A/B Phase | | | | | | | | | |
| RS422 Communication Specifications | Communication Specifications | ANSI/TIA/EIA-422 StandardSpecficiations | | | | | | | | | |
| | Communication Protocol | MODBUS-RTU | | | | | | | | | |
| | Connector | RJ45 x 2 | | | | | | | | | |
| | Synchro Method | Asynchronous | | | | | | | | | |
| | Transmission Speed | 9600 /19200/38400/57600 [bps] Can be configured at [0x3002] | | | | | | | | | |
| | Transmission Distance | Maximum 200 [m] | | | | | | | | | |
| Input/Output Signal | Power Consumption | 100[mA] Less than | | | | | | | | | |
| | Terminating Resistance | Dip S/W(On/Off), Built-In 120Ω | | | | | | | | | |
| | Digital Input | Input voltage range: DC 12[V] ~ DC 24[V] Total 16 input channel (allocatable) 32 function inputs can be selectively allocated (*SV_ON, *POT, *NOT, *A-RST, *START, *STOP, *REGT, *EMG, *HOME, *HSTART, *ISEL0, *ISEL1, *ISEL2, *ISEL3, *ISEL4, *ISEL5, PCON, GAIN2, P_CL, N_CL, MODE, PAUSE, ABSRQ, JSTART, JDIF, PCLR, AOVR, SPD1/LVSF1, SPD2/LVSF2, SPD3, PROBE1, PROBE2) * Basic allocationsignal. | | | | | | | | | |
| | Digital Output | Use rating: DC 24[V] $\pm 10\%$, 120[mA] Total 8 input channel (allocatable) 19 function inputs can be selectively allocated (*ALARM \pm , *READY \pm , *BRAKE \pm , *INPOS1 \pm , *ORG \pm , *EOS \pm , *TGON \pm , *TLMT \pm , VLMT \pm , INSPD \pm , ZSPD \pm , WARN \pm , INPOS2 \pm , IOUT0 \pm , IOUT1 \pm , IOUT2 \pm IOUT3 \pm , IOUT4 \pm , IOUT5 \pm) * Standard Allocationsignal | | | | | | | | | |
| | Analog input | Total 2 channels analogspeedoverrideinput(-10[V] ~ +10[V]) analogtorquecommand input(-10[V] ~ +10[V]) | | | | | | | | | |
| | Analog output | Total 2 channels 15 function inputs can be selectively allocated | | | | | | | | | |
| USB Communciation | Protection | Firmware download, parametersetting, tuning, auxiliary function,parametercopy | | | | | | | | | |
| | Communication Specifications | Complies with USB 2.0 Full Speed Specifications | | | | | | | | | |
| | Connection Device | PC or USB storage media | | | | | | | | | |
| Built-in functions | Dynamic Braking | Standard built-in(activated by servoalarm or servo OFF) | | | | | | | | | |
| | Regenerative Braking | Built-in, external brake attachable | | | | | | | | | |
| | Display | 7 Segment(5 DIGIT) | | | | | | | | | |
| | Setting Function | Drive node address can be set using rotary switch | | | | | | | | | |
| | Additional Function | Gaintuning, alarm history, JOG operation, origin search | | | | | | | | | |
| | Protective Function | Excessie current, overload, excessive current limit, overheating, excessive voltage, low voltage, excessive speed, encoder fail, position following fail, current sensing fail | | | | | | | | | |
| Environment | Temperature | 0 ~ 50[°C] / -20 ~ 65 °C | | | | | | | | | |
| | Humidity | Below 90[%]RH(avoid dew-condensation) | | | | | | | | | |
| | Environment | Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust. | | | | | | | | | |

L7S Series

L7NH Series

L7P Series

S Series

F Series

MDM Series

PEGASUS Series

Options

L7 SERIES SYSTEM

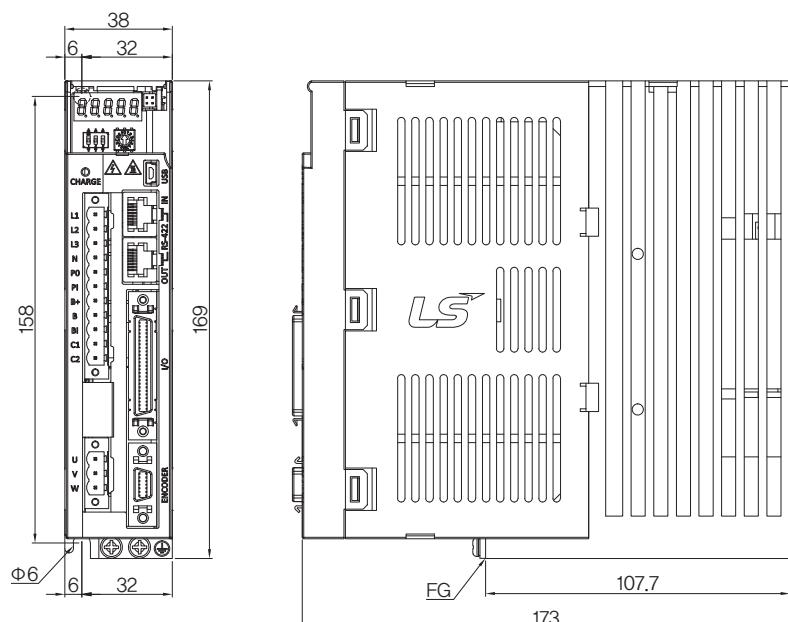
L7PB Drive Product Features

| Item | Type Name | L7PB010U | L7PB020U | L7PB035U | L7PB050U | L7PB075U | L7PB150U |
|------------------------------------|------------------------------|--|----------|----------|----------|----------|----------|
| Input Power | Main Power Supply | 3 Phase AC380 ~ 480[V](-15 ~ +10[%]), 50 ~ 60[Hz] | | | | | |
| | Control Power Supply | Single Phase AC380 ~ 480[V](-15 ~ +10[%]), 50 ~ 60[Hz] | | | | | |
| | Rated Current[A] | 3.7 | 8 | 10.1 | 17.5 | 22.8 | 39 |
| | Peak Current[A] | 11.1 | 24 | 30.3 | 47.25 | 57 | 97.5 |
| | Encoder Type | Universal Encoder Feedback Quadrature(Incremental) BISS-B, BISS-C(Absolute, Incremental) Tamagawa Serial(Absolute, Incremental) EnDat 2.2 | | | | | |
| Control Performance | Speed Control Range | Maximum 1: 5000 | | | | | |
| | Frequency Response | Maximum 1 [kHz] or above (When using 19bit Serial Encoder) | | | | | |
| | Speed Variation Ratio | ±0.01 [%] or lower [when load changes between 0 and 100%] ±0.1[%] or lower [temperature 25 ±10°C] | | | | | |
| | Accel/Decel Time | Straight or S-curve acceleration/deceleration (0~10,000 [ms], possible to be set by one [ms] unit) | | | | | |
| | Input Frequency | 1[Mpps], Line Driver / 200[kpps], Open Collector | | | | | |
| | Input Pulse Type | Symbol + Pulse Series, CW+CCW, A/B Phase | | | | | |
| RS422 Communication Specifications | Communication Specifications | ANSI/TIA/EIA-422 StandardSpecficiations | | | | | |
| | Communication Protocol | MODBUS-RTU | | | | | |
| | Connector | RJ45 x 2 | | | | | |
| | Synchro Method | Asynchronous | | | | | |
| | Transmission Speed | 9600 /19200/38400/57600 [bps] Can be configured at [0x3002] | | | | | |
| | Transmission Distance | Maximum 200 [m] | | | | | |
| | Power Consumption | 100[mA] Less than | | | | | |
| | Terminating Resistance | Dip S/W(On/Off), Built-In 120Ω | | | | | |
| Input/Output Signal | Digital Input | Input voltage range: DC 12[V] ~ DC 24[V] Total 16 input channel (allocatable) 30 function inputs can be selectively allocated *SV_ON, *POT, *NOT, *A-RST, *START, *STOP, *REGT, *EMG, *HOME, *HSTART, *SEL0, *SEL1, *SEL2, *SEL3, *SEL4, *SEL5, *PCON, *GAIN2, *P_CL, *N_CL, *PAUSE, *ABS_RQ, *JSTART, *JDIR, *PCLR, *AOVR, *SPD1/LVFS1, *SPD2/LVFS2, *SPD3, *MODE주) * Basic allocationsignal. | | | | | |
| | Digital Output | Use rating: DC 24[V] ±10%, 120[mA] Total 8 input channel (allocatable) 19 function inputs can be selectively allocated *ALARM±, *READY±, *BRAKE±, *INPOS1±, *ORG±, *EOS±, *TGON±, *TLMT±, VLMT±, INSPD±, ZSPD±, WARN±, INPOS2±, IOUT0±, IOUT1±, IOUT2± IOUT3±, IOUT4±, IOUT5± * Basic allocationsignal. | | | | | |
| Analog Input/output | Analog input | Total 2 channels analog speed override input(-10[V] ~ +10[V]) analog torque command input(-10[V] ~ +10[V]) | | | | | |
| | Analog output | Total 2 channels 15 function inputs can be selectively allocated | | | | | |
| USB Communication | Protection | Firmware download, parameter setting, tuning, auxiliary function, parameter copy | | | | | |
| | Communication Specifications | Complies with USB 2.0 Full Speed Specifications | | | | | |
| | Connection Device | PC or USB storage media | | | | | |
| Built-in functions | Dynamic Braking | Standard built-in(activated by servo alarm or servo OFF) | | | | | |
| | Regenerative Braking | Built-in, external brake attachable | | | | | |
| | Display | 7 Segment(5 DIGIT) | | | | | |
| | Setting Function | Drive node address can be set using rotary switch | | | | | |
| | Additional Function | Gain tuning, alarm history, JOG operation, origin search | | | | | |
| | Protective Function | Excessive current, overload, excessive current limit, overheating, excessive voltage, low voltage, excessive speed, encoder fail, position following fail, current sensing fail | | | | | |
| Environment | Temperature | 0 ~ 50 [°C] / -20 ~ 70 [°C] | | | | | |
| | Humidity | Below 80[%]RH(avoid dew-condensation) / Below 90[%]RH(avoid dew-condensation) | | | | | |
| | Environment | Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust. | | | | | |

External Dimensions of L7P Drive

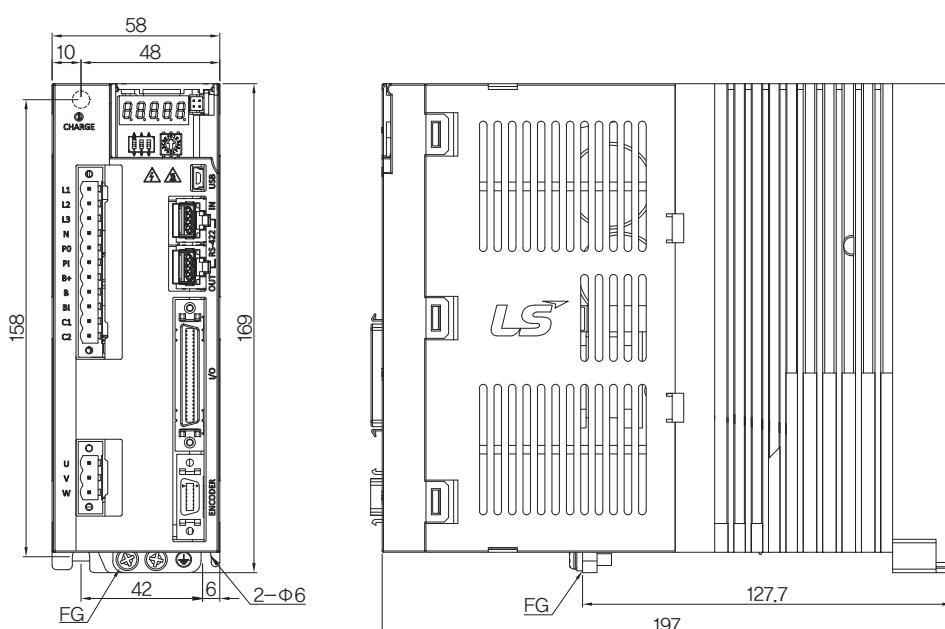
L7PA001U ~ L7PA004U [Weight : 1.0kg]

* Unit [mm]



L7PA008U / L7PA010U [Weight : 1.5kg(Fan-Cooling included)]

* Unit [mm]

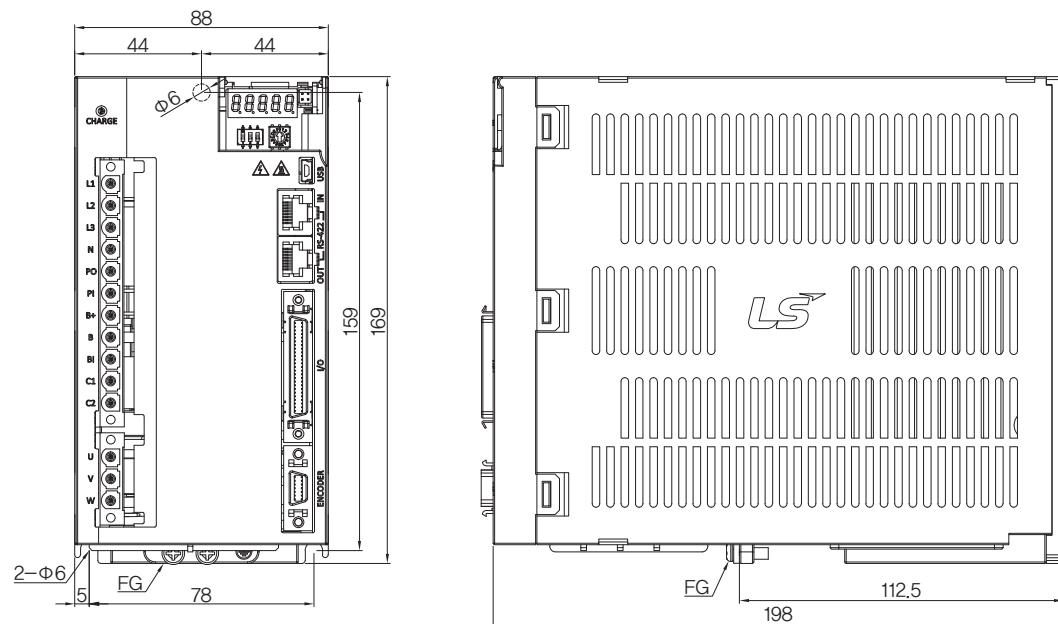


L7 SERIES SYSTEM

External Dimensions of L7PA Drive

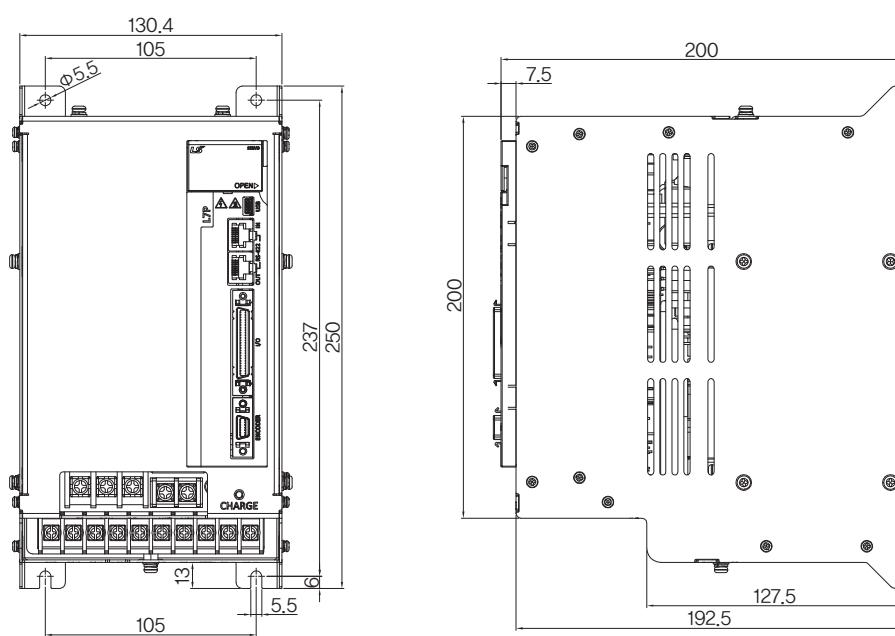
L7PA020U / L7PA035U [Weight : 2.5kg(Fan–Cooling included)]

* Unit [mm]



L7PA050U [Weight : 5.5kg(Fan–Cooling included)]

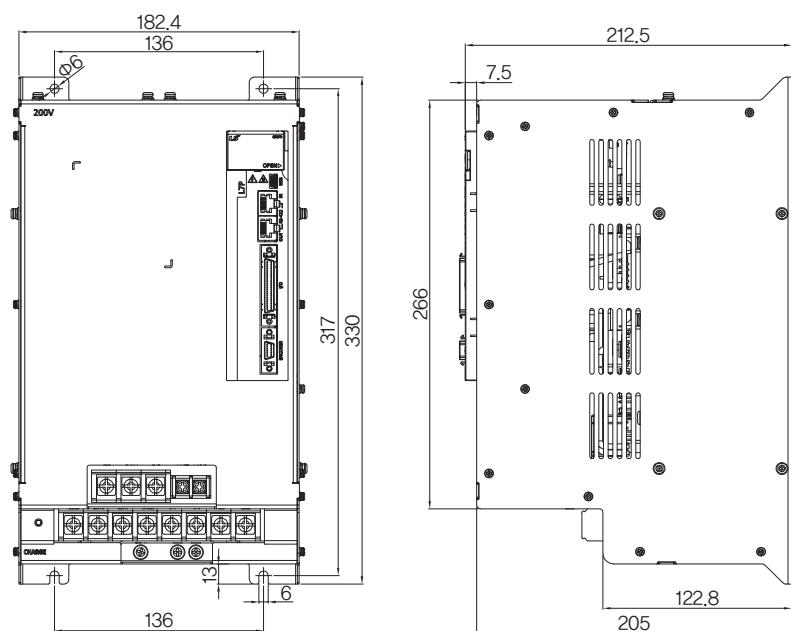
* Unit [mm]



External Dimensions of L7PA Drive

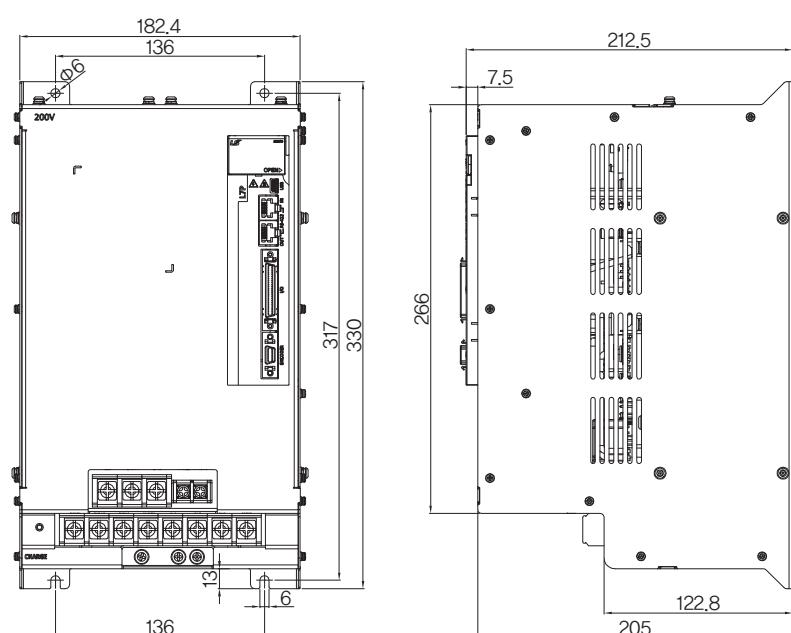
L7PA075U [Weight : 8.5kg(Fan–Cooling included)]

* Unit [mm]



L7PA150U [Weight : 16.2kg(Fan–Cooling included)]

* Unit [mm]



L7S Series

L7N Series

L7P Series

S Series

F Series

MDM Series

Options

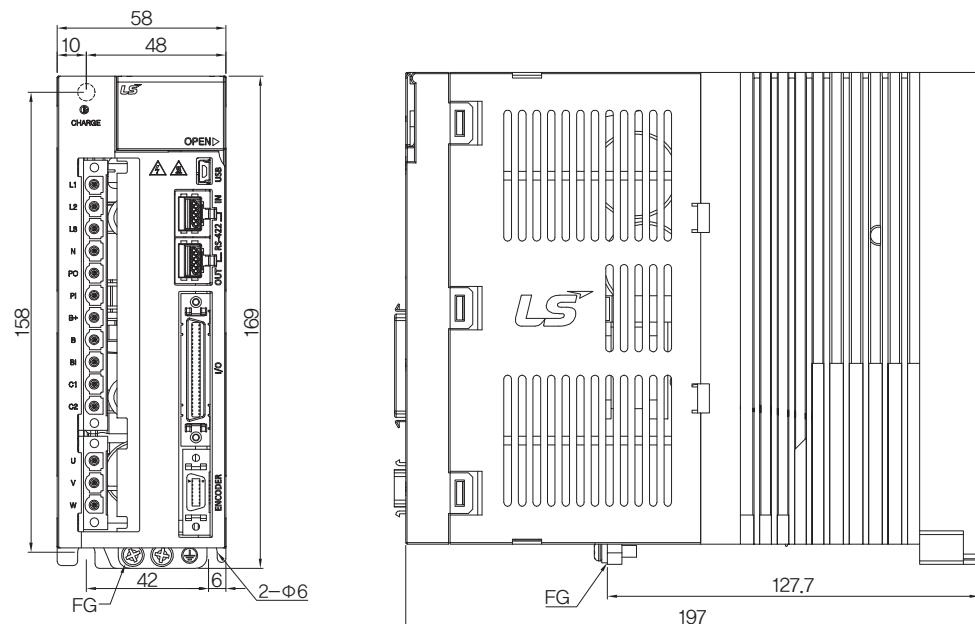
PEGASUS Series

L7 SERIES SYSTEM

External Dimensions of L7PB Drive

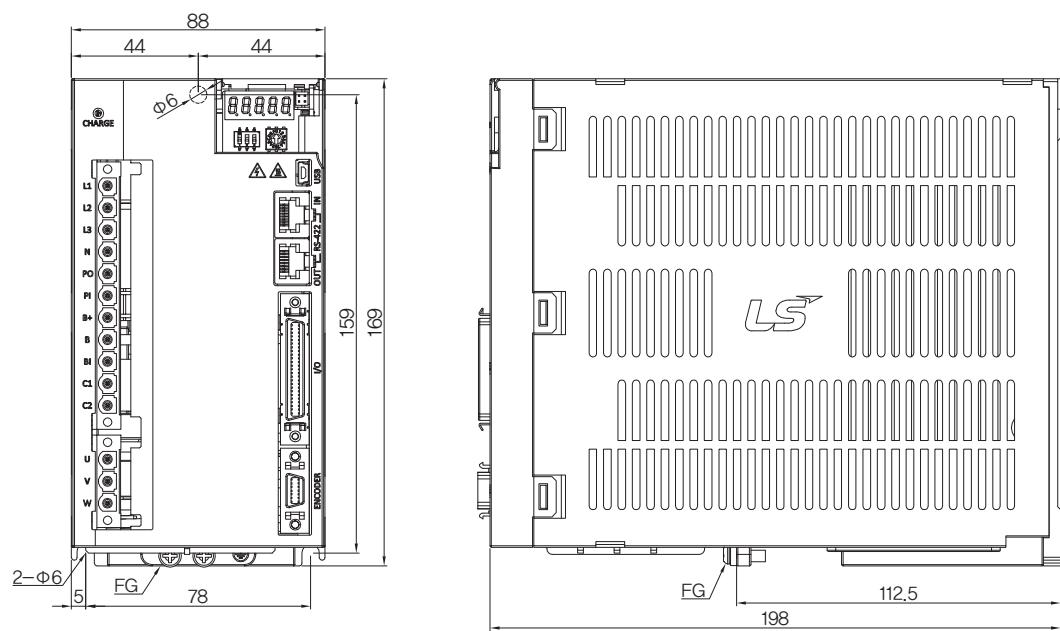
L7PB010U [Weight : 1.5kg(Fan-Cooling included)]

* Unit [mm]



L7PB020U / L7PB035U [Weight : 2.5kg(Fan-Cooling included)]

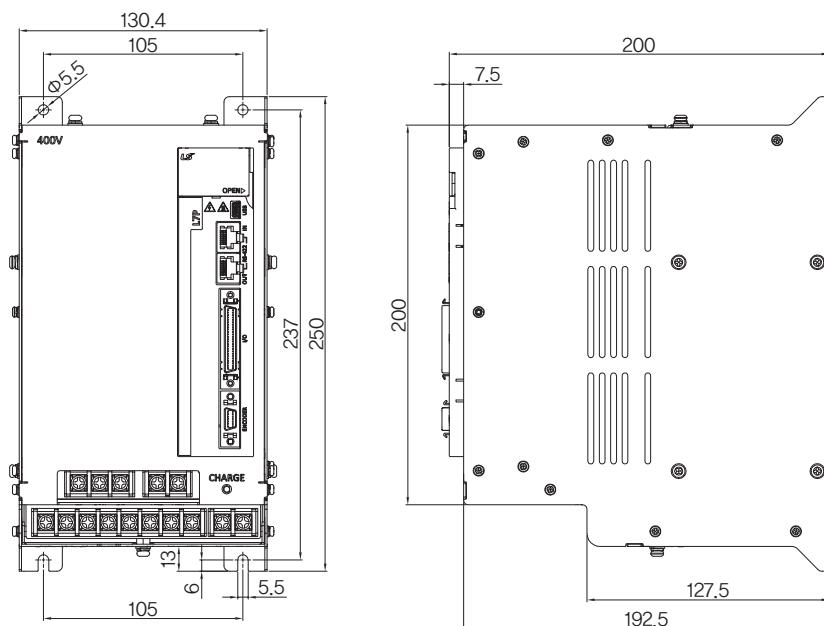
* Unit [mm]



External Dimensions of L7PB Drive

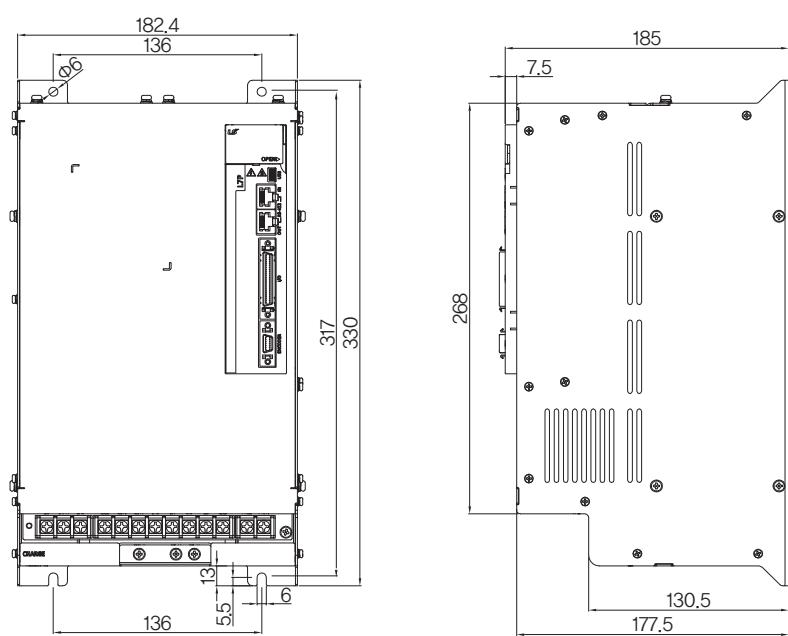
L7PB050U [Weight : 5.5kg(Fan–Cooling included)]

*Unit [mm]



L7PB075U [Weight : 8.5kg(Fan–Cooling included)]

*Unit [mm]

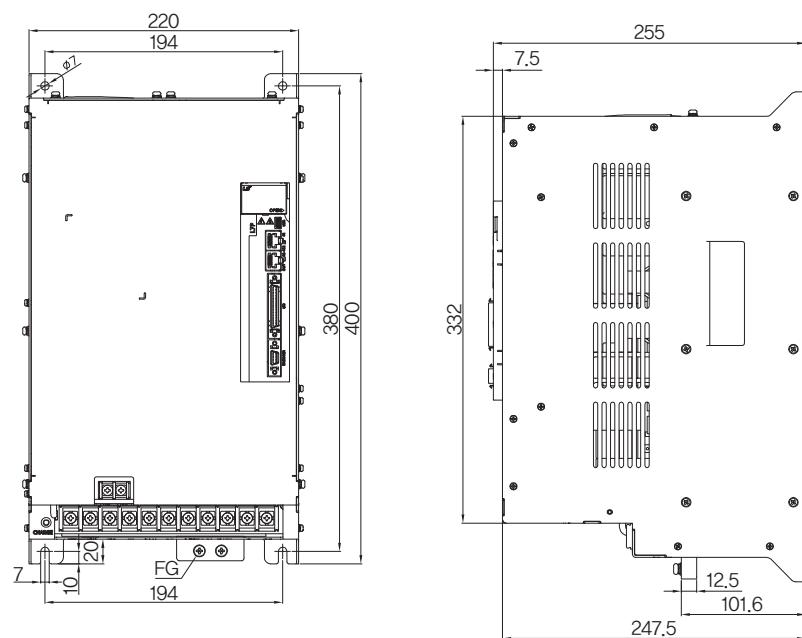


L7 SERIES SYSTEM

External Dimensions of L7PB Drive

■ L7PB150U [Weight : 15.5kg(Fan-Cooling included)]

* Unit [mm]



Contents

Servo Motor

S Series

Solid/Hollow Type Rotating Servo Motor

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- Product Feature 61
- External Dimensions 67



F Series

Flat Type Rotating Servo Motor

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- Product Feature 73
- External Dimensions 83



MDM Series

Direct-Drive Motor

- Servo Motor Designation 87
- Product Feature 88
- External Dimensions 93



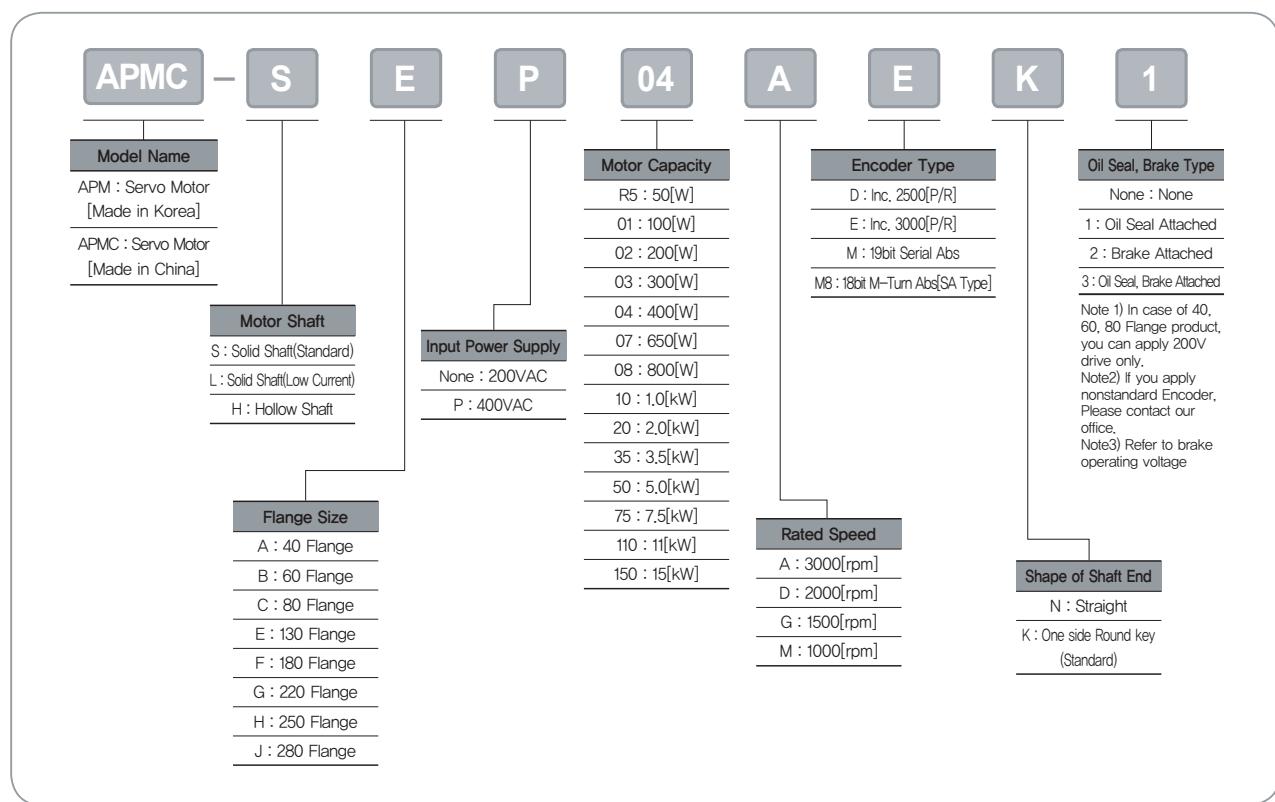
L7 SERIES SYSTEM

Solid/Hollow Type Rotating Servo Motor

I S Series



Servo Motor Designation



S Series Motor Characteristics (200V)

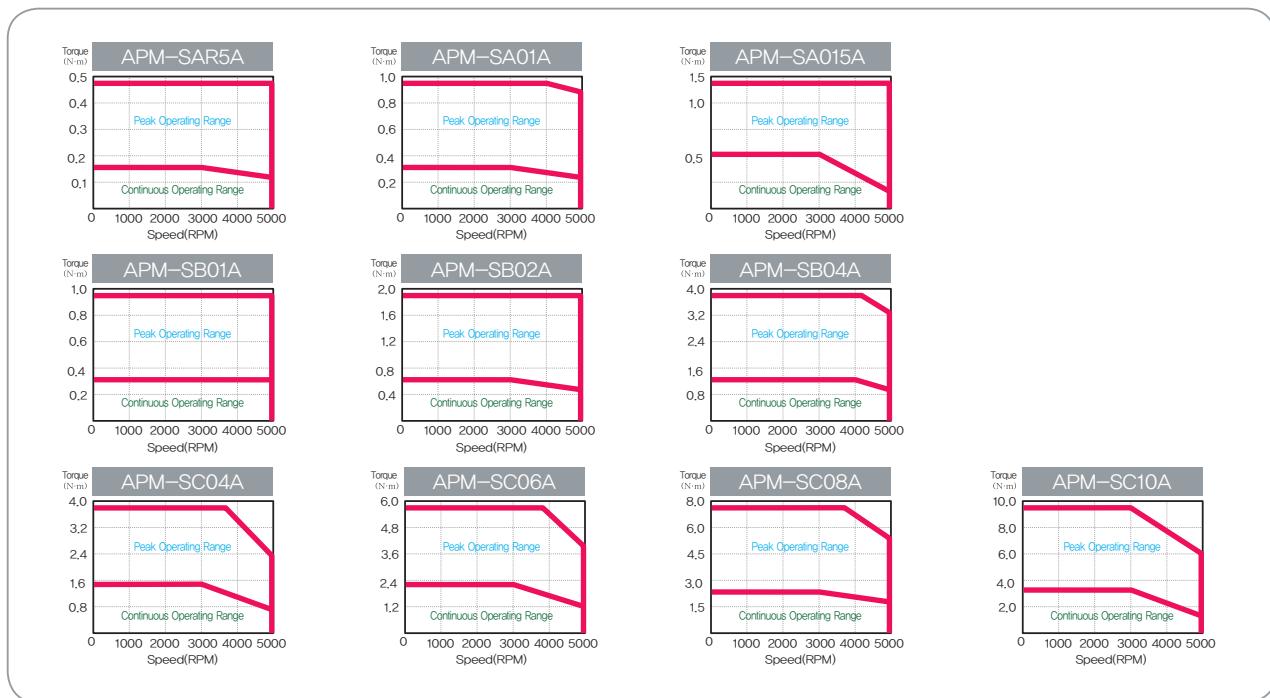
Motor Specifications [Rated 3000r/min]

| Servo Motor (APM-□□□□) | | SAR5A | SA01A | SA015A | SB01A | SB02A | SB04A | SC04A | SC06A | SC08A | SC10A | | | | |
|------------------------------|---|--|-------|---------------------------|-------|----------------------------------|-------|---|-------|---------|-------|--|--|--|--|
| Applicable Drive (L7□A□□) | | L7□A001 | | L7□A002 | | L7□A004 | | L7□A008 | | L7□A010 | | | | | |
| Flange Size(□) | | □40 | | | | □60 | | | | □80 | | | | | |
| Rated Output | [kW] | 0.05 | 0.1 | 0.15 | 0.1 | 0.2 | 0.4 | 0.4 | 0.6 | 0.8 | 1 | | | | |
| Rated Torque | [N · m] | 0.16 | 0.32 | 0.48 | 0.32 | 0.64 | 1.27 | 1.27 | 1.91 | 2.55 | 3.19 | | | | |
| | [kgf · cm] | 1.62 | 3.25 | 4.87 | 3.25 | 6.49 | 12.99 | 12.99 | 19.49 | 25.98 | 32.48 | | | | |
| Instantaneous Maximum Torque | [N · m] | 0.48 | 0.96 | 1.43 | 0.96 | 1.91 | 3.82 | 3.82 | 5.73 | 7.64 | 9.56 | | | | |
| | [kgf · cm] | 4.87 | 9.74 | 14.62 | 9.74 | 19.48 | 38.96 | 38.96 | 58.47 | 77.95 | 97.43 | | | | |
| Rated Current | [A] | 1.2 | 1.38 | 1.73 | 1.65 | 1.63 | 2.89 | 2.89 | 3.58 | 4.83 | 5.37 | | | | |
| Max. Current | [A] | 3.6 | 4.14 | 5.19 | 4.95 | 4.89 | 8.67 | 8.46 | 10.74 | 14.49 | 16.11 | | | | |
| Rated Speed | [r/min] | 3000 | | | | | | | | | | | | | |
| Max. Speed | [r/min] | 5000 | | | | | | | | | | | | | |
| Inertia | [kg · m ² × 10 ⁻⁴] | 0.02 | 0.05 | 0.06 | 0.11 | 0.18 | 0.32 | 0.67 | 1.09 | 1.51 | 1.93 | | | | |
| | [gf · cm × s ²] | 0.02 | 0.05 | 0.07 | 0.12 | 0.19 | 0.33 | 0.69 | 1.11 | 1.54 | 1.97 | | | | |
| Allowable Load Inertia Ratio | 30 times of motor inertia | | | 20 times of motor inertia | | | | 15 times of motor inertia | | | | | | | |
| Rated Power Rate | [kW/s] | 10.55 | 23.78 | 35.34 | 8.89 | 22.26 | 50.49 | 24.05 | 33.39 | 43.02 | 52.57 | | | | |
| Speed/Position Detector | Standard(Note1) | Quad. Type Incremental 2048[P/R] | | | | Quad. Type Incremental 3000[P/R] | | | | | | | | | |
| | Option | Serial Type 18[Bit] | | | | Serial Type 19[Bit] | | | | | | | | | |
| Specifications & Features | Structure | Fully closed · Self cooling IP55 Note1) | | | | | | Fully closed · Self cooling IP65 Note1) | | | | | | | |
| | Rated Time | Continuous | | | | | | | | | | | | | |
| | Ambient Temp | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | | | | | | | | |
| | Ambient Humidity | 20 ~ 80[%] (avoid dew-condensation) | | | | | | | | | | | | | |
| | Atmosphere | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | | | | | | | | | |
| | E/V | Elevation/vibration 49[m/s ²](5G) | | | | | | | | | | | | | |
| Weight | [kg] | 0.38 | 0.5 | 0.7 | 0.82 | 1.08 | 1.58 | 1.88 | 2.52 | 3.15 | 3.8 | | | | |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked

It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



L7S Series

L7N Series

L7P Series

S Series

F Series

MDM Series

PEGASUS Series

Options

L7 SERIES SYSTEM

S Series Motor Characteristics (200V)

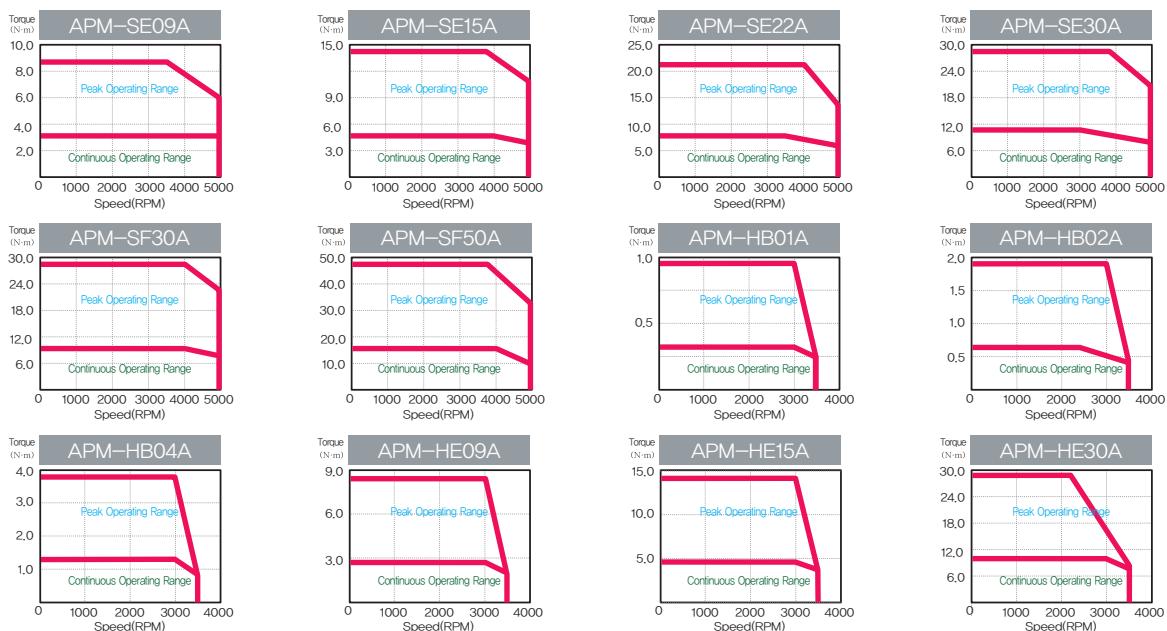
Motor Specifications [Rated 3000r/min]

| Servo Motor (APM-□□□□) | SE09A | SE15A | SE22A | SE30A | SF30A | SF50A | HB01A | HB02A | HB04A | HE09A | HE15A | HE30A | | | | | | |
|---|--|---|--------|---------|--------------------------|--------|---------|---|---------------------------|---------|---------|--------|--|--|--|--|--|--|
| Applicable Drive (L7□A□□□) | L7□A008 | L7□A020 | | L7□A035 | L7□A050 | | L7□A002 | L7□A004 | L7□A008 | L7□A020 | L7□A050 | | | | | | | |
| Flange Size(□) | □130 | | | | □180 | | | | □60 | | | | | | | | | |
| Rated Output [kW] | 0.9 | 1.5 | 2.2 | 3 | 3 | 5 | 0.1 | 0.2 | 0.4 | 0.9 | 1.5 | 3 | | | | | | |
| Rated Torque [N·m] | 2.86 | 4.77 | 7 | 9.55 | 9.55 | 15.91 | 0.32 | 0.64 | 1.27 | 2.86 | 4.77 | 9.55 | | | | | | |
| [kgf·cm] | 29.23 | 48.72 | 71.45 | 97.43 | 97.43 | 162.38 | 3.25 | 6.49 | 12.99 | 29.23 | 48.72 | 97.43 | | | | | | |
| Instantaneous Maximum Torque [N·m] | 8.59 | 14.32 | 21.01 | 28.64 | 28.64 | 47.74 | 0.96 | 1.91 | 3.82 | 8.59 | 14.32 | 28.64 | | | | | | |
| Maximum Torque [kgf·cm] | 87.69 | 146.15 | 214.35 | 292.29 | 292.29 | 487.15 | 9.74 | 19.48 | 38.96 | 87.69 | 146.15 | 292.29 | | | | | | |
| Rated Current [A] | 4.95 | 8.23 | 11.98 | 17.16 | 16.7 | 27.4 | 1.65 | 1.63 | 2.89 | 4.95 | 8.23 | 17.16 | | | | | | |
| Max. Current [A] | 14.85 | 24.69 | 35.94 | 51.48 | 50.1 | 82.2 | 4.95 | 4.89 | 8.67 | 14.85 | 24.69 | 51.48 | | | | | | |
| Rated Speed [r/min] | 3000 | | | | | | | | | | | | | | | | | |
| Max. Speed [r/min] | 5000 | | | | | | 3500 | | | | | | | | | | | |
| Inertia [$\text{kg} \cdot \text{m}^2 \times 10^{-4}$] | 6.66 | 12 | 17.34 | 22.68 | 30.74 | 52.13 | 0.27 | 0.33 | 0.46 | 19.56 | 22.27 | 31.81 | | | | | | |
| [$\text{gf} \cdot \text{cm} \times \text{s}^2$] | 6.8 | 12.24 | 17.69 | 23.14 | 31.37 | 53.19 | 0.27 | 0.34 | 0.47 | 19.96 | 22.72 | 32.46 | | | | | | |
| Allowable Load Inertia Ratio | 10 times of motor inertia | | | | 5 times of motor inertia | | | | 20 times of motor inertia | | | | | | | | | |
| Rated Power Rate [kW/s] | 12.32 | 18.99 | 28.28 | 40.20 | 29.66 | 48.58 | 3.34 | 11.98 | 34.47 | 4.10 | 10.01 | 22.03 | | | | | | |
| Speed/Position Detector | Standard(Note1) | Quad, Type Incremental 3000[P/R] | | | | | | Quad, Type Incremental 1024[P/R] | | | | | | | | | | |
| Option | Serial Type 19[Bit] | | | | | | | | | | | | | | | | | |
| Specifications & Features | Structure | Fully closed · Self cooling IP65 Note1) | | | | | | Fully closed · Self cooling IP55 Note1) | | | | | | | | | | |
| Rated Time | Continuous | | | | | | | | | | | | | | | | | |
| Ambient Temp | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | | | | | | | | | | | | |
| Ambient Humidity | 90[%]RH Below (avoid dew-condensation) | | | | | | | | | | | | | | | | | |
| Atmosphere | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust, | | | | | | | | | | | | | | | | | |
| E/V | Elevation/vibration 49[m/s ²](5G) | | | | | | | | | | | | | | | | | |
| Weight [kg] | 5.5 | 7.5 | 9.7 | 11.8 | 12.4 | 17.7 | 0.9 | 1.2 | 1.7 | 5.8 | 7.4 | | | | | | | |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked.

It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



S Series Motor Characteristics (200V)

■ Motor Specifications [Rated 2000r/min]

| Servo Motor (APM-□□□□) | | SC03D | SC05D | SC06D | SC07D | SE06D | SE11D | SE16D | SE22D |
|------------------------------|---|--|---------|-------|-------|---------------------------|---------|--------|--------|
| Applicable Drive (L7□A□□) | | L7□A004 | L7□A008 | | | L7□A010 | L7□A020 | | |
| Flange Size(□) | | □80 | | | | □130 | | | |
| Rated Output | [kW] | 0.3 | 0.45 | 0.55 | 0.65 | 0.6 | 1.1 | 1.6 | 2.2 |
| Rated Torque | [N · m] | 1.43 | 2.15 | 2.63 | 3.1 | 2.86 | 5.25 | 7.64 | 10.5 |
| | [kgf · cm] | 14.61 | 21.92 | 26.79 | 31.66 | 29.23 | 53.59 | 77.94 | 107.17 |
| Instantaneous Maximum Torque | [N · m] | 4.3 | 6.45 | 7.88 | 9.31 | 8.59 | 15.75 | 22.92 | 31.51 |
| | [kgf · cm] | 43.84 | 65.77 | 80.38 | 94.99 | 87.69 | 160.76 | 233.83 | 321.52 |
| Rated Current | [A] | 2.59 | 3.23 | 3.82 | 4.42 | 3.97 | 6.28 | 9.23 | 12.37 |
| Max. Current | [A] | 7.77 | 9.69 | 11.46 | 13.26 | 11.91 | 18.84 | 27.69 | 37.11 |
| Rated Speed | [r/min] | 2000 | | | | | | | |
| Max. Speed | [r/min] | 3000 | | | | | | | |
| Inertia | [kg · m ² × 10 ⁻⁴] | 0.67 | 1.09 | 1.51 | 1.93 | 6.66 | 12 | 17.34 | 22.68 |
| | [gf · cm × s ²] | 0.69 | 1.11 | 1.54 | 1.97 | 6.8 | 12.24 | 17.69 | 23.14 |
| Allowable Load Inertia Ratio | | 15 times of motor inertia | | | | 10 times of motor inertia | | | |
| Rated Power Rate | [kW/s] | 30.43 | 42.27 | 45.69 | 49.97 | 12.32 | 22.98 | 33.65 | 48.64 |
| Speed/Position Detector | Standard(Note1) | Quande, Type Incremental 3000[P/R] | | | | | | | |
| | Option | Serial Type 19[Bit] | | | | | | | |
| Specifications & Features | Structure | Fully closed · Self cooling IP65 Note1) | | | | | | | |
| | Rated Time | Continuous | | | | | | | |
| | Ambient Temp | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | | |
| | Ambient Humidity | 90[%]RH Below (avoid dew-condensation) | | | | | | | |
| | Atmosphere | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | | | |
| | E/V | Elevation/vibration 49[m/s ²](5G) | | | | | | | |
| Weight | [kg] | 1.9 | 2.5 | 3.2 | 3.9 | 5.5 | 7.5 | 9.7 | 11.8 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked

It can be satisfied protection grade when you use private cable only.

■ Speed-Torque Characteristics



L7 SERIES SYSTEM

S Series Motor Characteristics (200V)

Motor Specifications [Rated 2000r/min]

| Servo Motor (APM-□□□□) | | SF22D | LF35D | SF55D | SF75D | SG22D | LG35D | SG55D | SG75D | SG110D | | | | | | |
|------------------------------|---|--|---------|---------|---------|---------|---------------------|---------|---------|----------|--|--|--|--|--|--|
| Applicable Drive (L7□A□□) | | L7□A020 | L7□A035 | L7□A050 | L7□A075 | L7□A020 | L7□A035 | L7□A050 | L7□A075 | L7□A150 | | | | | | |
| Flange Size(□) | | □180 | | | | | □220 | | | | | | | | | |
| Rated Output | [kW] | 2,2 | 3,5 | 5,5 | 7,5 | 2,2 | 3,5 | 5,5 | 7,5 | 11 | | | | | | |
| Rated Torque | [N · m] | 10,5 | 16,71 | 26,26 | 35,81 | 10,5 | 16,71 | 26,26 | 35,81 | 52,5 | | | | | | |
| | [kgf · cm] | 107,17 | 170,5 | 267,93 | 365,36 | 107,2 | 170,52 | 267,9 | 365,4 | 535,9 | | | | | | |
| Instantaneous Maximum Torque | [N · m] | 31,51 | 50,13 | 78,77 | 89,51 | 31,51 | 50,13 | 78,77 | 89,51 | 157,55 | | | | | | |
| | [kgf · cm] | 321,52 | 511,51 | 803,8 | 913,41 | 321,52 | 511,51 | 803,8 | 913,4 | 1,607,60 | | | | | | |
| Rated Current | [A] | 13,5 | 15,85 | 30,25 | 34,6 | 12,3 | 16,05 | 30,25 | 35,49 | 51,39 | | | | | | |
| Max. Current | [A] | 40,5 | 47,55 | 90,75 | 86,5 | 36,9 | 48,15 | 90,75 | 88,73 | 154,17 | | | | | | |
| Rated Speed | [r/min] | 2000 | | | | | 2500 | | | | | | | | | |
| Max. Speed | [r/min] | 3000 | | | 2500 | 3000 | | | 2500 | | | | | | | |
| Inertia | [kg · m ² × 10 ⁻⁴] | 30,74 | 52,13 | 83,6 | 121,35 | 51,42 | 80,35 | 132,41 | 172,91 | 291,36 | | | | | | |
| | [gf · cm × s ²] | 31,35 | 53,16 | 85,31 | 123,74 | 52,47 | 81,99 | 135,11 | 176,44 | 297,31 | | | | | | |
| Allowable Load Inertia Ratio | | | | | | | | | | | | | | | | |
| Rated Power Rate | [kW/s] | 35,88 | 53,56 | 82,56 | 105,75 | 21,45 | 34,75 | 52,07 | 74,15 | 94,65 | | | | | | |
| Speed/Position Detector | Standard(Note1) | Quad. Type Incremental 3000[P/R] | | | | | Serial Type 19[Bit] | | | | | | | | | |
| | Option | | | | | | | | | | | | | | | |
| Specifications & Features | Structure | Fully closed · Self cooling IP65 Note1) | | | | | | | | | | | | | | |
| | Rated Time | Continuous | | | | | | | | | | | | | | |
| | Ambient Temp | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | | | | | | | | | |
| | Ambient Humidity | 90[%]RH Below (avoid dew-condensation) | | | | | | | | | | | | | | |
| | Atmosphere | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | | | | | | | | | | |
| | E/V | Elevation/vibration 49[m/s ²](5G) | | | | | | | | | | | | | | |
| Weight | [kg] | 12,4 | 17,7 | 26,3 | 35,6 | 17 | 22 | 30,8 | 37,5 | 66,2 | | | | | | |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked.
It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



S Series Motor Characteristics (200V)

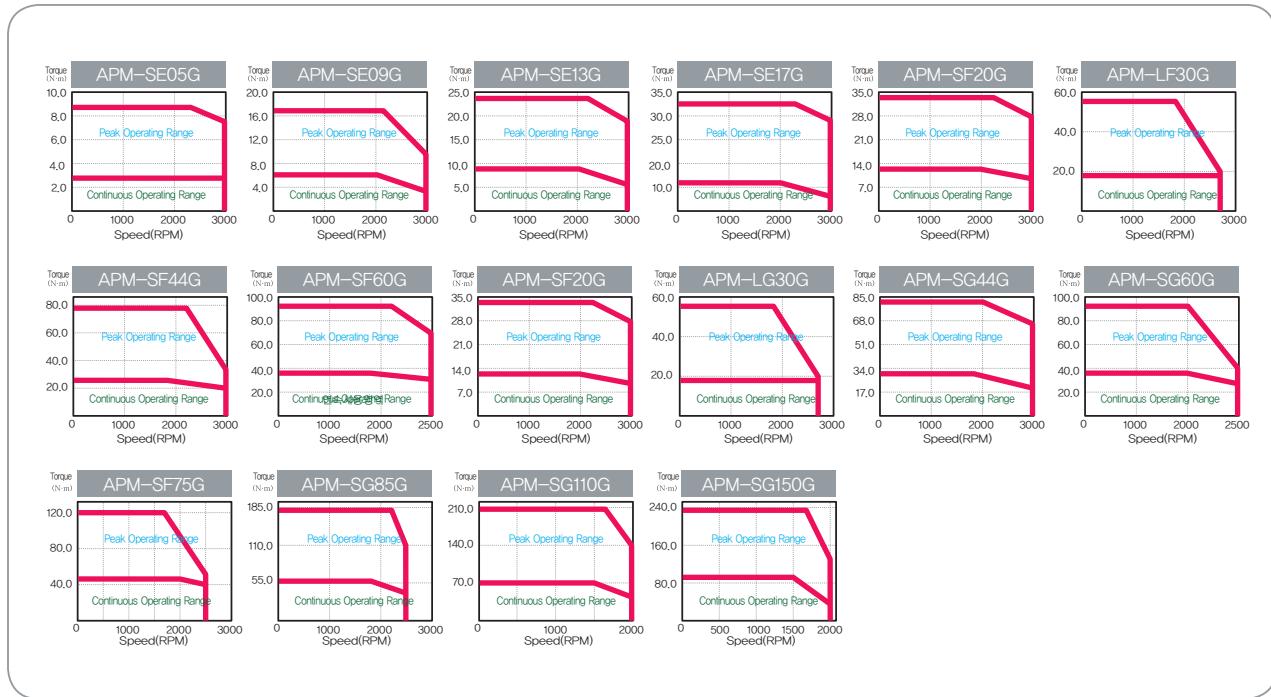
Motor Specifications [Rated 1500r/min]

| Servo Motor (APM-□□□□) | | SE05G | SE09G | SE13G | SE17G | SF20G | LF30G | SF44G | SF60G | SF75G | SG20G | LG30G | SG44G | SG60G | SG85G | SG110G | SG150G |
|------------------------------|---|--|---------|--------|--------|---------|---------|---------|--------------------------|----------|---------|---------|---------|---------|----------|----------|--------|
| Applicable Drive (L7□A□□) | | L7□A008 | L7□A010 | L7□A20 | | L7□A035 | L7□A050 | L7□A075 | L7□A150 | L7□A20 | L7□A035 | L7□A050 | L7□A075 | L7□A150 | L7□A150 | L7□A150 | |
| Flange Size(□) | | □130 | | | | | | | □180 | | | | | | | □220 | |
| Rated Output | [kW] | 0.45 | 0.85 | 1.3 | 1.7 | 1.8 | 2.9 | 4.4 | 6 | 7.5 | 1.8 | 2.9 | 4.4 | 6 | 8.5 | 11 | 15 |
| Rated Torque | [N · m] | 2.86 | 5.41 | 8.28 | 10.82 | 11.46 | 18.46 | 28.01 | 38.19 | 47.74 | 11.46 | 18.46 | 28.01 | 38.19 | 54.11 | 69.99 | 95.45 |
| | [kgf · cm] | 29.23 | 55.21 | 84.44 | 110.42 | 116.92 | 188.37 | 285.8 | 389.7 | 497.2 | 116.92 | 188.37 | 285.8 | 389.7 | 552.1 | 714.2 | 974 |
| Instantaneous Maximum Torque | [N · m] | 8.59 | 16.23 | 24.83 | 32.46 | 34.37 | 55.38 | 78.43 | 95.48 | 119.35 | 34.47 | 55.38 | 78.43 | 95.48 | 162.32 | 209.97 | 238.63 |
| | [kgf · cm] | 87.69 | 165.63 | 253.32 | 331.26 | 350.75 | 565.1 | 800.35 | 974.3 | 1,217.90 | 350.8 | 565.1 | 800.35 | 974.3 | 1,656.30 | 2,142.60 | 2,435 |
| Rated Current | [A] | 3.97 | 6.47 | 10 | 12.75 | 14.7 | 15.92 | 31.75 | 38 | 45.6 | 13.1 | 16.19 | 31.5 | 38 | 52.94 | 59.3 | 75.6 |
| Max. Current | [A] | 11.91 | 19.41 | 30 | 38.25 | 44.1 | 47.64 | 88.9 | 91.75 | 114 | 39.3 | 48.57 | 88.9 | 102 | 158.82 | 177.9 | 189 |
| Rated Speed | [r/min] | 1500 | | | | | | | | | | | | | | | |
| Max. Speed | [r/min] | 3000 | | | | 3000 | 2700 | 3000 | 2500 | 2500 | 3000 | 2700 | 3000 | 2500 | 2500 | 2000 | 2000 |
| Inertia | [kg · m ² × 10 ⁻⁴] | 6.66 | 12 | 17.34 | 22.68 | 30.74 | 52.13 | 83.6 | 121.35 | 143.82 | 51.42 | 80.35 | 132.41 | 172.91 | 291.36 | 291.36 | 424.57 |
| | [gf · cm × s ²] | 6.8 | 12.24 | 17.69 | 23.14 | 31.37 | 53.19 | 85.31 | 123.83 | 146.76 | 52.47 | 81.99 | 135.11 | 176.44 | 297.31 | 297.31 | 416.08 |
| Allowable Load Inertia Ratio | | 10 times of motor inertia | | | | | | | 5 times of motor inertia | | | | | | | | |
| Rated Power Rate | [kW/s] | 12.32 | 24.4 | 39.49 | 51.63 | 42.71 | 65.37 | 93.83 | 120.21 | 158.47 | 25.53 | 42.41 | 59.24 | 84.36 | 100.48 | 168.27 | 223.44 |
| Speed/Position Detector | Standard(Note1) | Quad. Type Incremental 3000[P/R] | | | | | | | | | | | | | | | |
| | Option | Serial Type 19[Bit] | | | | | | | | | | | | | | | |
| Specifications & Features | Structure | Fully closed · Self cooling IP65 Note1 | | | | | | | | | | | | | | | |
| | Rated Time | Continuous | | | | | | | | | | | | | | | |
| | Ambient Temp | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | | | | | | | | | | |
| | Ambient Humidity | 90[%]RH Below (avoid dew-condensation) | | | | | | | | | | | | | | | |
| | Atmosphere | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | | | | | | | | | | | |
| | E/V | Elevation/vibration 49[m/s ²](5G) | | | | | | | | | | | | | | | |
| Weight | [kg] | 5.5 | 7.5 | 9.7 | 11.8 | 12.4 | 17.7 | 26.3 | 35.6 | 39.4 | 17 | 22 | 30.8 | 37.52 | 66.2 | 66.3 | 92.2 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked

It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



L7 SERIES SYSTEM

S Series Motor Characteristics (200V)

Motor Specifications [Rated 1000r/min]

| Servo Motor (APM-□□□□) | | SE03M | SE06M | SE09M | SE12M | SF12M | SF20M | LF30M | SF44M | SG12M | SG20M | LG30M | SG44M | SG60M |
|------------------------------|---|--|---------|---------|---------|--------------------------|---------|--------|----------|---------|---------|---------|----------|----------|
| Applicable Drive (L7□A□□□) | | L7□A004 | L7□A008 | L7□A010 | L7□A020 | | L7□A035 | | L7□A050 | L7□A020 | L7□A035 | L7□A050 | L7□A075 | |
| Flange Size(□) | | □130 | | | | □180 | | | | □220 | | | | |
| Rated Output | [kW] | 0.3 | 0.6 | 0.9 | 1.2 | 1.2 | 2 | 3 | 4.4 | 1.2 | 2 | 3 | 4.4 | 6 |
| Rated Torque | [N · m] | 2.86 | 5.73 | 8.59 | 11.46 | 11.46 | 19.1 | 28.64 | 42.01 | 11.46 | 19.1 | 28.64 | 42.01 | 57.29 |
| | [kgf · cm] | 29.23 | 58.46 | 87.69 | 116.92 | 116.92 | 194.86 | 292.29 | 428.69 | 116.92 | 194.86 | 292.29 | 428.69 | 584.6 |
| Instantaneous Maximum Torque | [N · m] | 8.59 | 17.19 | 25.78 | 34.37 | 34.37 | 57.29 | 85.93 | 117.63 | 34.37 | 57.29 | 85.93 | 117.63 | 171.87 |
| | [kgf · cm] | 87.69 | 175.3 | 263.06 | 350.75 | 350.75 | 584.58 | 876.88 | 1,200.26 | 350.75 | 584.58 | 876.88 | 1,200.26 | 1,753.80 |
| Rated Current | [A] | 2.51 | 4.15 | 5.78 | 7.63 | 8.4 | 14.4 | 15.6 | 31.24 | 8.87 | 15.02 | 16.42 | 31.83 | 38 |
| Max. Current | [A] | 7.53 | 12.45 | 17.34 | 22.89 | 25.2 | 43.2 | 46.8 | 87.47 | 26.61 | 45.06 | 49.26 | 89.12 | 98.3 |
| Rated Speed | [r/min] | 1000 | | | | | | | | | | | | |
| Max. Speed | [r/min] | 2000 | | | | | 1700 | 2000 | | | | | 1700 | 2000 |
| Inertia | [kg · m ² × 10 ⁻⁴] | 6.66 | 12 | 17.34 | 22.68 | 30.74 | 52.13 | 83.6 | 121.35 | 51.42 | 80.35 | 132.41 | 172.91 | 291.36 |
| | [gf · cm × s ²] | 6.8 | 12.24 | 17.69 | 23.14 | 31.37 | 53.19 | 85.31 | 123.83 | 52.47 | 81.99 | 135.11 | 176.44 | 297.31 |
| Allowable Load Inertia Ratio | 10 times of motor inertia | | | | | 5 times of motor inertia | | | | | | | | |
| Rated Power Rate | [kW/s] | 12.32 | 27.35 | 42.59 | 57.89 | 42.71 | 69.95 | 98.15 | 145.45 | 25.53 | 45.39 | 61.97 | 102.08 | 112.65 |
| Speed/Position Detector | Standard(Note1) | Quad, Type Incremental 3000[P/R] | | | | | | | | | | | | |
| | Option | Serial Type 19[Bit] | | | | | | | | | | | | |
| Specifications & Features | Structure | Fully closed · Self cooling IP65 Note1 | | | | | | | | | | | | |
| | Rated Time | Continuous | | | | | | | | | | | | |
| | Ambient Temp | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | | | | | | | |
| | Ambient Humidity | 90[%]RH Below (avoid dew-condensation) | | | | | | | | | | | | |
| | Atmosphere | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | | | | | | | | |
| E/V | Elevation/vibration 49[m/s ²](5G) | | | | | | | | | | | | | |
| Weight | [kg] | 5.5 | 7.5 | 9.7 | 11.8 | 12.4 | 17.7 | 26.3 | 35.6 | 17 | 22 | 30.8 | 37.5 | 66.2 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked.
It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



External Dimensions of S Series Motor

SA Series

Plug Specifications

[Power]

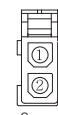


Spec. : 172167-1
(Made by AMP)

| Pin No. | Color | Signal |
|---------|-------|--------|
| 1 | Red | U |
| 2 | White | V |
| 3 | Black | W |
| 4 | Green | Ground |

(Power Connector Pin Table)

[Brake]

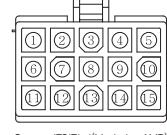


Spec. : 172165-1
(Made by AMP)

| Pin No. | Signal |
|---------|--------|
| 1 | BK+ |
| 2 | BK- |

(Brake Connector Pin Table)

[Encoder]



Spec. : 172171-1(Made by AMP)

| Pin No. | Signal | Pin No. | Signal |
|---------|-----------|---------|-----------|
| 1 | A | 9 | V |
| 2 | \bar{A} | 10 | \bar{V} |
| 3 | B | 11 | W |
| 4 | \bar{B} | 12 | \bar{W} |
| 5 | Z | 13 | +5V |
| 6 | \bar{Z} | 14 | 0V |
| 7 | U | 15 | SHIELD |
| 8 | \bar{U} | | |

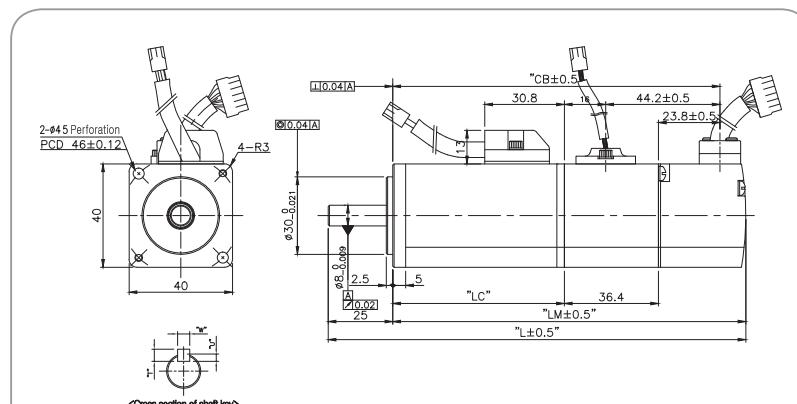
(Parallel Encoder Connector Pin Table)

Note1) Use DC[24V] for brake input power supply.

Note2) The () is for brake-attached type.

Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

Note4) Refer to page 24 for serial encoder pin table.



| Model | External Dimensions | | | | Key | | | Weight(kg) |
|--------|---------------------|--------------|------------|-------------|-----|---|-----|------------|
| | L | LM | LC | CB | T | W | U | |
| SAR3A | 101.3(137.6) | 76.3(112.6) | 42.5(42.4) | 66.3(102.3) | 5 | 5 | 1.8 | 0.32(0.67) |
| SAR5A | 108.3(144.6) | 83.3(119.6) | 49.5(49.4) | 73.3(109.3) | | | | 0.38(0.73) |
| SA01A | 125.3(161.6) | 100.3(136.6) | 66.5(66.4) | 90.3(126.6) | | | | 0.5(0.85) |
| SA015A | 145.3 | 120.3 | 86.5 | 110.3 | | | | 0.7 |

SB Series

Plug Specifications

[Power]

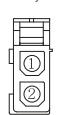


Spec. : 172167-1
(Made by AMP)

| Pin No. | Color | Signal |
|---------|-------|--------|
| 1 | Red | U |
| 2 | White | V |
| 3 | Black | W |
| 4 | Green | Ground |

(Power Connector Pin Table)

[Brake]



Spec. : 172165-1
(Made by AMP)

| Pin No. | Signal |
|---------|--------|
| 1 | BK+ |
| 2 | BK- |

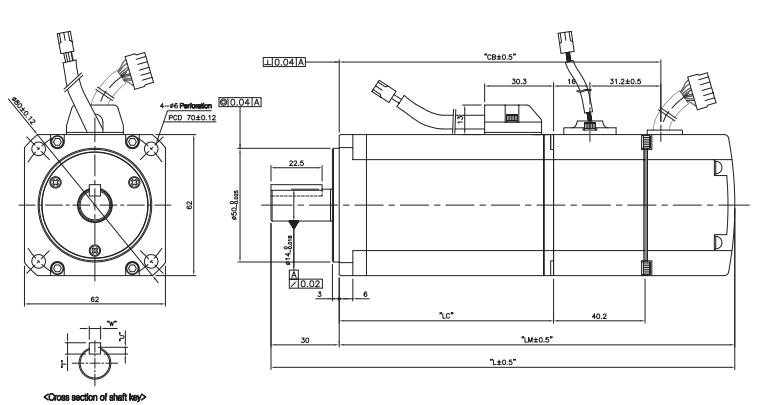
(Brake Connector Pin Table)

Note1) Use DC[24V] for brake input power supply.

Note2) The () is for brake-attached type.

Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

Note4) Refer to page 24 for serial encoder pin table.



| Model | External Dimensions | | | | Key | | | Weight(kg) |
|-------|---------------------|----------|------------|--------------|-----|---|---|------------|
| | L | LM | LC | CB | T | W | U | |
| SB01A | 122(162) | 92(132) | 52.5(52.3) | 59.5(99.5) | 5 | 5 | 3 | 0.82(1.4) |
| SB02A | 136(176) | 106(146) | 66.5(66.3) | 73.5(113.5) | | | | 1.08(1.66) |
| SB04A | 164(204) | 134(174) | 94.5(94.3) | 101.5(141.5) | | | | 1.58(2.16) |

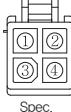
L7 SERIES SYSTEM

External Dimensions of S Series Motor

SC Series

Plug Specifications

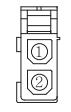
[Power]



| Pin No. | Color | Signal |
|---------|-------|--------|
| 1 | Red | U |
| 2 | White | V |
| 3 | Black | W |
| 4 | Green | Ground |

(Power Connector Pin Table)

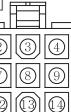
[Brake]



| Pin No. | Signal |
|---------|--------|
| 1 | BK+ |
| 2 | BK- |

(Brake Connector Pin Table)

[Encoder]



| Pin No. | Signal | Pin No. | Signal |
|---------|--------|---------|--------|
| 1 | A | 9 | V |
| 2 | Ā | 10 | V̄ |
| 3 | B | 11 | W |
| 4 | B̄ | 12 | W̄ |
| 5 | Z | 13 | +5V |
| 6 | Z̄ | 14 | 0V |
| 7 | U | 15 | SHIELD |
| 8 | Ū | | |

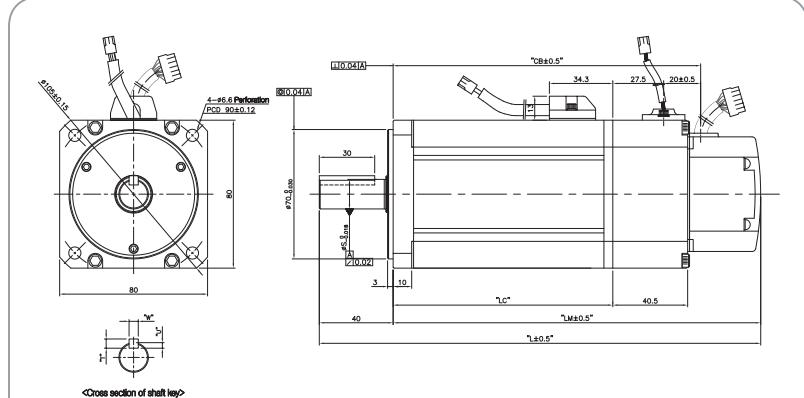
(Spec. : 172171-1(Made by AMP)) (Parallel Encoder Connector Pin Table)

Note1) Use DC[24V] for brake input power supply.

Note2) The () is for brake-attached type.

Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

Note4) Refer to page 24 for serial encoder pin table.

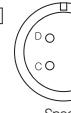


| Model | External Dimensions | | | | | Key | Weight(kg) |
|--------------|---------------------|--------------|------------|------------|----|-----|------------|
| | L | LM | LC | CB | S | | |
| SC04A, SC03D | 158.5(199.8) | 118.5(158.8) | 79(78.8) | 86(126.3) | 14 | | 1.88(2.92) |
| SC06A, SC05D | 178.5(218.8) | 138.5(178.8) | 99(98.8) | 106(146.3) | 16 | 5 | 2.52(3.56) |
| SC08A, SC06D | 198.5(238.8) | 158.5(198.8) | 119(118.8) | 126(166.3) | 16 | | 3.15(4.22) |
| SC10A, SC07D | 218.5(258.8) | 178.5(218.8) | 139(138.8) | 146(186.3) | 16 | 5 | 3.80(4.94) |

SE Series

Plug Specifications

[Power]



| Pin No. | Signal |
|---------|--------|
| A | U |
| B | V |
| C | W |
| D | Ground |

(Spec. : MS3102A20-4P (Standard))

Pin No. Signal Pin No. Signal

| | | | |
|---|---|---|--------|
| A | U | D | Ground |
| B | V | E | BK+ |
| C | W | F | BK- |

(Spec. : MS3102A20-15P (Brake-attached type))

Pin No. Signal Pin No. Signal

| | | | |
|---|----|---|--------|
| A | A | M | V |
| B | Ā | N | V̄ |
| C | B | P | W |
| D | B̄ | R | W̄ |
| E | Z | H | +5V |
| F | Z̄ | G | 0V |
| K | U | J | SHIELD |
| L | Ū | | |

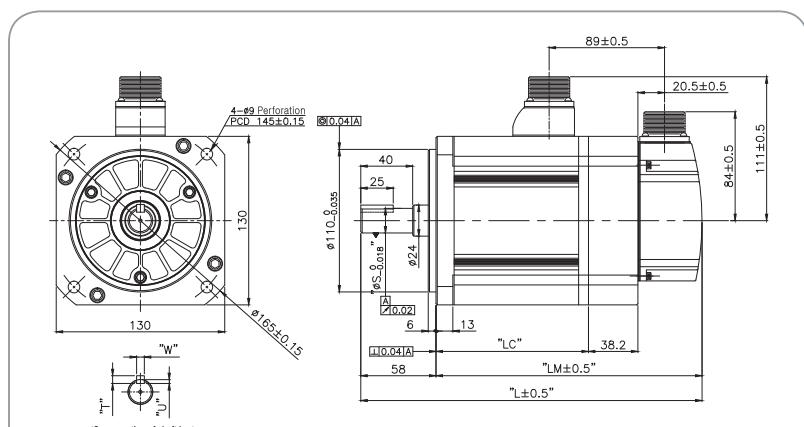
(Spec. : MS3102A20-29P (Parallel Encoder Connector Pin Table))

Note1) Use DC[24V] for brake input power supply.

Note2) The () is for brake-attached type.

Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

Note4) Refer to page 24 for serial encoder pin table.



| Model | External Dimensions | | | | | Key | Weight(kg) |
|----------------------------|---------------------|--------------|--------------|----|---|-----|--------------|
| | L | LM | LC | S | T | | |
| SE09A, SE06D, SE05G, SE03M | 201.3(239.3) | 143.3(181.3) | 93.8(93.6) | 19 | 5 | 5 | 5.5(7.04) |
| SE15A, SE11D, SE09G, SE06M | 225.3(263.3) | 167.3(205.3) | 117.8(117.6) | | | | 7.54(9.08) |
| SE22A, SE16D, SE13G, SE09M | 249.3(287.3) | 191.3(229.3) | 141.8(141.6) | 22 | 6 | 6 | 9.68(11.22) |
| SE30A, SE22D, SE17G, SE12M | 273.3(311.3) | 215.3(253.3) | 165.8(165.6) | | | | 11.78(13.32) |

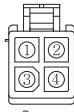
L7 SERIES SYSTEM

External Dimensions of S Series Motor

HB Series [Hollow Shaft type]

Plug Specifications |

[Power]

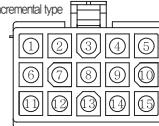


Spec. : 172167-1
(Made by AMP)

| Pin No. | Color | Signal |
|---------|-------|--------|
| 1 | Red | U |
| 2 | White | V |
| 3 | Black | W |
| 4 | Green | Ground |

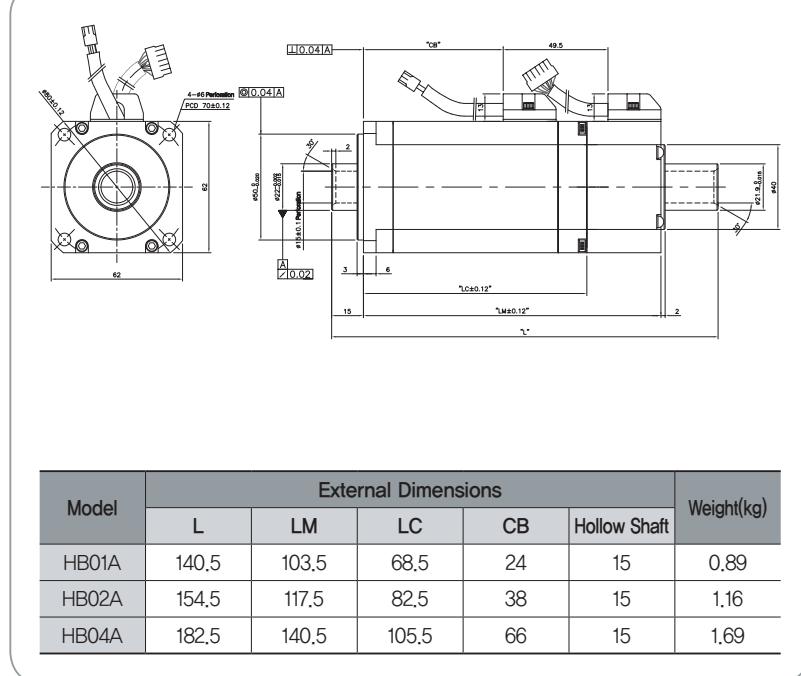
(Power Connector Pin Table)

[Encoder]



Spec. : 172171-1(Made by AMP) (Parallel Encoder Connector Pin Table)

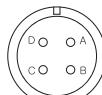
| Pin No. | Signal | Pin No. | Signal |
|---------|-----------|---------|-----------|
| 1 | A | 9 | V |
| 2 | \bar{A} | 10 | \bar{V} |
| 3 | B | 11 | W |
| 4 | \bar{B} | 12 | \bar{W} |
| 5 | Z | 13 | +5V |
| 6 | \bar{Z} | 14 | 0V |
| 7 | U | 15 | SHIELD |
| 8 | \bar{U} | | |



HE Series [Hollow Shaft type]

Plug Specifications |

[Power]

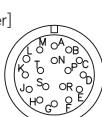


Spec. : MS3102A20-4P
(Standard)

| Pin No. | Signal |
|---------|--------|
| A | U |
| B | V |
| C | W |
| D | Ground |

(Power Connector Pin Table)

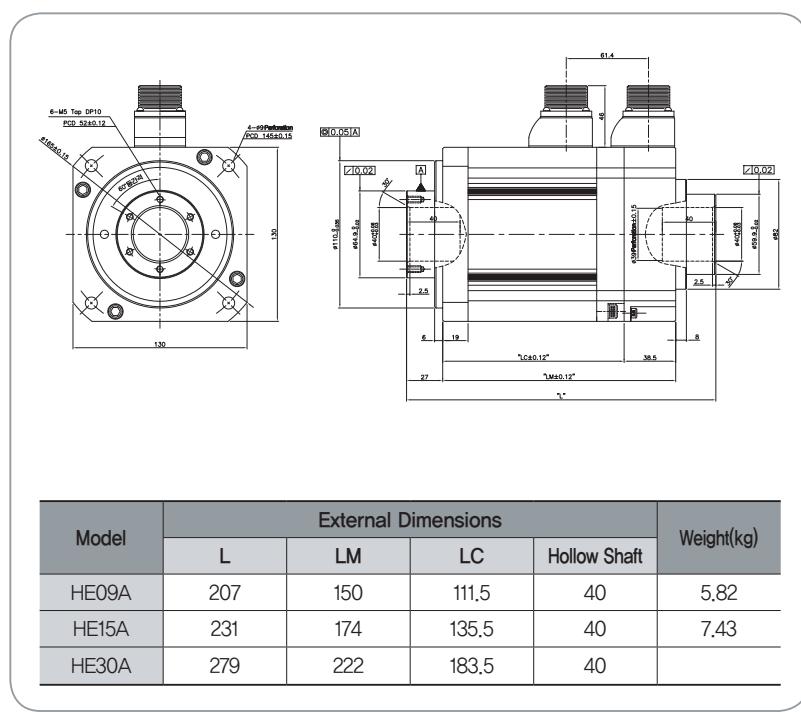
[Encoder]



Spec. : MS3102A20-29P

| Pin No. | Signal | Pin No. | Signal |
|---------|-----------|---------|-----------|
| A | A | M | V |
| B | \bar{A} | N | \bar{V} |
| C | B | P | W |
| D | \bar{B} | R | \bar{W} |
| E | Z | H | +5V |
| F | \bar{Z} | G | 0V |
| K | U | J | SHIELD |
| L | \bar{U} | | |

(Parallel Encoder Connector Pin Table)



Brake and Heat Sink Specification

Electric Brake Specifications

| Applicable Motor Series | APM-SA,FAL | APM-SB,FB,FBL | APM-SC, FC,FCL | APM-SE,SEP,FE,FEP | APM-SF,SFP,FF,FFF | APM-SG,SGP,FG,FGP |
|--------------------------------|--------------|---------------|----------------|-------------------|-------------------|-------------------|
| Purpose | Maintenance | | | | | |
| Input voltage [V] | DC 24V | DC 24V | DC 24V | DC 24V | DC 24V | DC 90V |
| Static friction torque [N · m] | 0.32 | 1.47 | 3.23 | 10.4 | 40 | 74 |
| Capacity [W] | 6 | 6.5 | 9 | 19.4 | 25 | 32 |
| Coil resistance [Ω] | 96 | 89 | 64 | 29.6 | 23 | 327 |
| Rated current [A] | 0.25 | 0.27 | 0.38 | 0.81 | 1.04 | 0.28 |
| Braking mechanism | Spring brake | | | | | |
| Insulation grade | Grade F | | | | | |

Note1) For the Electronic Brake that is attached to our Servo Motor, the same specific–ations are to be applied as per the series.

Note2) Do not use it for braking purpose because the electronic brake is only for maintaining the stopped condition.

Note3) The characteristics of electronic brake is measured at 20°C

Note4) Please make sure to always check the voltage specification on the motor because indicated brake specifications are subject to change.

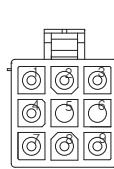
Heat Sink Specifications

| Type | Dimensions(mm) | Materials |
|------|----------------|-----------|
| AP04 | 250x250x6 | Aluminum |
| AP06 | 250x250x6 | |
| AP08 | 250x250x12 | |
| AP13 | 350x350x20 | |
| AP18 | 550x550x30 | |
| AP22 | 650x650x35 | |

NOTE 1) The data on the product features is measured when those heat sinks are applied.

S Series Encoder Pin Map

SA, SB, SC Series



Plug Specification :
172169-1
(AMP)

| Single Turn (N) | | Multi Turn (M) | |
|-----------------|--------|----------------|--------|
| Pin No. | Signal | Pin No. | Signal |
| 1 | MA | 1 | MA |
| 2 | MA | 2 | MA |
| 3 | SLO | 3 | SLO |
| 4 | SLO | 4 | SLO |
| 5 | — | 5 | VOD_B |
| 6 | — | 6 | GND_B |
| 7 | +5V | 7 | +5V |
| 8 | 0V | 8 | 0V |
| 9 | SHIELD | 9 | SHIELD |

(Serial Encoder Connector Pin Table)

SE, SF, SG Series



17 Pole Plug
(MS3102A20-29P)

| Single Turn (N) | | Multi Turn (M) | |
|--------------------------------------|--------|----------------|--------|
| Pin No. | Signal | Pin No. | Signal |
| A | MA | M | — |
| B | MA | N | — |
| C | SLO | P | — |
| D | SLO | R | — |
| E | — | H | +5V |
| F | — | G | 0V |
| K | — | J | MA |
| L | — | — | — |
| (Serial Encoder Connector Pin Table) | | | |

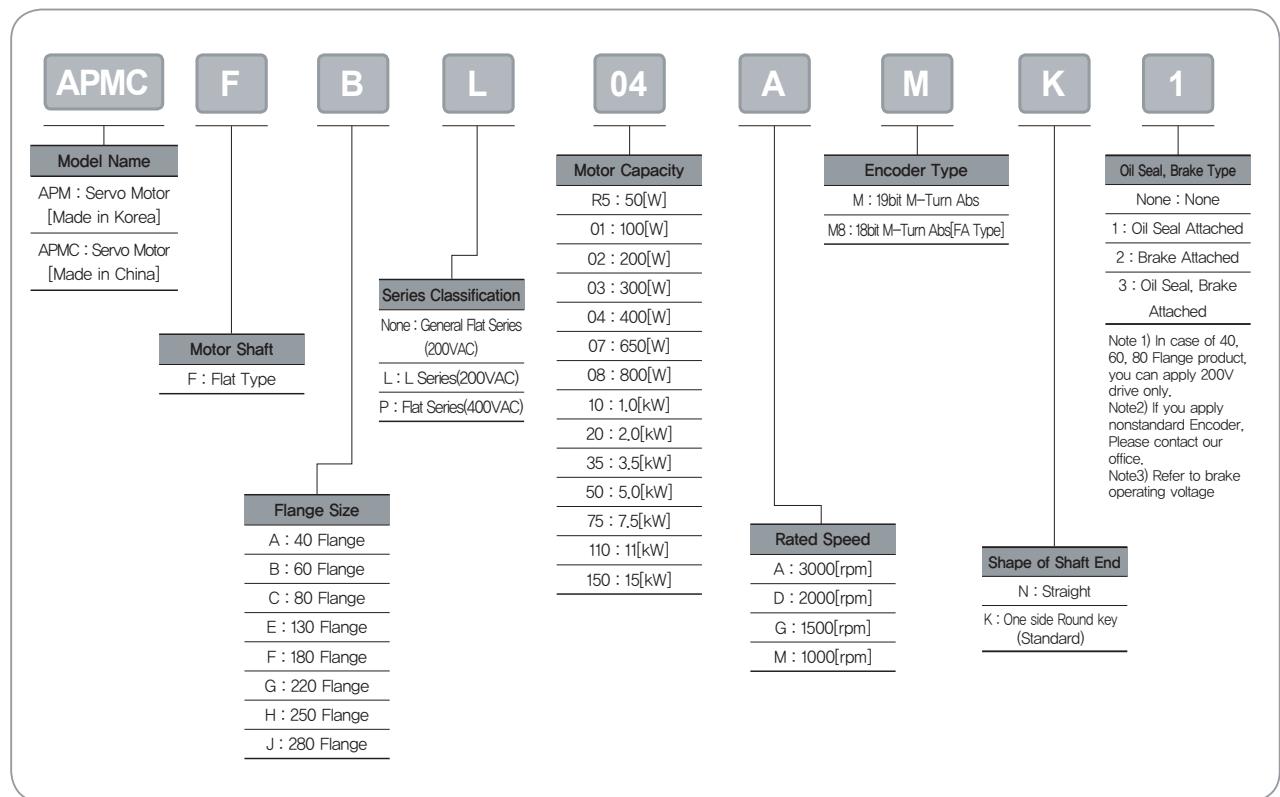
L7 SERIES SYSTEM

Flat Type Servo Motor

IF Series



■ Servo Motor Designation



F Series Motor Characteristics (200V)

Motor Specifications [Rated 3000r/min, 2000r/min]

| Servo Motor (APM-□□□□) | FALR5A | FAL01A | FAL015A | FBL01A | FBL02A | FBL04A | FCL04A | FCL06A | FCL08A | FCL10A | FCL03D | FCL05D | FCL06D | FCL07D |
|------------------------------|---|---|---------|---------------------------|---------|---------|---------|---------|---------|---------|---------------------------|--|---------|---------|
| Applicable Drive | L7□A001 | L7□A002 | L7□A001 | L7□A002 | L7□A004 | L7□A004 | L7□A004 | L7□A008 | L7□A010 | L7□A004 | L7□A008 | L7□A008 | L7□A008 | L7□A008 |
| Flange Size(□) | □40 | | | □60 | | | | | | | □80 | | | |
| Rated Output | [kW] | 0.05 | 0.1 | 0.15 | 0.1 | 0.2 | 0.4 | 0.4 | 0.6 | 0.75 | 1 | 0.3 | 0.45 | 0.55 |
| Rated Torque | [N · m] | 0.16 | 0.32 | 0.48 | 0.32 | 0.64 | 1.27 | 1.27 | 1.91 | 2.39 | 3.18 | 1.43 | 2.15 | 2.63 |
| | [kgf · cm] | 1.62 | 3.25 | 4.87 | 3.25 | 6.49 | 12.99 | 12.99 | 19.49 | 24.36 | 32.48 | 14.62 | 21.92 | 26.8 |
| Instantaneous Maximum Torque | [N · m] | 0.48 | 0.96 | 1.43 | 0.96 | 1.91 | 3.82 | 3.82 | 5.73 | 7.16 | 9.55 | 4.3 | 6.45 | 7.88 |
| | [kgf · cm] | 4.87 | 9.74 | 14.62 | 9.74 | 19.48 | 38.96 | 38.98 | 58.47 | 73.08 | 97.44 | 43.85 | 65.77 | 80.39 |
| Rated Current | [A] | 0.95 | 1.25 | 1.76 | 0.95 | 1.45 | 2.6 | 2.58 | 3.81 | 5.02 | 5.83 | 2.5 | 3.05 | 3.83 |
| Max. Current | [A] | 2.85 | 3.75 | 5.28 | 2.85 | 4.35 | 7.8 | 7.75 | 11.42 | 15.07 | 17.5 | 7.51 | 9.16 | 9.18 |
| Rated Speed | [r/min] | | | | | | 3000 | | | | | | 2000 | |
| Max. Speed | [r/min] | | | | | | 5000 | | | | | | 3000 | |
| Inertia | [kg · m ² × 10 ⁻⁴] | 0.023 | 0.042 | 0.063 | 0.091 | 0.147 | 0.248 | 0.53 | 0.897 | 1.264 | 1.632 | 0.53 | 0.897 | 1.264 |
| | [gf · cm × s ²] | 0.024 | 0.043 | 0.065 | 0.093 | 0.15 | 0.253 | 0.541 | 0.915 | 1.29 | 1.665 | 0.541 | 0.915 | 1.29 |
| Allowable Load Inertia Ratio | 30 times of motor inertia | | | 20 times of motor inertia | | | | | | | 15 times of motor inertia | | | |
| Rated Power Rate | [kW/s] | 10.55 | 23.78 | 35.34 | 11.09 | 27.6 | 27.57 | 30.6 | 40.66 | 45.09 | 62.08 | 38.73 | 51.47 | 54.56 |
| Speed/Position Detector | Standard(Note1) | Serial Multi-Turn Built-in Type (18bit) | | | | | | | | | | Serial Multi-Turn Built-in Type (19bit) | | |
| Option | | | | | | | | X | | | | | | |
| Structure | | | | | | | | | | | | Fully closed · Self cooling IP67 Note1 | | |
| Rated Time | | | | | | | | | | | | Continuous | | |
| Ambient Temp | | | | | | | | | | | | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | |
| Ambient Humidity | | | | | | | | | | | | 90[%]RH Below (avoid dew-condensation) | | |
| Atmosphere | | | | | | | | | | | | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | |
| E/V | | | | | | | | | | | | Elevation/vibration 49[m/s ²](5G) | | |
| Weight | [kg] | 0.31 | 0.45 | 0.61 | 0.56 | 0.74 | 1.06 | 1.52 | 2.14 | 2.68 | 3.3 | 1.26 | 2.12 | 2.66 |
| | | | | | | | | | | | | | | 2.78 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked
It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



L7 SERIES SYSTEM

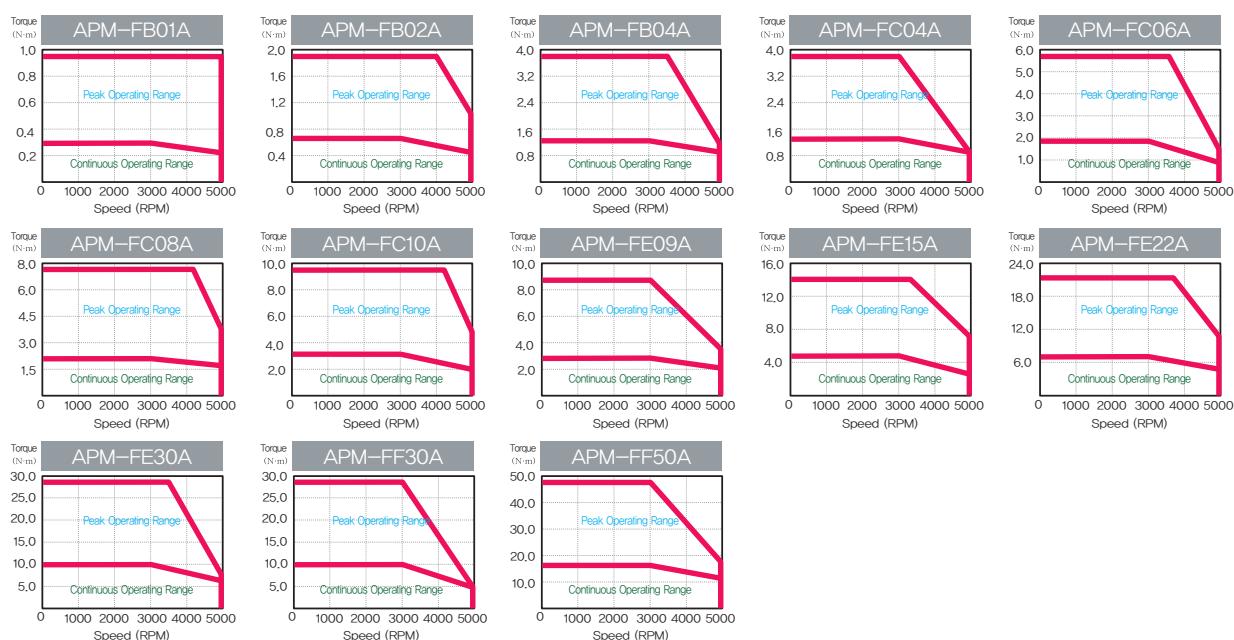
F Series Motor Characteristics (200V)

Motor Specifications [Rated 3000r/min]

| Servo Motor (APM-□□□□) | FB01A | FB02A | FB04A | FC04A | FC06A | FC08A | FC10A | FE09A | FE15A | FE22A | FE30A | FF30A | FF50A |
|---|---------------------------|---------|---------|---------------------------|---------|---------|---------------------------|--|---------|---------|--------------------------|---------|---------|
| Applicable Drive | L7□A001 | L7□A002 | L7□A004 | L7□A004 | L7□A008 | L7□A010 | L7□A010 | L7□A020 | L7□A035 | L7□A035 | L7□A050 | L7□A050 | L7□A050 |
| Flange Size(□) | □60 | | | □80 | | | □130 | | | | □180 | | |
| Rated Output [kW] | 0.1 | 0.2 | 0.4 | 0.4 | 0.6 | 0.75 | 1 | 0.9 | 1.5 | 2.2 | 3 | 3 | 5 |
| Rated Torque [N · m] | 0.32 | 0.64 | 1.27 | 1.27 | 1.91 | 2.39 | 3.18 | 2.86 | 4.77 | 7 | 9.55 | 9.55 | 15.91 |
| [kgf · cm] | 3.25 | 6.5 | 12.99 | 13 | 19.5 | 24.36 | 32.5 | 29.2 | 48.7 | 71.4 | 97.4 | 97.4 | 162.3 |
| Instantaneous Maximum Torque [N · m] | 0.96 | 1.91 | 3.82 | 3.82 | 5.73 | 7.16 | 9.55 | 8.59 | 14.32 | 21.01 | 28.65 | 28.65 | 47.74 |
| [kgf · cm] | 9.74 | 19.49 | 38.98 | 38.98 | 58.47 | 73.08 | 97.44 | 87.7 | 146.1 | 214.3 | 292.2 | 292.3 | 487 |
| Rated Current [A] | 0.95 | 1.45 | 2.6 | 2.58 | 3.81 | 5.02 | 6.7 | 6.45 | 9.15 | 13.24 | 16.09 | 15.26 | 26.47 |
| Max. Current [A] | 2.86 | 4.35 | 7.79 | 7.75 | 11.42 | 15.07 | 20.09 | 19.35 | 27.45 | 39.72 | 48.27 | 45.78 | 79.41 |
| Rated Speed [r/min] | | | | | | | | 3000 | | | | | |
| Max. Speed [r/min] | | | | | | | | 5000 | | | | | |
| Inertia [kg · m ² × 10 ⁻⁴] | 0.09 | 0.15 | 0.25 | 0.5 | 0.88 | 1.25 | 1.62 | 5.66 | 10.18 | 14.62 | 19.04 | 27.96 | 46.56 |
| [gf · cm × s ²] | 0.09 | 0.15 | 0.25 | 0.51 | 0.89 | 1.27 | 1.65 | 5.77 | 10.39 | 14.92 | 19.43 | 28.53 | 47.51 |
| Allowable Load Inertia Ratio | 20 times of motor inertia | | | 15 times of motor inertia | | | 10 times of motor inertia | | | | 5 times of motor inertia | | |
| Rated Power Rate [kW/s] | 11.38 | 27.95 | 65.9 | 32.62 | 41.69 | 45.78 | 62.74 | 14.47 | 22.38 | 33.59 | 47.85 | 32.59 | 54.33 |
| Speed/Position Detector | Standard(Note1) | | | | | | | Serial Type 19[bit] | | | | | |
| Option | | | | | | | | X | | | | | |
| Specifications & Features | Structure | | | | | | | Fully closed · Self cooling IP65 Note1 | | | | | |
| Rated Time | | | | | | | | Continuous | | | | | |
| Ambient Temp | | | | | | | | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | |
| Ambient Humidity | | | | | | | | 90[%]RH Below (avoid dew-condensation) | | | | | |
| Atmosphere | | | | | | | | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust, | | | | | |
| E/V | | | | | | | | Elevation/vibration 49[m/s ²](5G) | | | | | |
| Weight [kg] | 0.7 | 0.9 | 1.3 | 1.6 | 2.2 | 2.7 | 3.8 | 5 | 6.7 | 8.5 | 10.1 | 12.5 | 17.4 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked
It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



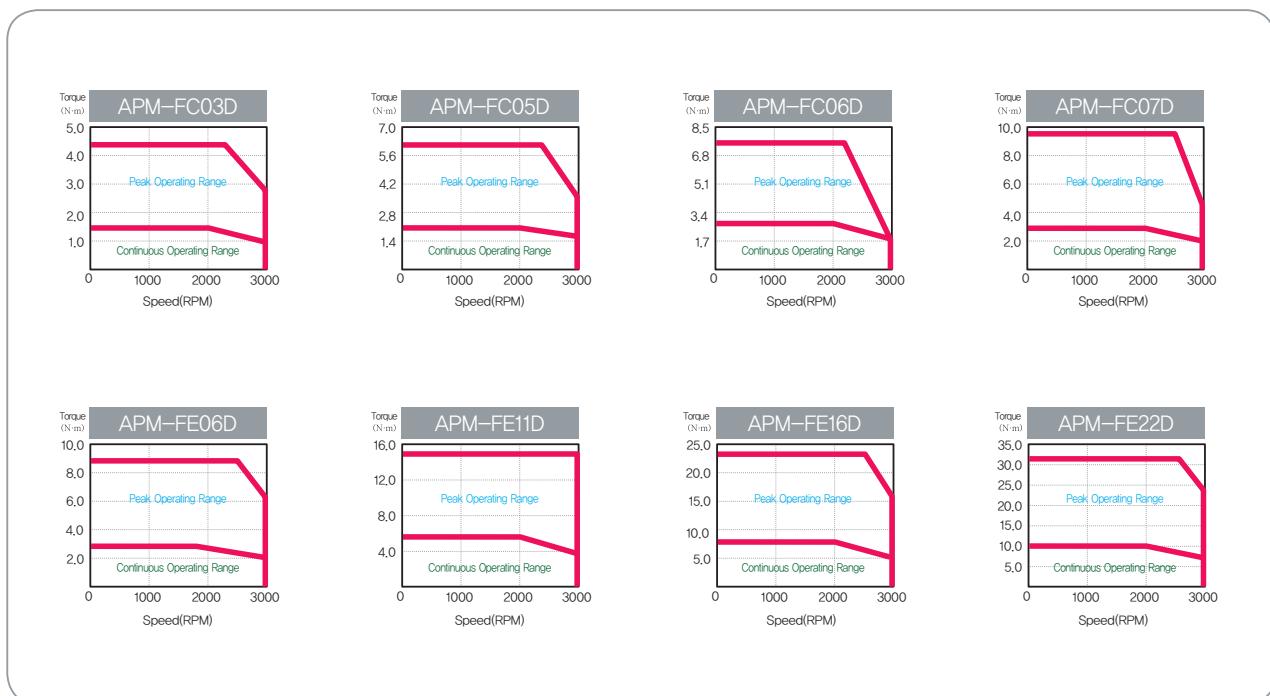
F Series Motor Characteristics (200V)

Motor Specifications [Rated 2000r/min]

| Servo Motor (APM-□□□□) | FC03D | FC05D | FC06D | FC07D | FE06D | FE11D | FE16D | FE22D |
|---|-----------------|-------|---------------------------|--|--|---------------------------|-------|---------|
| Applicable Drive | L7□A004 | | | L7□A008 | | L7□A010 | | L7□A020 |
| Flange Size(□) | | | □80 | | | □130 | | |
| Rated Output [kW] | 0.3 | 0.45 | 0.55 | 0.65 | 0.6 | 1.1 | 1.6 | 2.2 |
| Rated Torque [N · m] | 143 | 215 | 2.6 | 3.1 | 2.86 | 5.25 | 7.63 | 10.5 |
| [kgf · cm] | 14.6 | 21.9 | 26.8 | 31.7 | 29.20 | 53.6 | 77.9 | 107.1 |
| Instantaneous Maximum Torque [N · m] | 4.3 | 6.45 | 7.88 | 9.31 | 8.59 | 15.75 | 22.92 | 31.51 |
| [kgf · cm] | 43.8 | 65.8 | 80.4 | 95 | 87.7 | 160.7 | 233.8 | 321.4 |
| Rated Current [A] | 2.5 | 3.05 | 3.06 | 3.83 | 4.56 | 6.47 | 10.98 | 12.97 |
| Max. Current [A] | 7.51 | 9.16 | 9.18 | 11.5 | 13.68 | 19.41 | 32.94 | 38.91 |
| Rated Speed [r/min] | | | | 2000 | | | | |
| Max. Speed [r/min] | | | | 3000 | | | | |
| Inertia [kg · m ² × 10 ⁻⁴] | 0.5 | 0.88 | 1.25 | 1.62 | 5.66 | 10.18 | 14.62 | 19.04 |
| [gf · cm × s ²] | 0.51 | 0.89 | 1.27 | 1.65 | 5.77 | 10.39 | 14.92 | 19.43 |
| Allowable Load Inertia Ratio | | | 15 times of motor inertia | | | 10 times of motor inertia | | |
| Rated Power Rate [kW/s] | 41.28 | 52.76 | 55.39 | 59.64 | 14.49 | 27.08 | 39.89 | 57.9 |
| Speed/Position Detector | Standard(Note1) | | | | Serial Multi-Turn Built-in Type(19bit) | | | |
| Option | | | | | X | | | |
| Structure | | | | | Fully closed · Self cooling IP65 Note1 | | | |
| Rated Time | | | | | Continuous | | | |
| Ambient Temp | | | | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | |
| Ambient Humidity | | | | 90[%]RH Below (avoid dew-condensation) | | | | |
| Atmosphere | | | | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | |
| E/V | | | | Elevation/vibration 49[m/s ²](5G) | | | | |
| Weight [kg] | 1.6 | 2.2 | 2.7 | 3.8 | 5 | 6.7 | 8.5 | 10.1 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked
It can be satisfied protection grade when you use private cable only.

Speed–Torque Characteristics



L7 SERIES SYSTEM

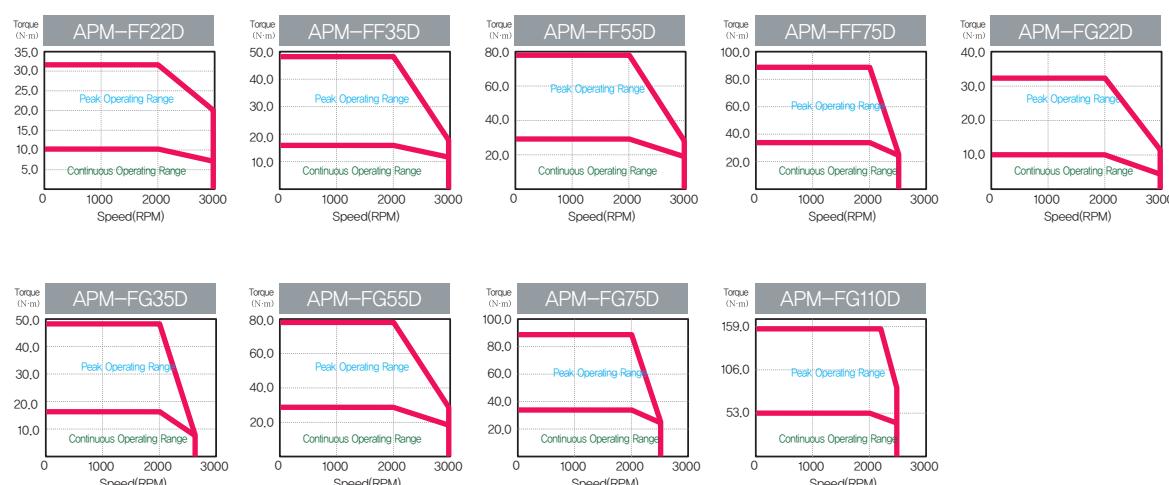
F Series Motor Characteristics (200V)

■ Motor Specifications [Rated 2000r/min]

| Servo Motor (APM-□□□□) | FF22D | FF35D | FF55D | FF75D | FG22D | FG35D | FG55D | FG75D | FG110D |
|--|------------------|---------|---------|---------|--|---------|---------|---------|----------|
| Applicable Drive | L7□A020 | L7□A035 | L7□A050 | L7□A075 | L7□A020 | L7□A035 | L7□A050 | L7□A075 | L7□A150 |
| Flange Size(□) | □180 | | | | | | □220 | | |
| Rated Output [kW] | 2.2 | 3.5 | 5.5 | 7.5 | 2.2 | 3.5 | 5.5 | 7.5 | 11 |
| Rated Torque [N·m] | 10.5 | 16.7 | 26.25 | 35.81 | 10.5 | 16.71 | 26.25 | 35.81 | 52.52 |
| [kgf·cm] | 107.1 | 170.4 | 267.8 | 365.4 | 107.1 | 170.4 | 267.8 | 365.4 | 535.9 |
| Instantaneous Maximum Torque [N·m] | 31.5 | 50.1 | 78.76 | 89.53 | 31.51 | 50.12 | 78.76 | 89.53 | 157.55 |
| [kgf·cm] | 321.3 | 511.4 | 803.4 | 913.5 | 321.3 | 511.3 | 803.4 | 913.5 | 1,607.60 |
| Rated Current [A] | 13.07 | 16.48 | 28.78 | 32.95 | 10.25 | 14.67 | 29.74 | 30.17 | 51.39 |
| Max.Current [A] | 39.21 | 49.44 | 86.34 | 82.37 | 30.75 | 44.01 | 89.22 | 75.43 | 154.17 |
| Rated Speed [r/min] | | | | | 2000 | | | | |
| Max. Speed [r/min] | | 3000 | | | 2500 | 3000 | 2700 | 3000 | 2500 |
| Inertia [kg·m ² ×10 ⁻⁴] | 27.96 | 46.56 | 73.85 | 106.7 | 41.13 | 71.53 | 117.72 | 149.4 | 291.36 |
| [gf·cm×s ²] | 28.53 | 47.51 | 75.36 | 108.9 | 41.97 | 72.99 | 120.12 | 152.45 | 297.31 |
| Allowable Load Inertia Ratio | | | | | 5 times of motor inertia | | | | |
| 정격파워레이트 [kW/s] | 39.43 | 59.89 | 93.27 | 120.15 | 26.78 | 38.99 | 58.51 | 85.83 | 94.65 |
| Speed/Position Detector | Standard(Note1) | | | | Serial Type 19[bit] | | | | |
| Option | | | | | X | | | | |
| Specifications & Features | Structure | | | | Fully closed · Self cooling IP65 Note1) | | | | |
| | Rated Time | | | | Continuous | | | | |
| | Ambient Temp | | | | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | |
| | Ambient Humidity | | | | 90[%]RH Below (avoid dew-condensation) | | | | |
| | Atmosphere | | | | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | |
| | E/V | | | | Elevation/vibration 49[m/s ²](5G) | | | | |
| Weight [kg] | 12.5 | 17.4 | 25.12 | 33.8 | 15.4 | 20.2 | 28.12 | 33.45 | 66.2 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked.
It can be satisfied protection grade when you use private cable only.

■ Speed-Torque Characteristics



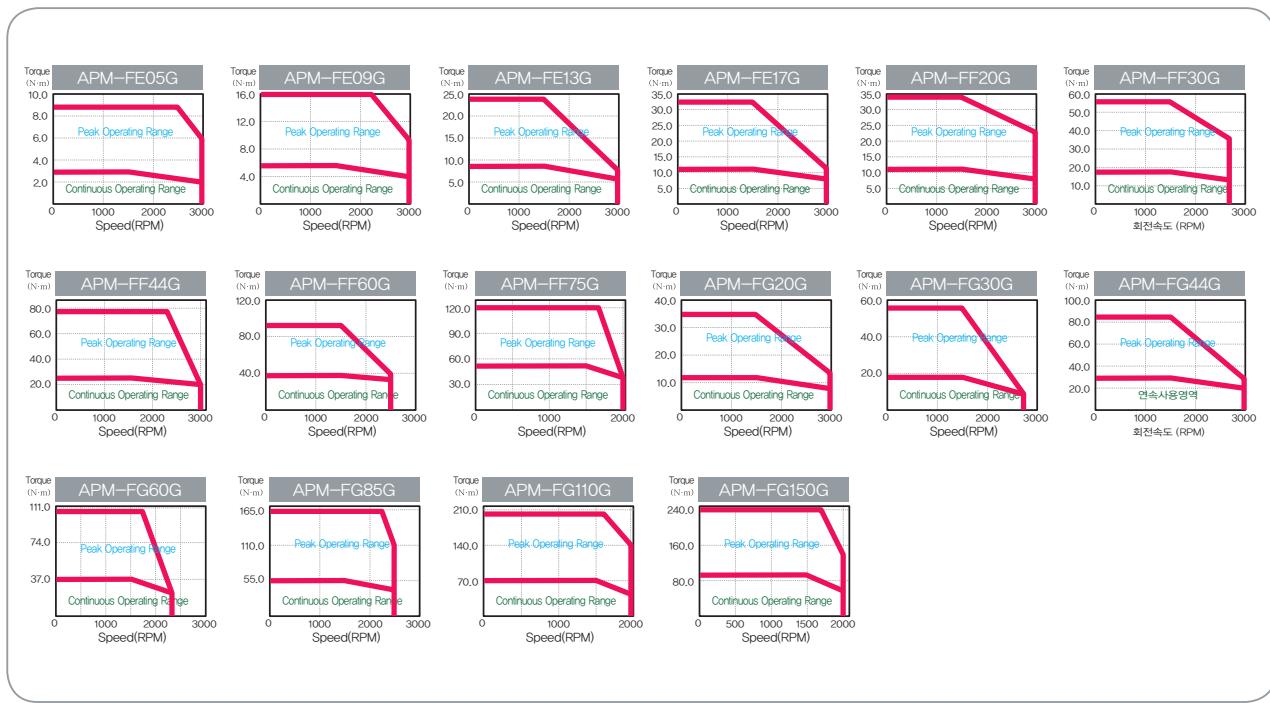
F Series Motor Characteristics (200V)

Motor Specifications [Rated 1500r/min]

| Servo Motor (APM-□□□□) | FE05G | FE09G | FE13G | FE17G | FF20G | FF30G | FF44G | FF60G | FF75G | FG20G | FG30G | FG44G | FG60G | FG85G | FG110G | FG150G | |
|------------------------------|---|--|---------|---------|---------|--------------------------|---------|---------|---------|---------|---------|---------|---------|---------|----------|----------|--------|
| Applicable Drive | L7□A008 | L7□A010 | L7□A020 | L7□A020 | L7□A035 | L7□A050 | L7□A075 | L7□A075 | L7□A075 | L7□A020 | L7□A035 | L7□A050 | L7□A075 | L7□A150 | L7□A150 | L7□A150 | |
| Flange Size(□) | □130 | | | | □180 | | | | □220 | | | | | | | | |
| Rated Output | [kW] | 0.45 | 0.85 | 1.3 | 1.7 | 1.8 | 2.9 | 4.4 | 6 | 7.5 | 1.8 | 2.9 | 4.4 | 6 | 8.5 | 11 | 15 |
| Rated Torque | [N · m] | 2.86 | 5.41 | 8.27 | 10.82 | 11.45 | 18.46 | 28 | 38.2 | 47.7 | 11.5 | 18.5 | 28 | 38.2 | 54.11 | 69.99 | 95.45 |
| | [kgf · cm] | 29.22 | 55.19 | 84.41 | 110.38 | 116.9 | 188.3 | 285.7 | 389.8 | 487.2 | 116.9 | 188.4 | 285.8 | 389.7 | 552.1 | 714.2 | 974 |
| Instantaneous Maximum Torque | [N · m] | 8.59 | 16.23 | 24.82 | 32.46 | 34.35 | 55.38 | 78.4 | 95.5 | 119.3 | 34.4 | 55.4 | 84 | 107.0 | 162.32 | 209.97 | 238.63 |
| | [kgf · cm] | 87.66 | 165.57 | 253.23 | 331.14 | 350.6 | 564.9 | 799.7 | 974.9 | 1,217.3 | 350.8 | 565.1 | 857.4 | 1,091.8 | 1,656.30 | 2,142.60 | 2,435 |
| Rated Current | [A] | 4.56 | 6.67 | 11.9 | 13.36 | 12.16 | 15.98 | 30.7 | 35.14 | 35.26 | 11.18 | 16.21 | 31.72 | 32.18 | 52.94 | 59.3 | 75.6 |
| Max. Current | [A] | 13.68 | 20.01 | 35.7 | 40.08 | 36.48 | 47.94 | 85.96 | 89.85 | 88.15 | 33.54 | 48.63 | 88.82 | 96.54 | 158.82 | 177.9 | 189 |
| Rated Speed | [r/min] | 1500 | | | | | | | | | | | | | | | |
| Max. Speed | [r/min] | 3000 | | | | 3000 | 2700 | 3000 | 2500 | 2200 | 3000 | 2700 | 3000 | 2500 | 2500 | 2000 | 2000 |
| Inertia | [kg · m ² × 10 ⁻⁴] | 5.66 | 10.18 | 14.62 | 19.04 | 27.96 | 46.56 | 73.85 | 106.7 | 131.3 | 14.13 | 71.53 | 117.72 | 149.4 | 291.36 | 291.36 | 424.57 |
| | [gf · cm × s ²] | 5.77 | 10.39 | 14.92 | 19.43 | 28.53 | 47.51 | 75.36 | 108.9 | 134 | 41.97 | 72.99 | 120.12 | 152.45 | 297.31 | 297.31 | 416.08 |
| Allowable Load Inertia Ratio | | 10 times of motor inertia | | | | 5 times of motor inertia | | | | | | | | | | | |
| Rated Power Rate | [kW/s] | 14.49 | 28.74 | 46.81 | 61.46 | 46.92 | 73.14 | 106.15 | 136.73 | 173.63 | 31.91 | 47.66 | 66.64 | 97.63 | 100.48 | 168.27 | 223.44 |
| Speed/Position Detector | Standard(Note1) | Serial Type 19 [bit] | | | | | | | | | | | | | | | |
| | Option | X | | | | | | | | | | | | | | | |
| | Structure | Fully closed · Self cooling IP65 Note1 | | | | | | | | | | | | | | | |
| | Rated Time | Continuous | | | | | | | | | | | | | | | |
| Specifications & Features | Ambient Temp | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | | | | | | | | | | |
| | Ambient Humidity | 90[%]RH Below (avoid dew-condensation) | | | | | | | | | | | | | | | |
| | Atmosphere | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | | | | | | | | | | | |
| | E/V | Elevation/vibration 49[m/s ²](5G) | | | | | | | | | | | | | | | |
| Weight | [kg] | 5.0 | 6.7 | 8.5 | 10.1 | 12.5 | 17.4 | 25.2 | 33.8 | 38.5 | 15.4 | 20.2 | 28 | 33.45 | 66.2 | 66.3 | 92.2 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked
It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



L7 SERIES SYSTEM

F Series Motor Characteristics (200V)

■ Motor Specifications [Rated 1000r/min]

| Servo Motor (APM-□□□□) | FE03M | FE06M | FE09M | FE12M | FF12M | FF20M | FF30M | FF44M | FG12M | FG20M | FG30M | FG44M | FG60M | |
|------------------------------|---|---------|---------|---------|---------------------------|---------|--|---------|---------|---------|--------------------------|--------|---------|----------|
| Applicable Drive | L7□A004 | L7□A008 | L7□A010 | L7□A020 | L7□A020 | L7□A035 | L7□A050 | L7□A020 | L7□A035 | L7□A050 | L7□A075 | | | |
| Flange Size(□) | □130 | | | | □180 | | | | □220 | | | | | |
| Rated Output | [kW] | 0.3 | 0.6 | 0.9 | 1.2 | 1.2 | 2 | 3 | 4.4 | 1.2 | 2 | 3 | 4.4 | 6 |
| Rated Torque | [N · m] | 2.86 | 5.72 | 8.59 | 11.46 | 11.46 | 19.09 | 28.64 | 42.02 | 11.5 | 19.1 | 28.6 | 42 | 57.29 |
| | [kgf · cm] | 29.22 | 58.4 | 87.7 | 116.9 | 116.9 | 194.8 | 292.2 | 428.7 | 116.9 | 194.9 | 292.3 | 428.7 | 584.6 |
| Instantaneous Maximum Torque | [N · m] | 8.59 | 17.18 | 25.77 | 34.22 | 34.38 | 57.29 | 85.94 | 105.1 | 34.4 | 57.3 | 85.9 | 126 | 171.87 |
| | [kgf · cm] | 87.66 | 175.3 | 262.9 | 349.1 | 350.7 | 584.4 | 876.6 | 1,072.4 | 350.8 | 584.6 | 876.9 | 1,286.1 | 1,753.80 |
| Rated Current | [A] | 2.73 | 4.56 | 6.18 | 10.67 | 11.01 | 12.96 | 16.58 | 30.6 | 11.28 | 13.1 | 15.52 | 27.26 | 38 |
| Max. Current | [A] | 8.19 | 13.68 | 18.54 | 32.01 | 33.03 | 38.88 | 49.74 | 85.68 | 33.84 | 39.3 | 46.56 | 81.78 | 102 |
| Rated Speed | [r/min] | | | | | | | | | 1000 | | | | |
| Max. Speed | [r/min] | | | | 2000 | | | | | 1700 | 2000 | 1700 | 2000 | |
| Inertia | [kg · m ² × 10 ⁻⁴] | 5.66 | 10.18 | 14.62 | 19.04 | 27.96 | 46.56 | 73.85 | 106.7 | 41.13 | 71.53 | 117.72 | 149.4 | 291.36 |
| | [gf · cm × s ²] | 5.77 | 10.39 | 14.92 | 19.43 | 28.53 | 47.51 | 75.36 | 108.9 | 41.97 | 72.99 | 120.12 | 152.45 | 297.31 |
| Allowable Load Inertia Ratio | | | | | 10 times of motor inertia | | | | | | 5 times of motor inertia | | | |
| Rated Power Rate | [kW/s] | 14.49 | 32.22 | 50.48 | 68.91 | 46.94 | 78.27 | 111.04 | 165.38 | 31.91 | 51 | 69.7 | 118.14 | 112.65 |
| Speed/Position Detector | Standard(Note1) | | | | | | Serial Type 19 [bit] | | | | | | | |
| | Option | | | | | | X | | | | | | | |
| | Structure | | | | | | Fully closed · Self cooling IP65 Note1) | | | | | | | |
| | Rated Time | | | | | | Continuous | | | | | | | |
| Specifications & Features | Ambient Temp | | | | | | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | | |
| | Ambient Humidity | | | | | | 90[%]RH Below (avoid dew-condensation) | | | | | | | |
| | Atmosphere | | | | | | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | | | |
| | E/V | | | | | | Elevation/vibration 49[m/s ²](5G) | | | | | | | |
| Weight | [kg] | 5 | 6.7 | 8.5 | 10.1 | 12.5 | 17.4 | 25.2 | 33.8 | 15.4 | 20.2 | 28 | 33.5 | 66.2 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked.
It can be satisfied protection grade when you use private cable only.

■ Speed-Torque Characteristics



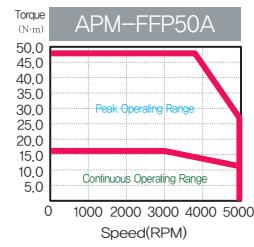
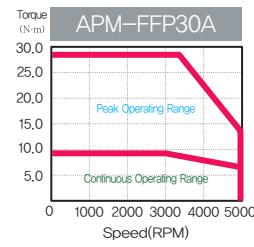
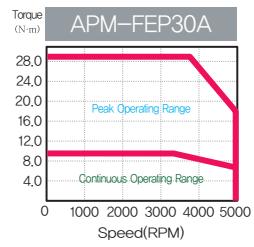
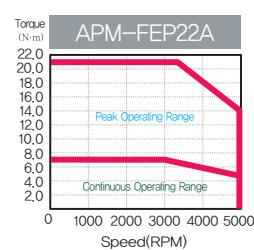
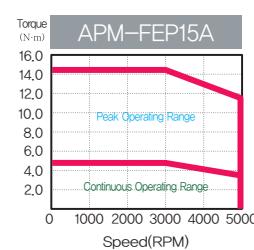
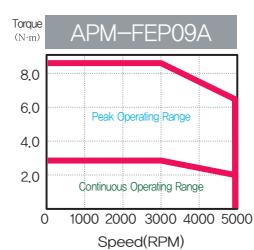
F Series Motor Characteristics (400V)

Motor Specifications [Rated 3000r/min]

| Servo Motor (APM-□□□□) | FEP09A | FEP15A | FEP22A | FEP30A | FFP30A | FFP50A |
|------------------------------|---|----------|--|--|--------|--------------------------|
| Applicable Drive | L7□B010□ | L7□B020□ | | L7□B035□ | | L7□B050□ |
| Flange Size(□) | | | □130 | | | □180 |
| Rated Output | [kW] | 0.9 | 1.5 | 2.2 | 3.0 | 5.0 |
| Rated Torque | [N · m] | 2.86 | 4.77 | 7.0 | 9.55 | 15.92 |
| | [kgf · cm] | 29.23 | 48.72 | 71.46 | 97.44 | 162.4 |
| Instantaneous Maximum Torque | [N · m] | 8.59 | 14.32 | 21.01 | 28.65 | 39.79 |
| | [kgf · cm] | 87.7 | 146.16 | 214.37 | 292.33 | 406.01 |
| Rated Current | [A] | 3.47 | 6.68 | 9.12 | 9.94 | 16.07 |
| Max. Current | [A] | 10.4 | 20.03 | 27.35 | 29.81 | 48.22 |
| Rated Speed | [r/min] | | | 3000 | | |
| Max. Speed | [r/min] | | | 5000 | | |
| Inertia | [kg · m ² × 10 ⁻⁴] | 5.659 | 10.179 | 14.619 | 19.04 | 27.96 |
| | [gf · cm × s ²] | 5.774 | 10.387 | 14.917 | 19.429 | 28.531 |
| Allowable Load Inertia Ratio | | | 10 times of motor inertia | | | 5 times of motor inertia |
| Rated Power Rate | [kW/s] | 14.5 | 22.4 | 33.55 | 47.89 | 32.61 |
| Speed/Position Detector | Standard(Note1) | | | Serial Type 19 [bit] | | |
| | Option | | | X | | |
| | Structure | | | Fully closed · Self cooling IP65 Note1 | | |
| | Rated Time | | | Continuous | | |
| Specifications & Features | Ambient Temp | | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | |
| | Ambient Humidity | | 90[%]RH Below (avoid dew-condensation) | | | |
| | Atmosphere | | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | |
| | E/V | | Elevation/vibration 49[m/s ²](5G) | | | |
| Weight | [kg] | 5.5 | 7.54 | 9.68 | 11.78 | 12.4 |
| | | | | | | 17.7 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked
It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



L7 SERIES SYSTEM

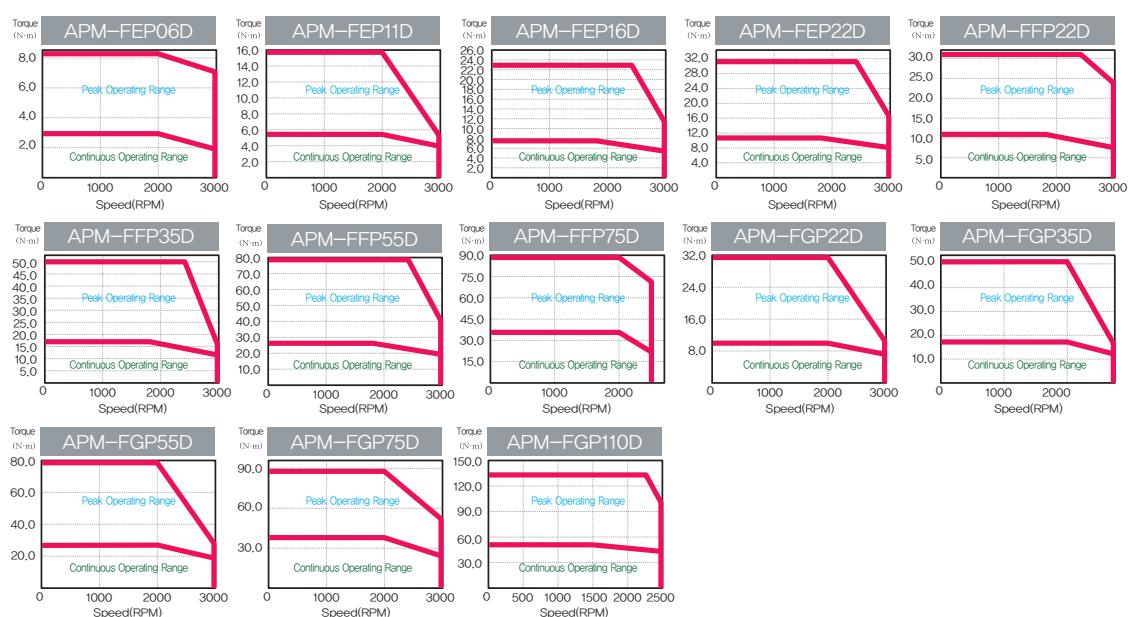
F Series Motor Characteristics (400V)

Motor Specifications [Rated 2000r/min]

| Servo Motor (APM-□□□□) | FEP06D | FEP11D | FEP16D | FEP22D | FFP22D | FFP35D | FFP55D | FFP75D | FGP22D | FGP35D | FGP55D | FGP75D | FGP110D |
|---|-----------------|--------|----------|---------------------------|----------|----------|--|----------|----------|--------------------------|----------|----------|---------|
| Applicable Drive | L7□B010□ | | L7□B020□ | | L7□B035□ | L7□B050□ | L7□B075□ | L7□B020□ | L7□B035□ | L7□B050□ | L7□B075□ | L7□B150□ | |
| Flange Size(□) | □130 | | | | □180 | | | | □220 | | | | |
| Rated Output [kW] | 0.6 | 1.1 | 1.6 | 2.2 | 2.2 | 3.5 | 5.5 | 7.5 | 2.2 | 3.5 | 5.5 | 7.5 | 11 |
| Rated Torque [N·m] | 2.86 | 5.25 | 7.64 | 10.5 | 10.5 | 16.71 | 26.26 | 35.81 | 10.5 | 16.71 | 26.26 | 35.81 | 52.52 |
| [kgf·cm] | 29.23 | 53.59 | 77.95 | 107.19 | 107.19 | 170.52 | 267.96 | 365.41 | 107.19 | 170.52 | 267.96 | 365.41 | 535.93 |
| Instantaneous Maximum Torque [N·m] | 8.59 | 15.76 | 22.92 | 31.51 | 31.51 | 50.13 | 65.65 | 89.52 | 31.51 | 50.13 | 78.78 | 89.52 | 131.30 |
| [kgf·cm] | 87.7 | 160.78 | 233.86 | 321.56 | 321.56 | 511.57 | 669.91 | 913.52 | 321.56 | 511.57 | 803.89 | 913.52 | 1339.82 |
| Rated Current [A] | 3.28 | 3.4 | 4.97 | 6.80 | 6.93 | 9.09 | 14.70 | 18.97 | 7.12 | 8.73 | 16.04 | 19.10 | 27.41 |
| Max. Current [A] | 9.83 | 10.19 | 14.92 | 20.4 | 20.8 | 27.26 | 44.1 | 47.42 | 21.35 | 26.2 | 48.11 | 47.76 | 67.33 |
| Rated Speed [r/min] | | | | | | | 2000 | | | | | | |
| Max. Speed [r/min] | | | | | 3000 | | | 2500 | 3000 | 2700 | 3000 | | 2500 |
| Inertia [$\text{kg} \cdot \text{m}^2 \times 10^{-4}$] | 5.659 | 10.179 | 14.619 | 19.04 | 27.96 | 46.56 | 73.85 | 106.73 | 41.13 | 71.53 | 117.72 | 149.4 | 291.36 |
| [gf·cm×s ²] | 5.774 | 10.387 | 14.917 | 19.429 | 28.531 | 47.51 | 75.357 | 108.908 | 41.67 | 72.99 | 120.12 | 152.45 | 297.31 |
| Allowable Load Inertia Ratio | | | | 10 times of motor inertia | | | | | | 5 times of motor inertia | | | |
| Rated Power Rate [kW/s] | 14.5 | 27.1 | 39.92 | 57.95 | 39.46 | 59.98 | 93.38 | 120.15 | 26.83 | 39.04 | 58.58 | 85.83 | 94.65 |
| Speed/Position Detector | Standard(Note1) | | | | | | Serial Type 19 [bit] | | | | | | |
| Option | | | | | | | X | | | | | | |
| Structure | | | | | | | Fully closed · Self cooling IP65 Note1) | | | | | | |
| Rated Time | | | | | | | Continuous | | | | | | |
| Ambient Temp | | | | | | | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | |
| Ambient Humidity | | | | | | | 90[%]RH Below (avoid dew-condensation) | | | | | | |
| Atmosphere | | | | | | | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | | |
| E/V | | | | | | | Elevation/vibration 49[m/s ²](5G) | | | | | | |
| Weight [kg] | 5.5 | 7.54 | 9.68 | 11.78 | 12.4 | 17.7 | 26.3 | 35.6 | 16.95 | 21.95 | 30.8 | 37.52 | 66.2 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked.
It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



F Series Motor Characteristics (400V)

Motor Specifications [Rated 1500r/min]

| Servo Motor (APM-□□□□) | FEP05G | FEP09G | FEP13G | FEP17G | FFP20G | FFP30G | FFP44G | FFP60G | FFP75G | FPG20G | FPG30G | FPG44G | FPG60G | FPG85G | FGP10G | FGP150G | |
|------------------------------|---|---------------------------|----------|--------|----------|----------|----------|----------|----------|----------|--------------------------|--|--------|--------|----------|---------|---------|
| Applicable Drive | L7□B010□ | | L7□B020□ | | L7□B035□ | L7□B050□ | L7□B075□ | L7□B020□ | L7□B035□ | L7□B050□ | L7□B075□ | | | | L7□B150□ | | |
| Flange Size(□) | | □130 | | | □180 | | | | | | | | | □220 | | | |
| Rated Output | [kW] | 0.45 | 0.85 | 1.3 | 1.7 | 1.8 | 2.9 | 4.4 | 6 | 7.5 | 1.8 | 2.9 | 4.4 | 6 | 8.5 | 11 | 15 |
| Rated Torque | [N · m] | 2.86 | 5.41 | 8.28 | 10.82 | 11.46 | 18.46 | 28.01 | 38.2 | 47.75 | 11.46 | 18.46 | 28.01 | 38.2 | 54.11 | 70.03 | 95.49 |
| | [kgf · cm] | 29.23 | 55.22 | 84.45 | 110.43 | 116.93 | 188.39 | 285.83 | 389.77 | 487.21 | 116.93 | 188.39 | 285.83 | 389.77 | 552.17 | 714.57 | 974.42 |
| Instantaneous Maximum Torque | [N · m] | 8.59 | 16.23 | 24.83 | 32.47 | 34.38 | 55.39 | 84.03 | 95.49 | 119.37 | 34.38 | 55.39 | 84.03 | 95.49 | 135.28 | 175.07 | 238.73 |
| | [kgf · cm] | 87.7 | 165.65 | 253.35 | 331.3 | 350.79 | 565.16 | 857.49 | 974.42 | 1218.02 | 350.79 | 565.16 | 857.49 | 974.42 | 1380.43 | 1786.43 | 2436.05 |
| Rated Current | [A] | 3.28 | 3.50 | 5.39 | 7.01 | 7.56 | 10.04 | 15.68 | 20.23 | 20.01 | 7.76 | 9.65 | 17.11 | 20.38 | 28.24 | 28.28 | 35.71 |
| Max. Current | [A] | 9.83 | 10.5 | 16.16 | 21.02 | 22.69 | 30.12 | 47.04 | 50.58 | 50.03 | 23.29 | 28.95 | 51.32 | 50.95 | 69.37 | 68.83 | 87.7 |
| Rated Speed | [r/min] | | | | | | | | | | 1500 | | | | | | |
| Max. Speed | [r/min] | | | 3000 | | 2700 | 3000 | 2500 | 2200 | 3000 | 2700 | 3000 | 2500 | 2000 | | | |
| Inertia | [kg · m ² × 10 ⁻⁴] | 5.659 | 10.179 | 14.619 | 19.04 | 27.96 | 46.56 | 73.85 | 106.73 | 131.29 | 51.42 | 80.35 | 132.41 | 172.91 | 291.36 | 51.42 | 424.5 |
| | [gf · cm × s ²] | 5.774 | 10.387 | 14.917 | 19.429 | 28.531 | 47.51 | 75.357 | 108.908 | 133.969 | 52.47 | 81.99 | 135.11 | 176.44 | 297.31 | 52.47 | 433.2 |
| Allowable Load Inertia Ratio | | 10 times of motor inertia | | | | | | | | | 5 times of motor inertia | | | | | | |
| Rated Power Rate | [kW/s] | 14.5 | 28.77 | 46.85 | 61.52 | 46.96 | 73.21 | 106.25 | 136.7 | 173.64 | 25.53 | 45.39 | 61.97 | 102.08 | 100.5 | 168.3 | 214.8 |
| Speed/Position Detector | Standard(Note1) | | | | | | | | | | Serial Type 19 [bit] | | | | | | |
| Option | | | | | | | | | | | X | | | | | | |
| Specifications & Features | Structure | | | | | | | | | | | Fully closed · Self cooling IP65 Note1) | | | | | |
| | Rated Time | | | | | | | | | | | Continuous | | | | | |
| | Ambient Temp | | | | | | | | | | | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | |
| | Ambient Humidity | | | | | | | | | | | 90[%]RH Below (avoid dew-condensation) | | | | | |
| | Atmosphere | | | | | | | | | | | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | |
| | E/V | | | | | | | | | | | Elevation/vibration 49[m/s ²](5G) | | | | | |
| Weight | [kg] | 5.5 | 7.54 | 9.68 | 11.78 | 12.4 | 17.7 | 26.3 | 35.6 | 39.4 | 16.95 | 21.95 | 30.8 | 37.52 | 66.2 | 66.3 | 92.2 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked
It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics



L7S Series

L7NH Series

F Series

MDM Series

PEGASUS Series

Options

L7 SERIES SYSTEM

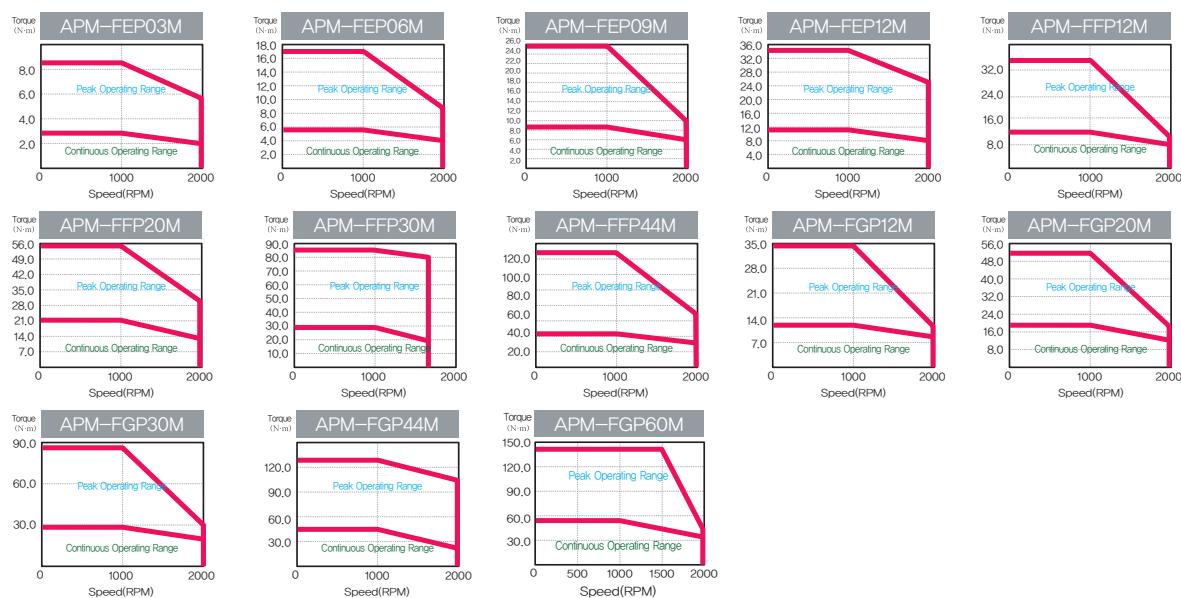
F Series Motor Characteristics (400V)

Motor Specifications [Rated 1000r/min]

| Servo Motor (APM-□□□□) | FEP03M | FEP06M | FEP09M | FEP12M | FFP12M | FFP20M | FFP30M | FFP44M | FGP12M | FGP20M | FGP30M | FGP44M | FGP60M |
|---|--|--------|--------|----------|--------|--------|--------------------------|---------|--------|----------|--------|---------|---------|
| Applicable Drive | L7□B010□ | | | L7□B020□ | | | L7□B050□ | | | L7□B020□ | | | L7□B150 |
| Flange Size(□) | □130 | | | | | | □180 | | | | | | □220 |
| Rated Output [kW] | 0.3 | 0.6 | 0.9 | 1.2 | 1.2 | 2 | 3 | 4.4 | 1.2 | 2 | 3 | 4.4 | 6 |
| Rated Torque [N·m] | 2.86 | 5.73 | 8.59 | 11.46 | 11.46 | 19.1 | 28.65 | 42.02 | 11.46 | 19.1 | 28.65 | 42.02 | 57.3 |
| [kgf·cm] | 29.23 | 58.47 | 87.7 | 116.93 | 116.93 | 194.88 | 292.33 | 428.74 | 116.93 | 194.88 | 292.33 | 428.74 | 584.65 |
| Instantaneous Maximum Torque [N·m] | 8.59 | 17.19 | 25.78 | 34.38 | 34.38 | 57.3 | 85.94 | 126.05 | 34.38 | 57.3 | 85.94 | 126.05 | 143.24 |
| [kgf·cm] | 87.7 | 175.4 | 263.09 | 350.79 | 350.79 | 584.65 | 876.98 | 1286.23 | 350.79 | 584.65 | 876.98 | 1071.86 | 1461.63 |
| Rated Current [A] | 3.28 | 3.28 | 3.33 | 4.87 | 4.83 | 7.94 | 11.9 | 16.69 | 4.75 | 7.88 | 11.74 | 17.39 | 23.58 |
| Max. Current [A] | 9.83 | 9.83 | 9.99 | 14.6 | 14.5 | 23.83 | 35.7 | 50.08 | 14.24 | 23.64 | 35.22 | 52.18 | 57.92 |
| Rated Speed [r/min] | 1000 | | | | | | | | | | | | |
| Max. Speed [r/min] | 2000 | | | | | | 1700 | | | 2000 | | | |
| Inertia [$\text{kg} \cdot \text{m}^2 \times 10^{-4}$] | 5.659 | 10.179 | 14.619 | 19.04 | 27.96 | 46.56 | 73.85 | 106.73 | 51.42 | 80.35 | 132.41 | 172.91 | 291.36 |
| [gf·cm×s ²] | 5.774 | 10.387 | 14.917 | 19.429 | 28.531 | 47.51 | 75.357 | 108.908 | 52.47 | 81.99 | 135.11 | 176.44 | 297.31 |
| Allowable Load Inertia Ratio | 10 times of motor inertia | | | | | | 5 times of motor inertia | | | | | | |
| Rated Power Rate [kW/s] | 14.5 | 32.25 | 50.53 | 68.97 | 46.96 | 78.38 | 111.13 | 165.41 | 25.53 | 45.39 | 61.97 | 102.08 | 112.64 |
| Speed/Position Detector | Standard (Note1) | | | | | | | | | | | | |
| Option | Serial Type 19 [bit] | | | | | | | | | | | | |
| Structure | Fully closed · Self cooling IP65 Note1) | | | | | | | | | | | | |
| Rated Time | Continuous | | | | | | | | | | | | |
| Ambient Temp | Operating : 0 ~ 40[°C] Storage : -10 ~ 60[°C] | | | | | | | | | | | | |
| Ambient Humidity | 90[%]RH Below (avoid dew-condensation) | | | | | | | | | | | | |
| Atmosphere | Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust. | | | | | | | | | | | | |
| E/V | Elevation/vibration 49[m/s ²](5G) | | | | | | | | | | | | |
| Weight [kg] | 5.5 | 7.54 | 9.68 | 11.78 | 12.4 | 17.7 | 26.3 | 35.6 | 16.95 | 21.95 | 30.8 | 37.52 | 66.2 |

Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked.
It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

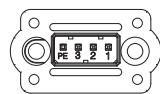


External Dimensions of Servo Motor

FAL Series

Plug Specifications

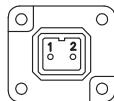
[Power]



| Pin No. | Color | Signal |
|---------|-------|--------|
| 1 | Red | U |
| 2 | White | V |
| 3 | Black | W |
| PE | Green | Ground |

(Power Connector Pin Table)

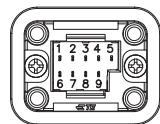
[Brake]



| Pin No. | Signal |
|---------|--------|
| 1 | BK+ |
| 2 | BK- |

(Brake Connector Pin Table)

[Encoder]



| Single Turn (N) | Multi Turn (M) | | |
|-----------------|----------------|---------|--------|
| Pin No. | Signal | Pin No. | Signal |
| 1 | MA | 1 | MA |
| 2 | SLO | 2 | SLO |
| 3 | - | 3 | GND_B |
| 4 | OV | 4 | OV |
| 5 | SHIELD | 5 | SHIELD |
| 6 | MA | 6 | MA |
| 7 | SLO | 7 | SLO |
| 8 | - | 8 | VDD_B |
| 9 | +5V | 9 | +5V |

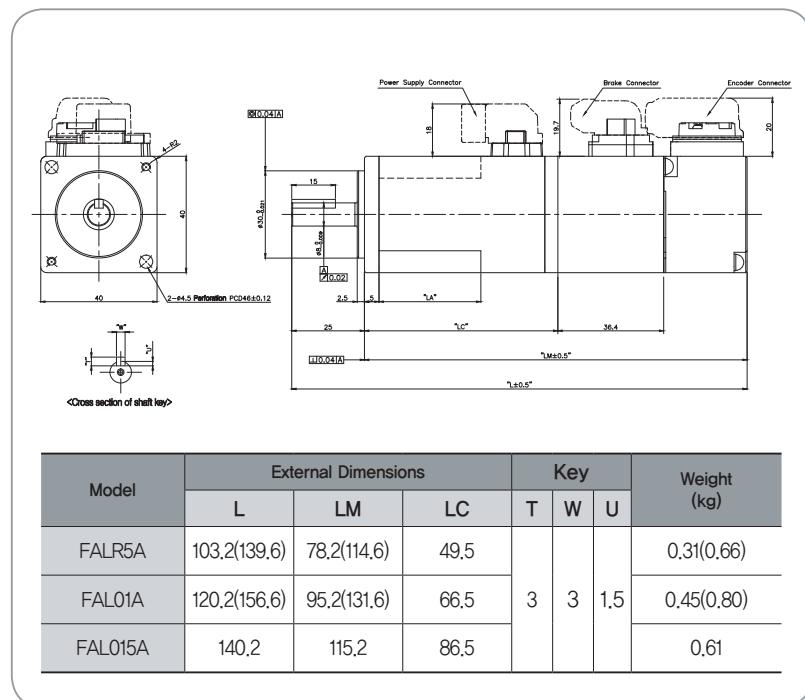
(Encoder Connector Pin Table)

Note1) Use DC[24V] for brake input power supply.

Note2) The () is for brake-attached type.

Note3) For external dimensions for oil-sealed type.
Please kindly contact us separately.

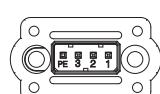
Note4) In case of FAL Type, the connector can draw
in a direction of only front



FBL Series

Plug Specifications

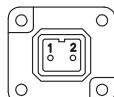
[Power]



| Pin No. | Color | Signal |
|---------|-------|--------|
| 1 | Red | U |
| 2 | White | V |
| 3 | Black | W |

(Power Connector Pin Table)

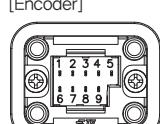
[Brake]



| Pin No. | Signal |
|---------|--------|
| 1 | BK+ |
| 2 | BK- |

(Brake Connector Pin Table)

[Encoder]



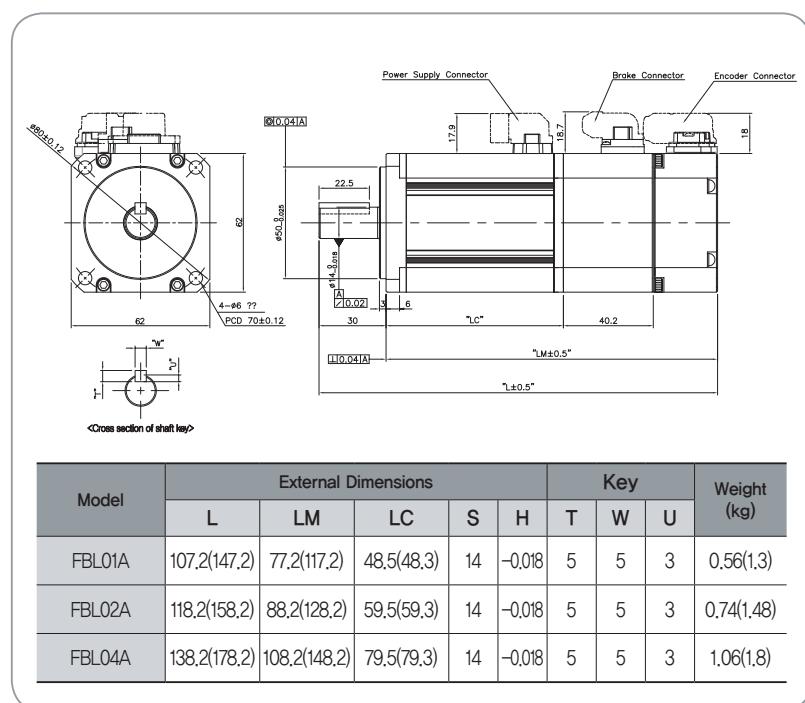
| Single Turn (N) | Multi Turn (M) | | |
|-----------------|----------------|---------|--------|
| Pin No. | Signal | Pin No. | Signal |
| 1 | MA | 1 | MA |
| 2 | SLO | 2 | SLO |
| 3 | - | 3 | GND_B |
| 4 | OV | 4 | OV |
| 5 | SHIELD | 5 | SHIELD |
| 6 | MA | 6 | MA |
| 7 | SLO | 7 | SLO |
| 8 | - | 8 | VDD_B |
| 9 | +5V | 9 | +5V |

(Encoder Connector Pin Table)

Note1) Use DC[24V] for brake input power supply.

Note2) The () is for brake-attached type.

Note3) For external dimensions for oil-sealed type.
Please kindly contact us separately.



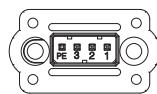
L7 SERIES SYSTEM

External Dimensions of Servo Motor

FCL Series

Plug Specifications

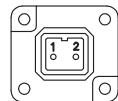
[Power]



| Pin No. | Color | Signal |
|---------|-------|--------|
| 1 | Red | U |
| 2 | White | V |
| 3 | Black | W |
| PE | Green | Ground |

(Power Connector Pin Table)

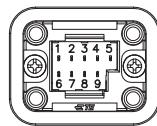
[Brake]



| Pin No. | Signal |
|---------|--------|
| 1 | BK+ |
| 2 | BK- |

(Brake Connector Pin Table)

[Encoder]



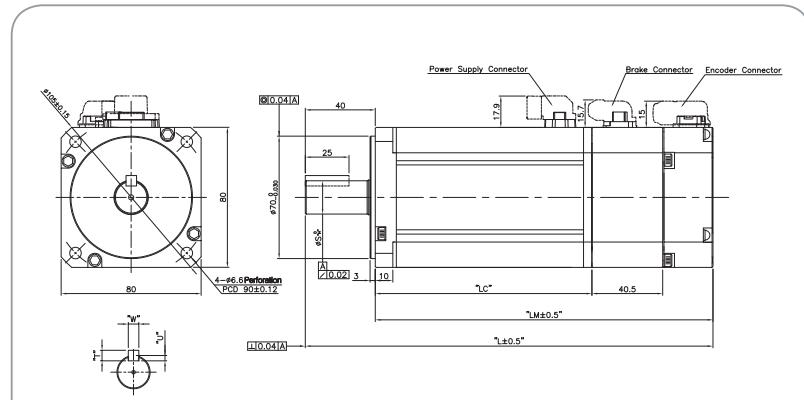
| Single Turn (N) | Multi Turn (M) | | |
|-----------------|----------------|---------|--------|
| Pin No. | Signal | Pin No. | Signal |
| 1 | MA | 1 | MA |
| 2 | SLO | 2 | SLO |
| 3 | - | 3 | GND_B |
| 4 | 0V | 4 | 0V |
| 5 | SHIELD | 5 | SHIELD |
| 6 | MA | 6 | MA |
| 7 | SLO | 7 | SLO |
| 8 | - | 8 | VDD_B |
| 9 | +5V | 9 | +5V |

(Encoder Connector Pin Table)

Note1) Use DC[24V] for brake input power supply.

Note2) The () is for brake-attached type.

Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

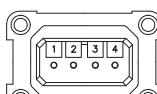


| Model | External Dimensions | | | | | | | Weight (kg) |
|---------------|---------------------|--------------|------------|----|--------|---|---|---------------------------|
| | L | LM | LC | S | H | T | W | |
| FCL04A,FCL03D | 138.7(179.5) | 98.7(139.5) | 70(69.8) | 14 | -0.018 | 5 | 5 | 3 1.52(2.32)/1.26(2.06) |
| FCL06A,FCL05D | 156.7(197.5) | 116.7(157.5) | 88(87.8) | 19 | -0.021 | 6 | 6 | 3.5 2.14(2.94)/2.12(2.92) |
| FCL08A,FCL06D | 174.7(215.5) | 134.7(175.5) | 106(105.8) | 19 | -0.021 | 6 | 6 | 3.5 2.68(3.48)/2.66(3.46) |
| FCL10A,FCL07D | 192.7(233.5) | 152.7(193.5) | 124(123.8) | 19 | -0.021 | 6 | 6 | 3.5 3.30(4.10)/2.78(3.58) |

FB Series

Plug Specifications

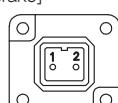
[Power]



| Pin No. | Color | Signal |
|---------|-------|--------|
| 1 | Black | W |
| 2 | White | V |
| 3 | Red | U |
| 4 | Green | Ground |

(Power Connector Pin Table)

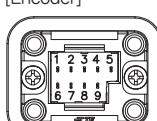
[Brake]



| Pin No. | Signal |
|---------|--------|
| 1 | BK+ |
| 2 | BK- |

(Brake Connector Pin Table)

[Encoder]



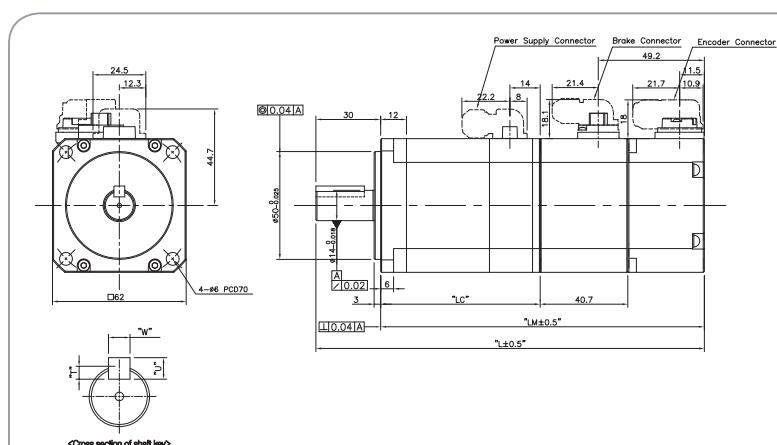
| Single Turn (N) | Multi Turn (M) | | |
|-----------------|----------------|---------|--------|
| Pin No. | Signal | Pin No. | Signal |
| 1 | MA | 1 | MA |
| 2 | SLO | 2 | SLO |
| 3 | - | 3 | GND_B |
| 4 | 0V | 4 | 0V |
| 5 | SHIELD | 5 | SHIELD |
| 6 | MA | 6 | MA |
| 7 | SLO | 7 | SLO |
| 8 | - | 8 | VDD_B |
| 9 | +5V | 9 | +5V |

(Encoder Connector Pin Table)

Note1) Use DC[24V] for brake input power supply.

Note2) The () is for brake-attached type.

Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.



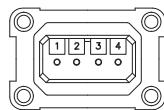
| Model | External Dimensions | | | Key | | | Weight (kg) |
|-------|---------------------|------------|----------|-----|---------------------------------------|---|-------------|
| | L | LM | LC | T | W | U | |
| FB01A | 109(149.2) | 79(119.2) | 43.5(43) | | | | 0.72(1.3) |
| FB02A | 120(160.2) | 90(130.2) | 54.5(54) | 3 | 5 ^{-0.012} _{-0.042} | 5 | 0.94(1.49) |
| FB04A | 140(180.2) | 110(150.2) | 74.5(74) | | | | 1.32(1.87) |

External Dimensions of Servo Motor

FC Series

Plug Specifications

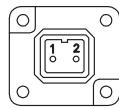
[Power]



| Pin No. | Color | Signal |
|---------|-------|--------|
| 1 | Black | W |
| 2 | White | V |
| 3 | Red | U |
| 4 | Green | Ground |

(Power Connector Pin Table)

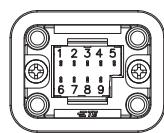
[Brake]



| Pin No. | Signal |
|---------|--------|
| 1 | BK+ |
| 2 | BK- |

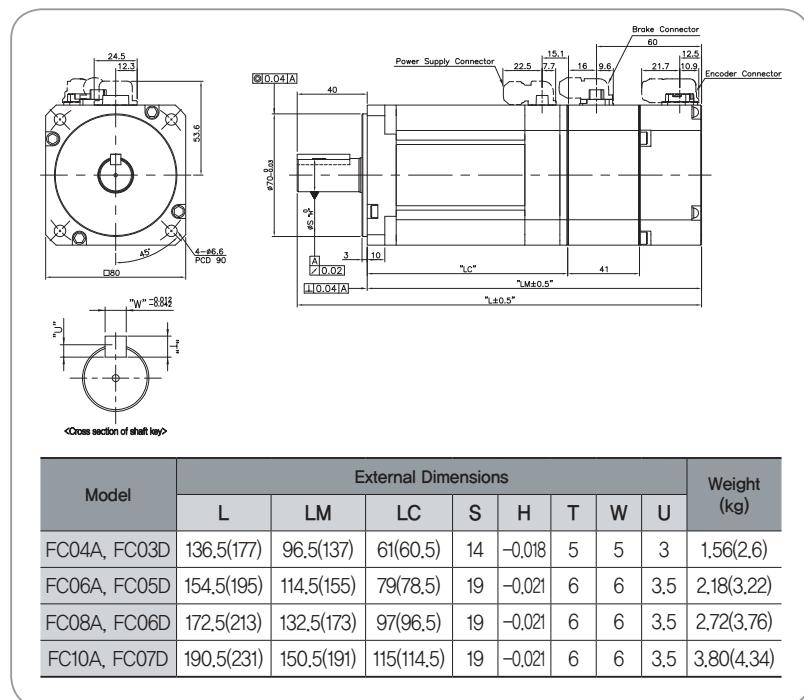
(Brake Connector Pin Table)

[Encoder]



| Single Turn (N) | Multi Turn (M) | | |
|-----------------|----------------|---------|--------|
| Pin No. | Signal | Pin No. | Signal |
| 1 | MA | 1 | MA |
| 2 | SLO | 2 | SLO |
| 3 | - | 3 | GND_B |
| 4 | OV | 4 | OV |
| 5 | SHIELD | 5 | SHIELD |
| 6 | MA | 6 | MA |
| 7 | SLO | 7 | SLO |
| 8 | - | 8 | VDD_B |
| 9 | +5V | 9 | +5V |

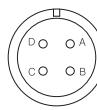
(Encoder Connector Pin Table)

Note1) Use DC[24V] for brake input power supply.**Note2)** The () is for brake-attached type.**Note3)** For external dimensions for oil-sealed type. Please kindly contact us separately.

FE, FEP Series

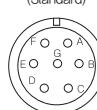
Plug Specifications

[Power]



| Pin No. | Signal |
|---------|--------|
| A | U |
| B | V |
| C | W |
| D | Ground |

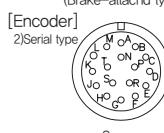
Spec. : MS3102A20-4P (Standard)



| Pin No. | Signal | Pin No. | Signal |
|---------|--------|---------|--------|
| A | U | D | Ground |
| B | V | E | BK+ |
| C | W | F | BK- |

Spec. : MS3102A20-15P (Brake-attached type)

[Encoder]

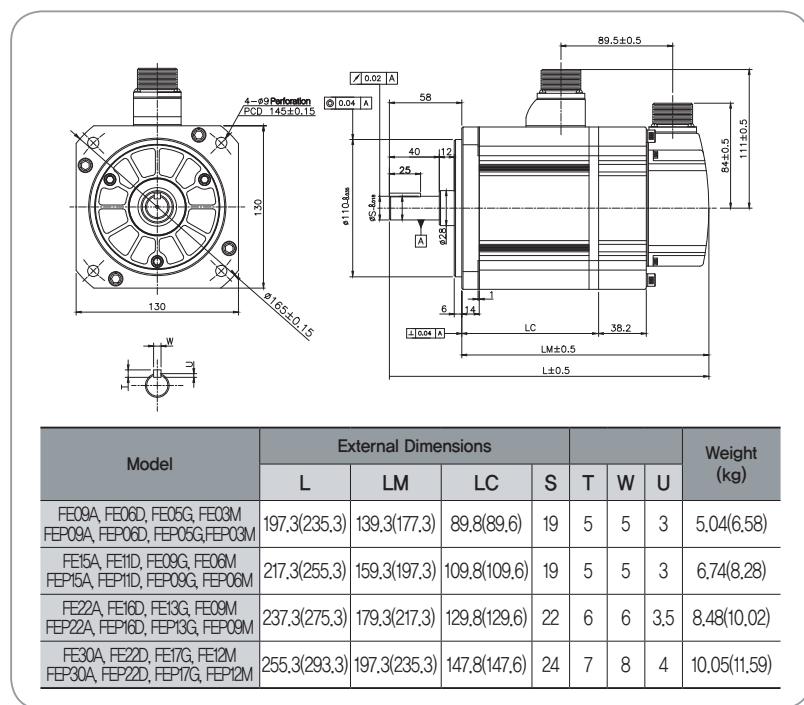


| Pin No. | Signal | Pin No. | Signal |
|---------|--------|---------|--------|
| A | MA | M | - |
| B | MA | N | - |
| C | SLO | P | - |
| D | SLO | R | - |
| E | - | H | +5V |
| F | - | G | OV |
| K | - | J | SHIELD |
| L | - | | |

Spec. : MS3102A20-29P (Serial type)

| Pin No. | Signal | Pin No. | Signal |
|---------|--------|---------|--------|
| A | MA | M | - |
| B | MA | N | - |
| C | SLO | P | - |
| D | SLO | R | - |
| E | VOD_B | H | +5V |
| F | GND_B | G | OV |
| K | - | J | SHIELD |
| L | - | | |

(Multi Turn Encoder Connector Pin Table)

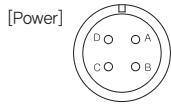
Note1) Use DC[24V] for brake input power supply.**Note2)** The () is for brake-attached type.

L7 SERIES SYSTEM

External Dimensions of Servo Motor

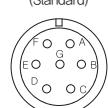
FF, FFP Series

Plug Specifications |



| Pin No. | Signal |
|---------|--------|
| A | U |
| B | V |
| C | W |
| D | Ground |

Spec. : MS3102A22-22P (Standard)



| Pin No. | Signal | Pin No. | Signal |
|---------|--------|---------|--------|
| A | U | D | Ground |
| B | V | E | BK+ |
| C | W | F | BK- |
| D | | | |

Spec. : MS3102A24-10P (Brake-attached type)



| (Single Turn Encoder Connector Pin Table) | | | |
|---|--------|---------|--------|
| Pin No. | Signal | Pin No. | Signal |
| A | MA | M | — |
| B | MA | N | — |
| C | SLO | P | — |
| D | SLO | R | — |
| E | VOD_B | H | +5V |
| F | GND_B | G | 0V |
| K | — | J | SHIELD |
| L | — | | |

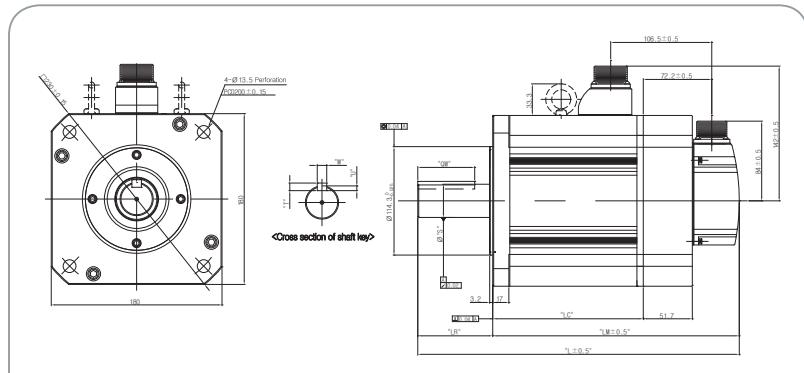
| (Multi Turn Encoder Connector Pin Table) | | | |
|--|--------|---------|--------|
| Pin No. | Signal | Pin No. | Signal |
| A | MA | M | — |
| B | MA | N | — |
| C | SLO | P | — |
| D | SLO | R | — |
| E | VOD_B | H | +5V |
| F | GND_B | G | 0V |
| K | — | J | SHIELD |
| L | — | | |

Note1) FF30M or above models have eye bolts.

Note2) Use DC[24V] for brake input power supply.

Note3) The () is for brake-attached type.

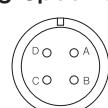
Note4) Use MS3102A32-17 for FF75G Power connector.



| Model | External Dimensions | | | | Key | | | | Weight (kg) |
|--|---------------------|--------------|------------|-----|-----------------------------------|----|---|----|-------------|
| | L | LM | LC | LR | S | QW | T | W | |
| FF30A, FF22D, FF20G, FF12M FFP30A, FFP22D, FFP20G, FFP12M | 257.5(308.9) | 178.5(229.9) | 129(128.7) | | | | | | 12.5(19.7) |
| FF30A, FF35D, FF30G, FF20M FFP50A, FFP35D, FFP30G, FFP20M | 287.5(338.9) | 208.5(259.9) | 159(158.7) | | | | | | 17.4(24.6) |
| FF55D, FF44G, FF30M FFP50D, FFP44G, FFP30M | 331.5(382.9) | 252.5(303.9) | 203(202.7) | 79 | 35 ^{+0.01} ₀ | 60 | 8 | 10 | 25.2(32.4) |
| FF75D-SF01, FF80G-SF01, FF44M-SF01, FF75D-SF01, FF80G-SF01, FF44M-SF01 | 384.5(435.9) | 305.5(356.9) | 256(255.7) | | | | | | 33.8(41.0) |
| FF75D, FF80G, FF44MFF75D, FFP80G, FFP44M | 384.5(435.9) | 305.5(356.9) | 256(255.7) | | 42 ^{-0.016} ₀ | | | 12 | 33.8(41.0) |
| FF75G, FFP75G | 439.5 | 326.5 | 277 | 113 | 96 | | | | 38.5(45.7) |

FG, FGP Series

Plug Specifications |



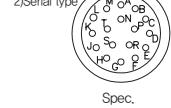
| Pin No. | Signal |
|---------|--------|
| A | U |
| B | V |
| C | W |
| D | Ground |

Spec. : MS3102A22-22P (Standard)



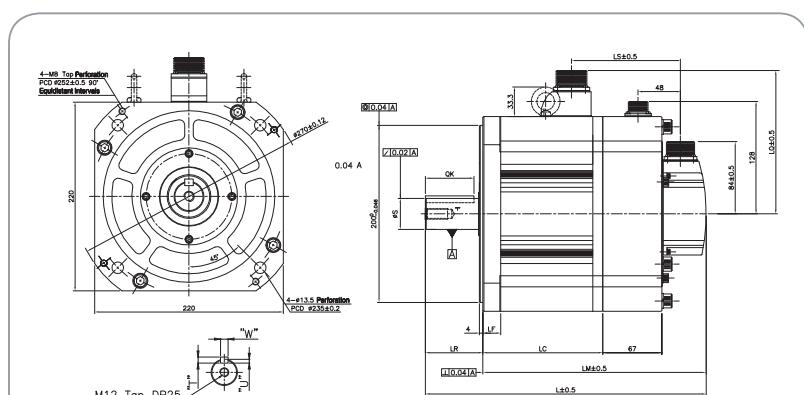
| Pin No. | Signal | Pin No. | Signal |
|---------|--------|---------|--------|
| A | BK+ | D | BK- |
| B | BK+ | E | — |
| C | NC | F | — |
| D | SLO | G | — |
| E | — | H | +5V |
| F | — | I | 0V |
| K | — | J | SHIELD |
| L | — | | |

Spec. : MS3102A24-10P (Brake-attached type)



| (Single Turn Encoder Connector Pin Table) | | | |
|---|--------|---------|--------|
| Pin No. | Signal | Pin No. | Signal |
| A | MA | M | — |
| B | MA | N | — |
| C | SLO | P | — |
| D | SLO | R | — |
| E | VOD_B | H | +5V |
| F | GND_B | G | 0V |
| K | — | J | SHIELD |
| L | — | | |

| (Multi Turn Encoder Connector Pin Table) | | | |
|--|--------|---------|--------|
| Pin No. | Signal | Pin No. | Signal |
| A | MA | M | — |
| B | MA | N | — |
| C | SLO | P | — |
| D | SLO | R | — |
| E | VOD_B | H | +5V |
| F | GND_B | G | 0V |
| K | — | J | SHIELD |
| L | — | | |



| Model | External Dimensions | | | | Key | | | | Weight (kg) | Power supply connector |
|---|---------------------|--------------|------------|----|--------------------------------------|-----|-----------------------------------|----|--------------|------------------------|
| | L | LM | LC | LF | S | QW | T | W | | |
| FG22D, FG20G, FG12M FGP22D, FGP20G, FGP12M | 229.5(295.7) | 164.5(230.7) | 115(114.2) | | | | | | 15.42(29.23) | |
| FG35D, FG30G, FG20M FGP35D, FGP30G, FGP20M | 250.5(316.7) | 185.5(251.7) | 136(135.2) | 19 | 56.4 ^{-0.016} ₀ | 162 | 35 ^{-0.016} ₀ | 55 | 20.22(34.03) | MS3102A22-22P |
| FG55D, FG44G, FG30M FGP55D, FGP44G, FGP30M | 282.5(348.7) | 217.5(283.7) | 168(167.2) | 65 | 122.6 ^{-0.016} ₀ | | 42 ^{-0.016} ₀ | 8 | 28.02(41.83) | |
| FG75D, FG60G, FG44M FGP75D, FGP60G, FGP44M | 304.5(370.7) | 239.5(305.7) | 190(189.2) | | | | 45 ^{-0.016} ₀ | 12 | 33.45(47.26) | |
| FG100, FG85G, FG60M FGP100, FGP85G, FGP60M | 418.5(484.7) | 353.5(419.7) | 304(303.2) | 21 | 115 ^{-0.016} ₀ | 173 | 42 ^{-0.016} ₀ | 96 | 66.2(82.6) | MS3102A32-17P |
| FG10G, FGP10G | 468.5 | 353.5 | 304 | 66 | 35 ^{-0.016} ₀ | | 55 ^{-0.016} ₀ | 12 | 66.3 | |
| FG150, FGP150 | 575 | 459 | 409 | 35 | 35 ^{-0.016} ₀ | | 55 ^{-0.016} ₀ | 6 | 92.2 | |

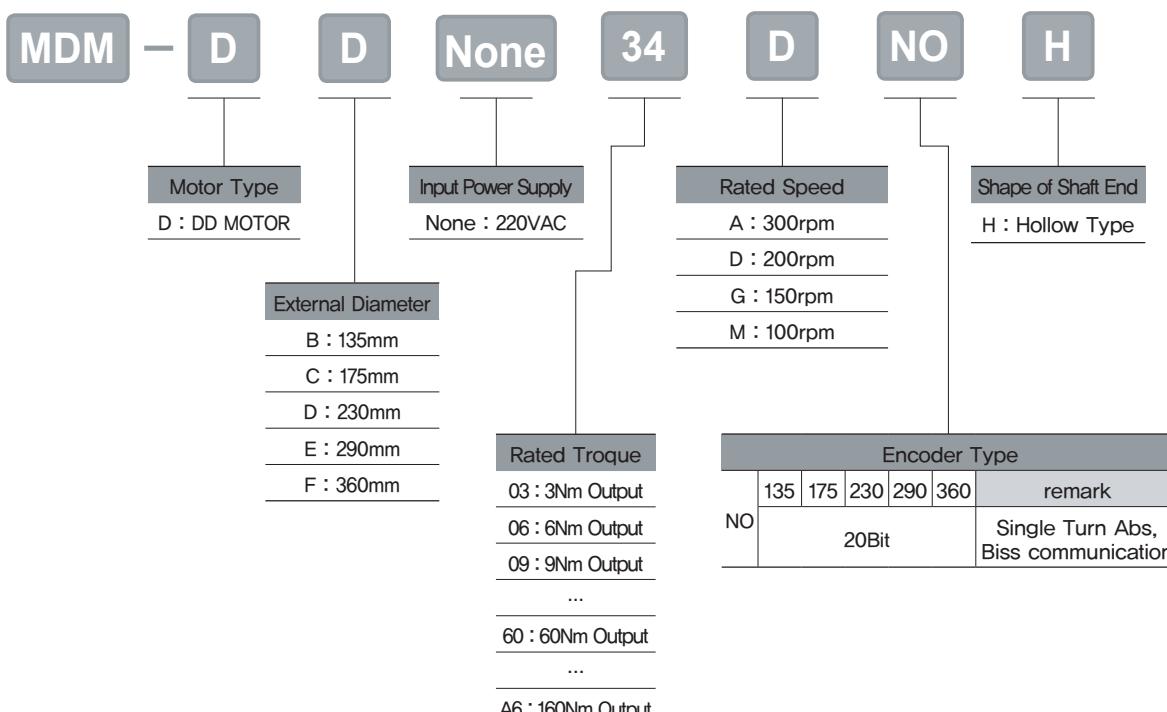
Note1) In case of SG, use DC[90V] for brake input power supply.

Note2) The () is for brake-attached type.

Direct-Drive motor



■ Direct-Drive Designation



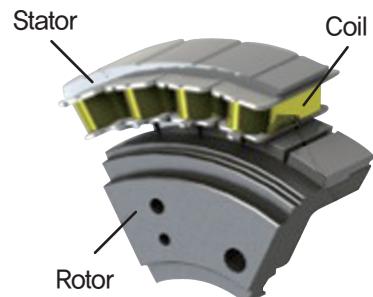
L7 SERIES SYSTEM

Features of Mecapion Direct-Drive Motor

- Using the own technologies to produce motors, drives and encoders domestically

- Optimized for low-speed, high-torque and high-precision operation

- Providing Power connection for the connection of DC-Link Terminal
- Compact Size and Easy Wring (Compared with 3 phase AC Reactor)
- Providing Connection for DC Input (PI, N)



- Reduced cogging torque and optimized torque design

- Optimal ratio of the permanent magnet and coil / slot selected through electromagnetic analysis
- Using multiple permanent magnets to reduce torque ripple and to maximize torque
- Using a permanent magnet of high-energy rare earth elements (Nd-Fe-B)

- Using the high-performance rotary optical encoder that adopts the Biss protocol

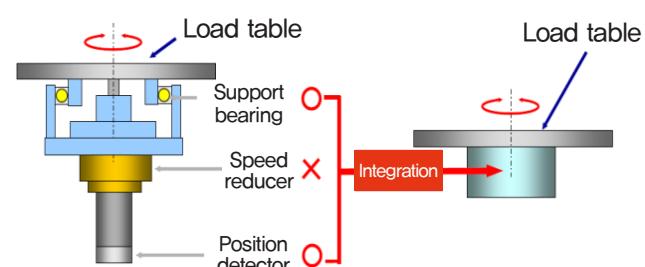
- Resolution of 1,048,576 CPR (Single turn Absolute)
- Using our own encoder technology to reduce the cost and shorten the delivery time

- Compatible with our L7 Series AC Servo Drive (3phase AC 220V)

- Both standard I/O type (serial communication supported) and network type (EtherCAT) applicable

- Direct Drive Structure

- No backlash impact
- High-precision operation and shortened installation time
- Smooth rotary motion
- Reduced noise



[Speed Reducer + Servo Motor]

[DD Motor]

- Hollow type that is efficient for wiring and piping

- A wide range of products

- Rated output: 63W–25kW
- Rated torque: 3.0N.m–160N.m (the instantaneous maximum torque should be 3 times the rated torque)
- Rated speed: 150RPM–200RPM
- Frame diameter: 135mm, 175mm, 230mm, 290mm, and 360mm (13 models)

DD Motor Specifications

Ratings and Specifications

- Insulation class : Class B
- Protection class: IP 40
- Cooling type : Fully enclosed self-cooling
- Vibration class : V15
- Insulation resistance : 500 VDC, 10[MΩ] or higher
- Insulation internal voltage: 1800 VAC, 1 second
- Operating voltage: 200 VAC
- Operating temperature : 0 – 40[°C] / Storage temperature: -10~60[°C]
- Ambient humidity : 20 – 80% RH (no condensation)
- Installation location : Place with no toxic substances, such as corrosive and combustible gasses, cutting oil, metal dust, grease or direct sunlight

Line-up Table

| Maximum Torque[Nm] | | | 9 | 18 | 27 | 36 | 54 | 66 | 102 | 120 | 180 | 330 | 480 |
|-------------------------|------------------------------|------|-------|-------|-------|----|-------|-------|-------|-------|-------|-------|-----|
| Rated speed 200[rpm] | Maximum speed 500[rpm] | Φ135 | DB03D | DB06D | DB09D | | | | | | | | |
| | | Φ175 | | | DC06D | | DC12D | | | | | | |
| | | Φ230 | | | | | DD12D | | | | | | |
| | Maximum speed 400[rpm] | Φ175 | | | | | | DC18D | | | | | |
| | | Φ230 | | | | | | DD22D | DD34D | | | | |
| | Maximum speed 300[rpm] | Φ290 | | | | | | | | DE40D | DE60D | | |
| Rated speed 150[rpm] | Maximum speed 250[rpm] | Φ360 | | | | | | | | | DFA1D | DFA6D | |
| | | | | | | | | | | | | | |

L7 SERIES SYSTEM

Motor Designation

Applicable drive to motor

| Rated Speed (RPM) | Maximum Speed (RPM) | External Diameter of Motor(Φ) | Applicable Motor | Applicable Drive | encoder type |
|----------------------|------------------------|----------------------------------|------------------|------------------|---|
| 200 | 500 | Φ135 | DB03D | L7□A001□ | 20 bit single turn serial encoder (Biss/Absolute) |
| | | Φ135 | DB06D | L7□A002□ | |
| | | Φ135 | DB09D | L7□A004□ | |
| | 500 | Φ175 | DC06D | L7□A002□ | |
| | | Φ175 | DC12D | L7□A004□ | |
| | 400 | Φ175 | DC18D | L7□A008□ | |
| | 500 | Φ230 | DD12D | L7□A004□ | |
| | 400 | Φ230 | DD22D | L7□A008□ | |
| | 400 | Φ230 | DD34D | L7□A010□ | |
| | 300 | Φ290 | DE40D | L7□A010□ | |
| | 300 | Φ290 | DE60D | L7□A020□ | |
| 150 | 250 | Φ360 | DFA1G | L7□A020□ | |
| | | Φ360 | DFA6G | L7□A035□ | |

Appearances of Motor



Features of Direct Drive Motor

| Motor Designation | MDM-DB□□D□H | | | MDM-DC□□D□H | | |
|---------------------------------|---|---|----------|-------------|----------|----------|
| | 03 | 06 | 09 | 06 | 12 | 18 |
| Applicable Drive (L7□-A□□□□) | L7□A001□ | L7□A002□ | L7□A004□ | L7□A002□ | L7□A004□ | L7□A008□ |
| Flange Size | mm | Φ135 | | Φ175 | | |
| Rated Output | W | 63 | 126 | 188 | 126 | 251 |
| Rated Torque | N·m | 3 | 6 | 9 | 6 | 12 |
| Max Torque | N·m | 9 | 18 | 27 | 18 | 36 |
| Rated Current | Arms | 1.12 | 1.46 | 2.63 | 1.48 | 2.41 |
| Max Current | Arms | 3.36 | 4.38 | 7.89 | 4.44 | 7.23 |
| Rated Speed | rpm | 200 | | 200 | | |
| Max Speed | rpm | 500 | 500 | 500 | 500 | 400 |
| Constant of Torque | N·m/Arms | 2.76 | 4.25 | 3.57 | 4.18 | 5.13 |
| Inertia | $\text{kg}\cdot\text{m}^2 \times 10^{-4}$ | 5.74 | 8.67 | 11.5 | 27.32 | 38.9 |
| Rated Power Rate | kW/s | 15.68 | 42.35 | 70.43 | 13.18 | 52.71 |
| Angular acceleration | rad/s^2 | 191.2 | 141.6 | 127.7 | 455.03 | 323.9 |
| positioning accuracy | arc-sec | | | ± 15 | | |
| positioning repeatability | arc-sec | | | ± 1.3 | | |
| Axial run-out | mm | | | 0.015 | | |
| Radial run-out | mm | | | 0.03 | | |
| Allowed Moment Load | N | 1500 | | 3300 | | |
| Max. Instantaneous | N·m | 40 | | 70 | | |
| Encoder Type | 20-bit single turn serial encoder (Biss/Absolute) | | | | | |
| Weight (Approx.) | kg | 6.3 | 7.2 | 9.2 | 8.7 | 10.6 |
| Working Environment | Ambient Temp | operating : 0~40[°C] / storage : -20~60[°C] | | | | |
| | Ambient Humidity | 20~80[%] RH(avoid dew-condensation) | | | | |
| | Atmosphere | Avoid direct sunlight, No corrosive gas, Inflammable gas, Oil mist, or Dust | | | | |

* In case of allowable load inertia ratio, please apply within 30 times of rotator inertia

Speed-Torque Characteristics



L7S Series

L7N Series

S Series

F Series

PEGASUS Series

91

L7 SERIES SYSTEM

Features of Direct Drive Motor

| Motor Designation | MDM-DD□□D□H | | | MDM-DE□□D□H | | MDM-DF□□G□H | |
|---------------------------------|---|---|----------|-------------|------------|-------------|------------|
| | 12 | 22 | 34 | 40 | 60 | A1 | A6 |
| Applicable Drive (L7□-A□□□□) | L7□A004□ | L7□A008□ | L7□A010□ | L7□A010□ | L7□A020□ | L7□A020□ | L7□A035□ |
| Flange Size | mm | $\Phi 230$ | | | $\Phi 290$ | | $\Phi 360$ |
| Rated Output | W | 251 | 461 | 712 | 838 | 1,257 | 1,728 |
| Rated Torque | N·m | 12 | 22 | 34 | 40 | 60 | 110 |
| Max Torque | N·m | 36 | 66 | 102 | 120 | 180 | 330 |
| Rated Current | Arms | 2.58 | 3.33 | 5.72 | 5.3 | 8.33 | 9.48 |
| Max Current | Arms | 7.74 | 9.99 | 17.16 | 15.9 | 24.99 | 28.44 |
| Rated Speed | rpm | 200 | | | 200 | | 150 |
| Max Speed | rpm | 500 | 400 | 400 | 300 | 300 | 250 |
| Constant of Torque | N·m/Arms | 4.8 | 6.81 | 6.13 | 7.77 | 7.42 | 11.95 |
| Inertia | $\text{kg}\cdot\text{m}^2 \times 10^{-4}$ | 54.14 | 68.15 | 82.16 | 311.55 | 371.71 | 1410.2 |
| Rated Power Rate | kW/s | 26.6 | 71.02 | 140.7 | 51.36 | 96.68 | 85.9 |
| Angular acceleration | rad/s^2 | 450.9 | 309.6 | 241.5 | 778.35 | 619.1 | 1281.13 |
| positioning accuracy | arc-sec | ± 15 | | | | | |
| positioning repeatability | arc-sec | ± 1.3 | | | | | |
| Axial run-out | mm | 0.015 | | | | | |
| Radial run-out | mm | 0.03 | | | | | |
| Allowed Moment Load | N | 4000 | | 11000 | | 15000 | |
| Max. Instantaneous | N·m | 93 | | 250 | | 350 | |
| Encoder Type | | 20-bit single turn serial encoder (Biss/Absolute) | | | | | |
| Weight (Approx.) | kg | 17.3 | 19.6 | 21.9 | 28.2 | 35 | 54 |
| Working Environment | Ambient Temp | operating : 0~40[°C] / storage : -20~60[°C] | | | | | |
| | Ambient Humidity | 20~80[%] RH (avoid dew-condensation) | | | | | |
| | Atmosphere | Avoid direct sunlight, No corrosive gas, Inflammable gas, Oil mist, or Dust | | | | | |

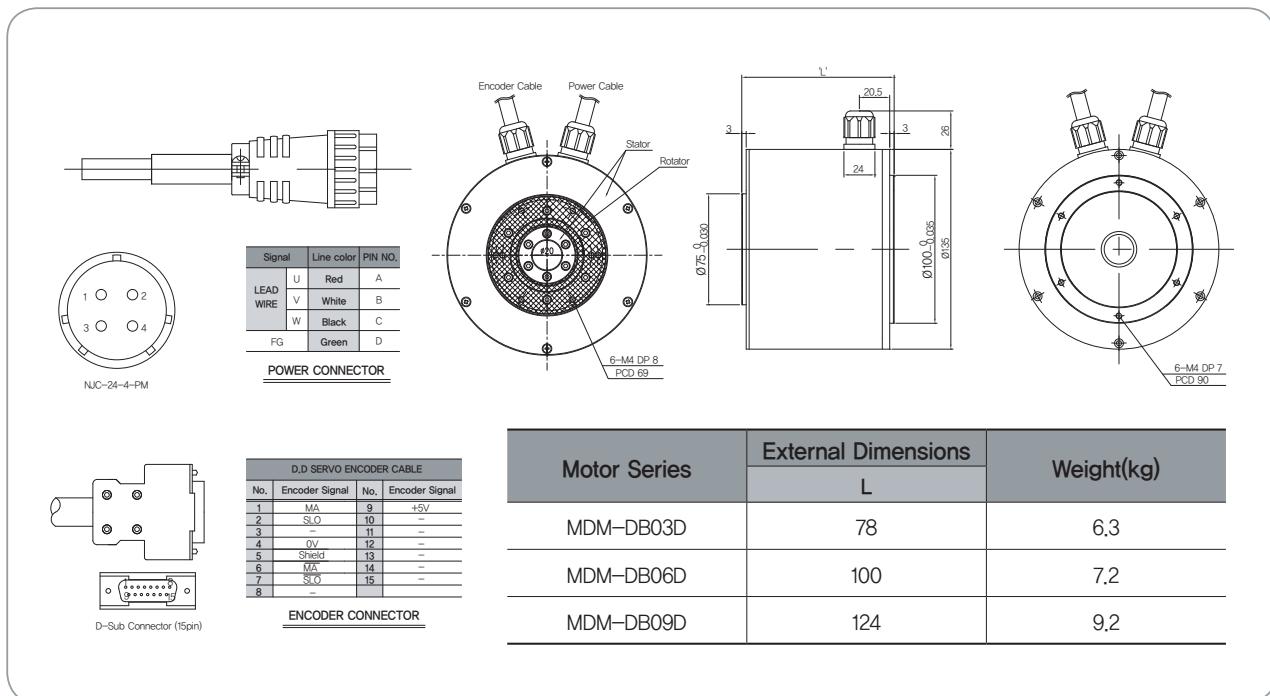
* In case of allowable load inertia ratio, please apply within 30 times of rotator inertia

Speed-Torque Characteristics

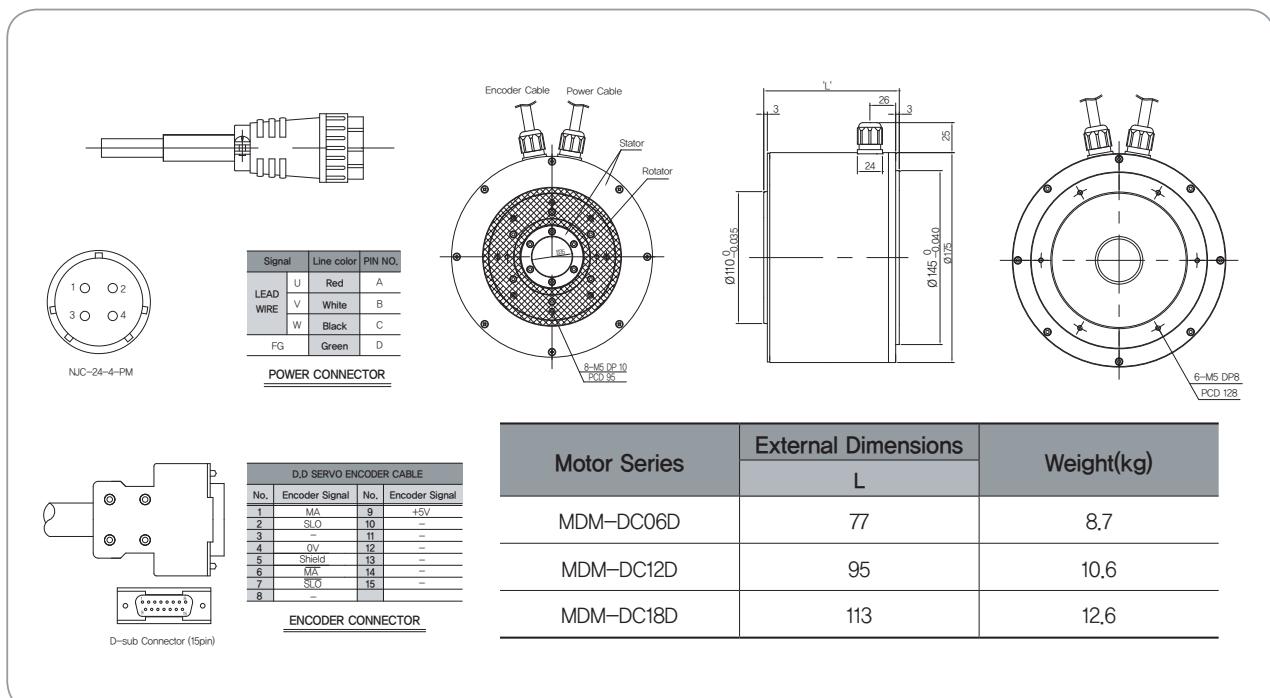


External Dimensions of Direct-Drive Rotary Motor

■ MDM-DB03D, MDM-DB06D, MDM-DB09D



■ MDM-DC06D, MDM-DC12D, MDM-DC18D



L7 SERIES SYSTEM

External Dimensions of Direct-Drive Rotary Motor

■ MDM-DD12D, MDM-DD22D, MDM-DD34D

POWER CONNECTOR

| Signal | Line color | PIN NO. |
|-----------|------------|---------|
| LEAD WIRE | U Red | A |
| V White | B | |
| W Black | C | |
| FG Green | D | |

ENCODER CONNECTOR

| D.D SERVO ENCODER CABLE | | | |
|-------------------------|----------------|-----|----------------|
| No. | Encoder Signal | No. | Encoder Signal |
| 1 | MA | 9 | +5V |
| 2 | SLO | 10 | - |
| 3 | - | 11 | - |
| 4 | 0V | 12 | - |
| 5 | Shield | 13 | - |
| 6 | MA | 14 | - |
| 7 | SLO | 15 | - |
| 8 | - | | |

External Dimensions

External Dimensions

External Dimensions

| Motor Series | External Dimensions | | Weight(kg) |
|--------------|---------------------|--|------------|
| | L | | |
| MDM-DD12D | 82.5 | | 17.3 |
| MDM-DD22D | 100.5 | | 19.6 |
| MDM-DD34D | 118.5 | | 21.9 |

■ MDM-DE40D, MDM-DE60D

POWER CONNECTOR

| Signal | Line color | PIN NO. |
|-----------|------------|---------|
| LEAD WIRE | U Red | A |
| V White | B | |
| W Black | C | |
| FG Green | D | |

ENCODER CONNECTOR

| D.D SERVO ENCODER CABLE | | | |
|-------------------------|----------------|-----|----------------|
| No. | Encoder Signal | No. | Encoder Signal |
| 1 | MA | 9 | +5V |
| 2 | SLO | 10 | - |
| 3 | - | 11 | - |
| 4 | 0V | 12 | - |
| 5 | Shield | 13 | - |
| 6 | MA | 14 | - |
| 7 | SLO | 15 | - |
| 8 | - | | |

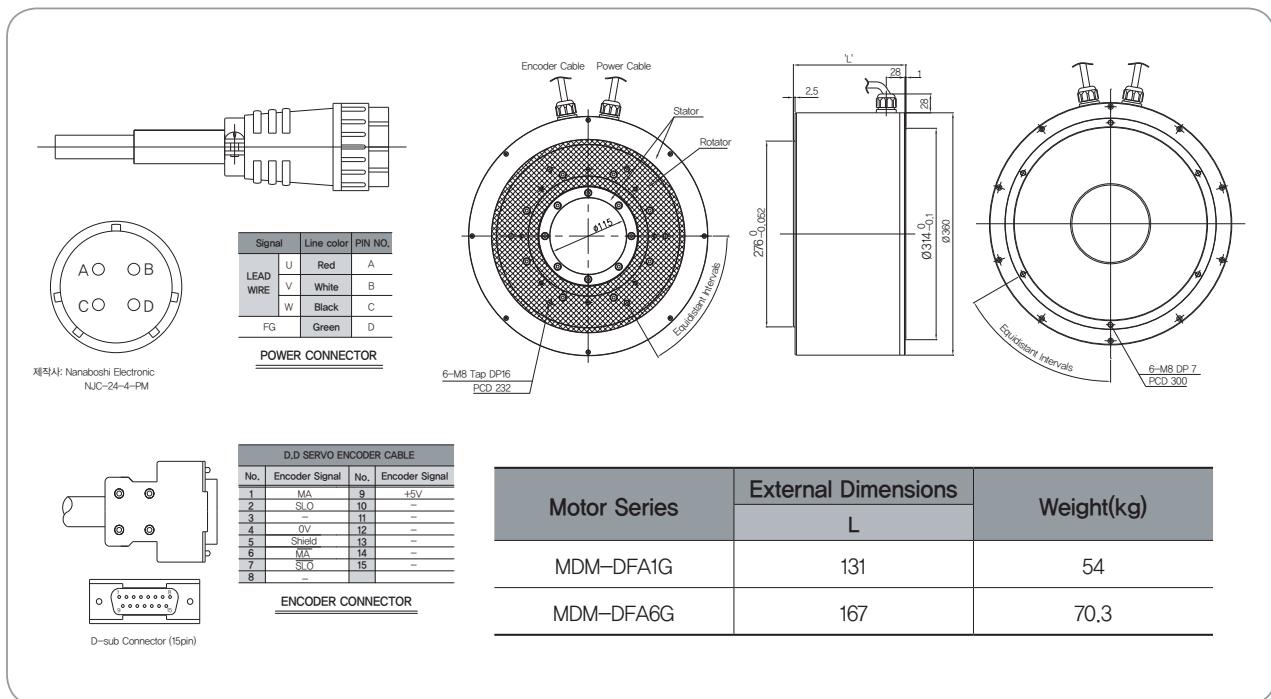
External Dimensions

External Dimensions

| Motor Series | External Dimensions | | Weight(kg) |
|--------------|---------------------|--|------------|
| | L | | |
| MDM-DE40D | 95.4 | | 28.2 |
| MDM-DE60D | 113.4 | | 35 |

External Dimensions of Direct-Drive Rotary Motor

■ MDM-DFA1G, MDM-DFA6G



L7S Series

L7N Series

L7NH Series L7P Series

S Series

F Series

MDM Series

Options

PEGASUS Series

Contents

■ Options

Servo motor options

- Signal cable _ 97
- Power cable _ 100

Servo drive options

- Signal cable _ 109
- Connector _ 110

Other options

- Braking resistance _ 112
- Noise Filter _ 114

Servo Motor Option

■ Signal Cable [Incremental]

| Type | Product Type | Model Name ^(Note) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|------------|--|------------------------------|-----------------------------------|--|--|---------|----------------|---------|----------------|---|---|---|---|---|---|----|---|---|---|----|---|---|---|----|---|---|---|----|-----|---|---|----|----|---|---|----|--------|---|---|--|--|---------|----------------|---------|----------------|---|---|---|---|---|---|---|---|---|---|----|---|---|---|----|---|---|---|----|---|---|---|----|---|---|----|----|-----|--|--|-------|--------|--|
| For Signal | Parallel Encoder Cable (Small Capacity) | APCS-E□□□AS | L7SA□□□A L7NHA□□□U L7PA□□□U | All Models of APM-SA APM-SB APM-SC APM-HB SERIES | <p style="text-align: center;">Motor Side Connector</p> <p style="text-align: center;">Drive Side Connector(CN2)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th>PIN No.</th> <th>Encoder Signal</th> <th>PIN No.</th> <th>Encoder Signal</th> </tr> <tr><td>1</td><td>A</td><td>9</td><td>V</td></tr> <tr><td>2</td><td>Ā</td><td>10</td><td>Ā</td></tr> <tr><td>3</td><td>B</td><td>11</td><td>W</td></tr> <tr><td>4</td><td>Ā</td><td>12</td><td>W</td></tr> <tr><td>5</td><td>Z</td><td>13</td><td>+5V</td></tr> <tr><td>6</td><td>Ā</td><td>14</td><td>0V</td></tr> <tr><td>7</td><td>U</td><td>15</td><td>SHIELD</td></tr> <tr><td>8</td><td>Ā</td><td></td><td></td></tr> </table> <p style="text-align: center;">(Motor Side Connector)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th>PIN No.</th> <th>Encoder Signal</th> <th>PIN No.</th> <th>Encoder Signal</th> </tr> <tr><td>1</td><td>W</td><td>8</td><td>Z</td></tr> <tr><td>2</td><td>Ā</td><td>9</td><td>Ā</td></tr> <tr><td>3</td><td>V</td><td>10</td><td>Ā</td></tr> <tr><td>4</td><td>Ā</td><td>11</td><td>B</td></tr> <tr><td>5</td><td>U</td><td>12</td><td>Ā</td></tr> <tr><td>6</td><td>Ā</td><td>13</td><td>A</td></tr> <tr><td>7</td><td>OV</td><td>14</td><td>+5V</td></tr> <tr><td></td><td></td><td>PLATE</td><td>SHIELD</td></tr> </table> <p style="text-align: center;">(Driver Side Connector)</p> | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | A | 9 | V | 2 | Ā | 10 | Ā | 3 | B | 11 | W | 4 | Ā | 12 | W | 5 | Z | 13 | +5V | 6 | Ā | 14 | 0V | 7 | U | 15 | SHIELD | 8 | Ā | | | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | W | 8 | Z | 2 | Ā | 9 | Ā | 3 | V | 10 | Ā | 4 | Ā | 11 | B | 5 | U | 12 | Ā | 6 | Ā | 13 | A | 7 | OV | 14 | +5V | | | PLATE | SHIELD | <ol style="list-style-type: none"> 1. Motor Side Connector <ol style="list-style-type: none"> a. Cap Spec.(15 Position) : 172163-1(AMP) b. Socket Spec. : 170361-1(AMP) 2. Driver Side Connector(CN2) <ol style="list-style-type: none"> a. Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone) b. Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone) 3. Cable Spec. : 7P×0.2SQ or 7P×AWG24 |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | A | 9 | V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Ā | 10 | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | B | 11 | W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | Ā | 12 | W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | Z | 13 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | Ā | 14 | 0V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | U | 15 | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | W | 8 | Z | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Ā | 9 | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | V | 10 | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | Ā | 11 | B | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | U | 12 | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | Ā | 13 | A | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | OV | 14 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| For Signal | Parallel Encoder Cable (Middle Capacity) | APCS-E□□□BS | L7S□□□A L7NH□□□U L7PA□□□U | All Models of APM-SE, SEP APM-SF, SFP APM-SG, SGP APM-LF APM-LG APM-HE SERIES | <p style="text-align: center;">Motor Side Connector</p> <p style="text-align: center;">Drive Side Connector(CN2)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th>PIN No.</th> <th>Encoder Signal</th> <th>PIN No.</th> <th>Encoder Signal</th> </tr> <tr><td>A</td><td>A</td><td>M</td><td>V</td></tr> <tr><td>B</td><td>Ā</td><td>N</td><td>Ā</td></tr> <tr><td>C</td><td>B</td><td>P</td><td>W</td></tr> <tr><td>D</td><td>Ā</td><td>R</td><td>Ā</td></tr> <tr><td>E</td><td>Z</td><td>H</td><td>+5V</td></tr> <tr><td>F</td><td>Ā</td><td>G</td><td>0V</td></tr> <tr><td>K</td><td>U</td><td>J</td><td>SHIELD</td></tr> <tr><td>L</td><td>Ā</td><td></td><td></td></tr> </table> <p style="text-align: center;">(Motor Side Connector)</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <th>PIN No.</th> <th>Encoder Signal</th> <th>PIN No.</th> <th>Encoder Signal</th> </tr> <tr><td>1</td><td>W</td><td>8</td><td>Z</td></tr> <tr><td>2</td><td>Ā</td><td>9</td><td>Ā</td></tr> <tr><td>3</td><td>V</td><td>10</td><td>B</td></tr> <tr><td>4</td><td>Ā</td><td>11</td><td>B</td></tr> <tr><td>5</td><td>U</td><td>12</td><td>Ā</td></tr> <tr><td>6</td><td>Ā</td><td>13</td><td>A</td></tr> <tr><td>7</td><td>OV</td><td>14</td><td>+5V</td></tr> <tr><td></td><td></td><td>PLATE</td><td>SHIELD</td></tr> </table> <p style="text-align: center;">(Driver Side Connector)</p> | PIN No. | Encoder Signal | PIN No. | Encoder Signal | A | A | M | V | B | Ā | N | Ā | C | B | P | W | D | Ā | R | Ā | E | Z | H | +5V | F | Ā | G | 0V | K | U | J | SHIELD | L | Ā | | | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | W | 8 | Z | 2 | Ā | 9 | Ā | 3 | V | 10 | B | 4 | Ā | 11 | B | 5 | U | 12 | Ā | 6 | Ā | 13 | A | 7 | OV | 14 | +5V | | | PLATE | SHIELD | <ol style="list-style-type: none"> 1. Motor Side Connector(MS : Military Standard) <ol style="list-style-type: none"> a. Plug Spec. : MS3108A20-29S 2. Drive Side Connector(CN2) <ol style="list-style-type: none"> a. Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone) b. Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone) 3. Cable Spec. : 7P×0.2SQ or 7P×AWG24 |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| A | A | M | V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| B | Ā | N | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| C | B | P | W | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| D | Ā | R | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| E | Z | H | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| F | Ā | G | 0V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| K | U | J | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| L | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | W | 8 | Z | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | Ā | 9 | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | V | 10 | B | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | Ā | 11 | B | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | U | 12 | Ā | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | Ā | 13 | A | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | OV | 14 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| General Cable(N) | N03 | N05 | N10 | N20 |
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

L7S Series

L7N Series

L7P Series

S Series

F Series

MDM Series

PEGASUS Series

Options

L7 SERIES SYSTEM

Servo Motor Option

■ Signal Cable [Serial]

| Type | Product Type | Model Name ^(Note) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|------------|---|------------------------------|---|---|---|---------|----------------|---------|----------------|---|----|---|---|---|----|---|---|---|-----|----|---|---|-----|----|---|---|-------|----|-----|---|-------|----|----|---|-----|----|--------|---|----|-------|--------|---------|----------------|---------|----------------|---|---|---|---|---|---|---|---|---|----|----|---|---|----|----|---|---|-----|----|---|---|-----|----|---|---|----|----|-----|---|-------|--------|---|
| For Signal | S Series Motor S-turn Encoder Cable (Small Capacity) | APCS-E□□□CS | L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | All Models of APM-SA APM-SB APM-SC SERIES | <p>1. Motor Side Connector a. Cap Spec.(9 Position) : 172161-1(AMP) b. Socket Spec. : 170361-1(AMP)</p> <p>2. Drive Side Connector(CN2) a. Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone) b. Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)</p> <p>3. Cable Spec. : 3P×0.2SQ or 3P×24AWG</p> <table border="1"> <tr> <td>PIN No.</td> <td>Encoder Signal</td> <td>PIN No.</td> <td>Encoder Signal</td> </tr> <tr> <td>1</td> <td>MA</td> <td>8</td> <td>-</td> </tr> <tr> <td>2</td> <td>MA</td> <td>9</td> <td>-</td> </tr> <tr> <td>3</td> <td>SLO</td> <td>10</td> <td>-</td> </tr> <tr> <td>4</td> <td>SLO</td> <td>11</td> <td>-</td> </tr> <tr> <td>5</td> <td>-</td> <td>12</td> <td>-</td> </tr> <tr> <td>6</td> <td>-</td> <td>13</td> <td>-</td> </tr> <tr> <td>7</td> <td>+5V</td> <td>14</td> <td>+5V</td> </tr> <tr> <td>8</td> <td>0V</td> <td>PLATE</td> <td>SHIELD</td> </tr> </table> <p>(Motor Side Connector) (Drive Side Connector)</p> | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | MA | 8 | - | 2 | MA | 9 | - | 3 | SLO | 10 | - | 4 | SLO | 11 | - | 5 | - | 12 | - | 6 | - | 13 | - | 7 | +5V | 14 | +5V | 8 | 0V | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | MA | 8 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | MA | 9 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | SLO | 10 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | SLO | 11 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | - | 12 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | - | 13 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | +5V | 14 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | 0V | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| For Signal | S Series Motor M-turn Encoder Cable (Small Capacity) | APCS-E□□□CS1 | L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | All Models of APM-SA APM-SB APM-SC SERIES | <p>1. Motor Side Connector a. CAP Spec.(9 Position) : 172161-1(AMP) b. Socket Spec. : 170361-1(AMP)</p> <p>2. Drive Side Connector(CN2) a. Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone) b. Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)</p> <p>3. Cable Spec. : 4P×0.2SQ or 4P×24AWG</p> <p>4. Battery Connector Spec. : 5267-02A(MOLEX)</p> <table border="1"> <tr> <td>PIN No.</td> <td>Encoder Signal</td> <td>PIN No.</td> <td>Encoder Signal</td> </tr> <tr> <td>1</td> <td>MA</td> <td>8</td> <td>-</td> </tr> <tr> <td>2</td> <td>MA</td> <td>9</td> <td>-</td> </tr> <tr> <td>3</td> <td>SL</td> <td>10</td> <td>-</td> </tr> <tr> <td>4</td> <td>SL</td> <td>11</td> <td>-</td> </tr> <tr> <td>5</td> <td>VDD B</td> <td>12</td> <td>-</td> </tr> <tr> <td>6</td> <td>GND B</td> <td>13</td> <td>-</td> </tr> <tr> <td>7</td> <td>+5V</td> <td>14</td> <td>+5V</td> </tr> <tr> <td>8</td> <td>0V</td> <td>PLATE</td> <td>SHIELD</td> </tr> </table> <p>(Motor Side Connector) (Drive Side Connector)</p> <table border="1"> <tr> <td>PIN No.</td> <td>Encoder Signal</td> <td>PIN No.</td> <td>Encoder Signal</td> </tr> <tr> <td>1</td> <td>-</td> <td>8</td> <td>-</td> </tr> <tr> <td>2</td> <td>-</td> <td>9</td> <td>-</td> </tr> <tr> <td>3</td> <td>MA</td> <td>10</td> <td>-</td> </tr> <tr> <td>4</td> <td>MA</td> <td>11</td> <td>-</td> </tr> <tr> <td>5</td> <td>SLO</td> <td>12</td> <td>-</td> </tr> <tr> <td>6</td> <td>SLO</td> <td>13</td> <td>-</td> </tr> <tr> <td>7</td> <td>0V</td> <td>14</td> <td>+5V</td> </tr> <tr> <td>8</td> <td>PLATE</td> <td>SHIELD</td> <td>-</td> </tr> </table> <p>(Battery Connector)</p> | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | MA | 8 | - | 2 | MA | 9 | - | 3 | SL | 10 | - | 4 | SL | 11 | - | 5 | VDD B | 12 | - | 6 | GND B | 13 | - | 7 | +5V | 14 | +5V | 8 | 0V | PLATE | SHIELD | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | - | 8 | - | 2 | - | 9 | - | 3 | MA | 10 | - | 4 | MA | 11 | - | 5 | SLO | 12 | - | 6 | SLO | 13 | - | 7 | 0V | 14 | +5V | 8 | PLATE | SHIELD | - |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | MA | 8 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | MA | 9 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | SL | 10 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | SL | 11 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | VDD B | 12 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | GND B | 13 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | +5V | 14 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | 0V | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | - | 8 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | - | 9 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | MA | 10 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | MA | 11 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | SLO | 12 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | SLO | 13 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | 0V | 14 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | PLATE | SHIELD | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| For Signal | S/F Series Motor S-turn Encoder Cable (Middle Capacity) | APCS-E□□□DS | L7S□□□B L7NA□□□B L7NH□□□U L7PA□□□U | All Models of APM-SE, FE, SEP, FEP APM-SF, FF SFP, FFP APM-SG, FG SGP, FGP APM-LF APM-LG SERIES | <p>1. Motor Side Connector(MS : Military Standard) a. Plug Spec. : MS3108A20-29S</p> <p>2. Drive Side Connector(CN2) a. Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone) b. Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)</p> <p>3. Cable Spec. : 3P×0.2SQ or 3P×24AWG</p> <table border="1"> <tr> <td>PIN No.</td> <td>Encoder Signal</td> <td>PIN No.</td> <td>Encoder Signal</td> </tr> <tr> <td>A</td> <td>MA</td> <td>M</td> <td>-</td> </tr> <tr> <td>B</td> <td>MA</td> <td>N</td> <td>-</td> </tr> <tr> <td>C</td> <td>SLO</td> <td>P</td> <td>-</td> </tr> <tr> <td>D</td> <td>SLO</td> <td>R</td> <td>-</td> </tr> <tr> <td>E</td> <td>-</td> <td>H</td> <td>+5V</td> </tr> <tr> <td>F</td> <td>-</td> <td>G</td> <td>0V</td> </tr> <tr> <td>K</td> <td>-</td> <td>J</td> <td>SHIELD</td> </tr> <tr> <td>L</td> <td>-</td> <td>PLATE</td> <td>SHIELD</td> </tr> </table> <p>(Motor Side Connector) (Drive Side Connector)</p> | PIN No. | Encoder Signal | PIN No. | Encoder Signal | A | MA | M | - | B | MA | N | - | C | SLO | P | - | D | SLO | R | - | E | - | H | +5V | F | - | G | 0V | K | - | J | SHIELD | L | - | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| A | MA | M | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| B | MA | N | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| C | SLO | P | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| D | SLO | R | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| E | - | H | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| F | - | G | 0V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| K | - | J | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| L | - | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| General Cable(N) | N03 | N05 | N10 | N20 |
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

Servo Motor Option

■ Signal Cable [Serial]

| Type | Product Type | Model Name ^(Note) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|------------|--|------------------------------|--|---|--|---------|----------------|---------|----------------|---|----|---|---|---|-----|---|---|---|-------|---|---|---|-----|---|---|---|--------|---|-----|---|-------|---|----|---|-----|---|--------|---|-------|---|---|---------|----------------|---------|----------------|---------|----------------|---------|----------------|---|---|---|---|---|----|----|---|---|----|----|---|---|-----|----|---|---|-----|----|---|---|-----|----|-----|-------|--------|-------|--------|-------|--------|-------|--------|
| For Signal | S/F Series Motor M-turn Encoder Cable (Middle Capacity) | APCS-E□□□DS1 | L7S□□□□B L7NA□□□B L7NH□□□U L7PA□□□U | All Models of APM-SE, FE SEP,FEP APM-SF, FF SFP,FPP APM-SG, FG, SGP,FGP APM-LF APM-LG SERIES | <p>Motor Side Connector</p> <table border="1"> <tr><td>PIN No.</td><td>Encoder Signal</td><td>PIN No.</td><td>Encoder Signal</td></tr> <tr><td>A</td><td>MA</td><td>M</td><td>-</td></tr> <tr><td>B</td><td>MA</td><td>N</td><td>-</td></tr> <tr><td>C</td><td>SLO</td><td>P</td><td>-</td></tr> <tr><td>D</td><td>SLO</td><td>R</td><td>-</td></tr> <tr><td>E</td><td>VOD_B</td><td>H</td><td>+5V</td></tr> <tr><td>F</td><td>GND_B</td><td>G</td><td>0V</td></tr> <tr><td>G</td><td>-</td><td>J</td><td>SHIELD</td></tr> <tr><td>L</td><td>-</td><td>-</td><td>-</td></tr> </table> <p>Drive Side Connector(CN2)</p> <table border="1"> <tr><td>PIN No.</td><td>Encoder Signal</td><td>PIN No.</td><td>Encoder Signal</td></tr> <tr><td>1</td><td>-</td><td>8</td><td>-</td></tr> <tr><td>2</td><td>-</td><td>9</td><td>-</td></tr> <tr><td>3</td><td>MA</td><td>10</td><td>-</td></tr> <tr><td>4</td><td>MA</td><td>11</td><td>-</td></tr> <tr><td>5</td><td>SLO</td><td>12</td><td>-</td></tr> <tr><td>6</td><td>SLO</td><td>13</td><td>-</td></tr> <tr><td>7</td><td>OV</td><td>14</td><td>+5V</td></tr> <tr><td>PLATE</td><td>SHIELD</td><td>PLATE</td><td>SHIELD</td></tr> </table> <p>(Motor Side Connector)</p> <p>(Driver Side Connector)</p> <p>(Battery Connector)</p> <ol style="list-style-type: none"> 1. Motor Side Connector(MS : Military Standard) <ol style="list-style-type: none"> a. Plug Spec. : MS3108A20-29S 2. Drive Side Connector(CN2) <ol style="list-style-type: none"> a. Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone) b. Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone) 3. Cable Spec. : 4P×0.25Q or 4P×24AWG 4. Battery Connector Spec. : 5267-02A(MOLEX) | PIN No. | Encoder Signal | PIN No. | Encoder Signal | A | MA | M | - | B | MA | N | - | C | SLO | P | - | D | SLO | R | - | E | VOD_B | H | +5V | F | GND_B | G | 0V | G | - | J | SHIELD | L | - | - | - | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | - | 8 | - | 2 | - | 9 | - | 3 | MA | 10 | - | 4 | MA | 11 | - | 5 | SLO | 12 | - | 6 | SLO | 13 | - | 7 | OV | 14 | +5V | PLATE | SHIELD | PLATE | SHIELD | | | | |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| A | MA | M | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| B | MA | N | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| C | SLO | P | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| D | SLO | R | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| E | VOD_B | H | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| F | GND_B | G | 0V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| G | - | J | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| L | - | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | - | 8 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | - | 9 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | MA | 10 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | MA | 11 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | SLO | 12 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | SLO | 13 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | OV | 14 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PLATE | SHIELD | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| For Signal | F Series Motor S-turn Encoder Cable (Small Capacity) | APCS-E□□□ES-□ | L7SA□□□B L7NA□□□B L7NH□□□U L7PA□□□U | All Models of APM-FAL APM-FB, FBL APM-FC, FCL SERIES | <p>Motor Side Connector</p> <table border="1"> <tr><td>PIN No.</td><td>Encoder Signal</td><td>PIN No.</td><td>Encoder Signal</td></tr> <tr><td>1</td><td>MA</td><td>8</td><td>-</td></tr> <tr><td>2</td><td>SLO</td><td>9</td><td>-</td></tr> <tr><td>3</td><td>-</td><td>-</td><td>-</td></tr> <tr><td>4</td><td>OV</td><td>-</td><td>-</td></tr> <tr><td>5</td><td>SHIELD</td><td>-</td><td>-</td></tr> <tr><td>6</td><td>MA</td><td>-</td><td>-</td></tr> <tr><td>7</td><td>SLO</td><td>-</td><td>-</td></tr> <tr><td>8</td><td>-</td><td>-</td><td>-</td></tr> <tr><td>9</td><td>+5V</td><td>-</td><td>-</td></tr> </table> <p>Drive Side Connector(CN2)</p> <table border="1"> <tr><td>PIN No.</td><td>Encoder Signal</td><td>PIN No.</td><td>Encoder Signal</td></tr> <tr><td>1</td><td>-</td><td>8</td><td>-</td></tr> <tr><td>2</td><td>-</td><td>9</td><td>-</td></tr> <tr><td>3</td><td>MA</td><td>10</td><td>-</td></tr> <tr><td>4</td><td>MA</td><td>11</td><td>-</td></tr> <tr><td>5</td><td>SLO</td><td>12</td><td>-</td></tr> <tr><td>6</td><td>SLO</td><td>13</td><td>-</td></tr> <tr><td>7</td><td>OV</td><td>14</td><td>+5V</td></tr> <tr><td>PLATE</td><td>SHIELD</td><td>PLATE</td><td>SHIELD</td></tr> </table> <p>(Motor Side Connector)</p> <p>(Driver Side Connector)</p> <p>Tyco Connector</p> <ol style="list-style-type: none"> 1. Motor Side Connector <ol style="list-style-type: none"> a. Cap Spec. : 2201825-1(Tyco) b. Socket Spec. : 2174065-4(Tyco) 2. Drive Side Connector(CN2) <ol style="list-style-type: none"> a. Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone) b. Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone) 3. Cable Spec. : 3P×0.25Q or 3P×24AWG | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | MA | 8 | - | 2 | SLO | 9 | - | 3 | - | - | - | 4 | OV | - | - | 5 | SHIELD | - | - | 6 | MA | - | - | 7 | SLO | - | - | 8 | - | - | - | 9 | +5V | - | - | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | - | 8 | - | 2 | - | 9 | - | 3 | MA | 10 | - | 4 | MA | 11 | - | 5 | SLO | 12 | - | 6 | SLO | 13 | - | 7 | OV | 14 | +5V | PLATE | SHIELD | PLATE | SHIELD |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | MA | 8 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | SLO | 9 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | - | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | OV | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | SHIELD | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | MA | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | SLO | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | - | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 9 | +5V | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | - | 8 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | - | 9 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | MA | 10 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | MA | 11 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | SLO | 12 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | SLO | 13 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | OV | 14 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PLATE | SHIELD | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| For Signal | F Series Motor M-turn Encoder Cable (Small Capacity) | APCS-E□□□ES1-□ | L7SA□□□B L7NA□□□B L7NH□□□U L7PA□□□U | All Models of APM-FAL APM-FB, FBL APM-FC, FCL SERIES | <p>Motor Side Connector</p> <table border="1"> <tr><td>PIN No.</td><td>Encoder Signal</td><td>PIN No.</td><td>Encoder Signal</td></tr> <tr><td>1</td><td>MA</td><td>8</td><td>-</td></tr> <tr><td>2</td><td>SLO</td><td>9</td><td>-</td></tr> <tr><td>3</td><td>GND_B</td><td>-</td><td>-</td></tr> <tr><td>4</td><td>0V</td><td>-</td><td>-</td></tr> <tr><td>5</td><td>SHIELD</td><td>-</td><td>-</td></tr> <tr><td>6</td><td>MA</td><td>-</td><td>-</td></tr> <tr><td>7</td><td>SLO</td><td>-</td><td>-</td></tr> <tr><td>8</td><td>VOD_B</td><td>-</td><td>-</td></tr> <tr><td>9</td><td>+5V</td><td>-</td><td>-</td></tr> </table> <p>Drive Side Connector(CN2)</p> <table border="1"> <tr><td>PIN No.</td><td>Encoder Signal</td><td>PIN No.</td><td>Encoder Signal</td></tr> <tr><td>1</td><td>-</td><td>8</td><td>-</td></tr> <tr><td>2</td><td>-</td><td>9</td><td>-</td></tr> <tr><td>3</td><td>MA</td><td>10</td><td>-</td></tr> <tr><td>4</td><td>MA</td><td>11</td><td>-</td></tr> <tr><td>5</td><td>SLO</td><td>12</td><td>-</td></tr> <tr><td>6</td><td>SLO</td><td>13</td><td>-</td></tr> <tr><td>7</td><td>OV</td><td>14</td><td>+5V</td></tr> <tr><td>PLATE</td><td>SHIELD</td><td>PLATE</td><td>SHIELD</td></tr> </table> <p>(Motor Side Connector)</p> <p>(Driver Side Connector)</p> <p>(Battery Connector)</p> <p>Tyco Connector</p> <ol style="list-style-type: none"> 1. Motor Side Connector <ol style="list-style-type: none"> a. Cap Spec. : 2201825-1(Tyco) b. Socket Spec. : 2174065-4(Tyco) 2. Drive Side Connector(CN2) <ol style="list-style-type: none"> a. Cap Spec. : 10314-52A0-008(3M) or SM-14J(Suntone) b. Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone) 3. Cable Spec. : 4P×0.25Q or 4P×24AWG 4. Battery Connector Spec. : 5267-02A(MOLEX) | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | MA | 8 | - | 2 | SLO | 9 | - | 3 | GND_B | - | - | 4 | 0V | - | - | 5 | SHIELD | - | - | 6 | MA | - | - | 7 | SLO | - | - | 8 | VOD_B | - | - | 9 | +5V | - | - | PIN No. | Encoder Signal | PIN No. | Encoder Signal | 1 | - | 8 | - | 2 | - | 9 | - | 3 | MA | 10 | - | 4 | MA | 11 | - | 5 | SLO | 12 | - | 6 | SLO | 13 | - | 7 | OV | 14 | +5V | PLATE | SHIELD | PLATE | SHIELD |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | MA | 8 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | SLO | 9 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | GND_B | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | 0V | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | SHIELD | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | MA | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | SLO | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | VOD_B | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 9 | +5V | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PIN No. | Encoder Signal | PIN No. | Encoder Signal | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | - | 8 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | - | 9 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | MA | 10 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | MA | 11 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | SLO | 12 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | SLO | 13 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | OV | 14 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PLATE | SHIELD | PLATE | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

Note2) In case of □ marked product, the connector can draw in a direction of Front(load) / Rear(half load).(Front Type : No mark, Rear Type : -R)

Note3) In case of FAL Type, the connector can draw in a direction of only front

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| General Cable(N) | N03 | N05 | N10 | N20 |
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

L7S Series

L7N Series

S Series

F Series

PEGASUS Series

L7 SERIES SYSTEM

Servo Motor Option

■ Power Cable [200V]

| Type | Product Type | Model Name ^(Note1) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | |
|-----------|---|-------------------------------|---|---|---|---------|--------|---|-----|---|-----|---|---|---|--------|
| For Power | S Series Power Cable (Small Capacity) | APCS-P□□□GS | L7SA□□□A L7NHA□□□U L7PA□□□U | All Models of APM-SA APM-SB APM-SC APM-HB SERIES | <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>1</td> <td>U</td> </tr> <tr> <td>2</td> <td>V</td> </tr> <tr> <td>3</td> <td>W</td> </tr> <tr> <td>4</td> <td>Ground</td> </tr> </table> <p>1. Motor Side Connector a. Cap Spec.(4 Position) : 172159-1(AMP) b. Socket Spec. : 170362-1(AMP)</p> <p>2. Drive Side Connector(U, V, W, FG) a. U, V, W Pin Spec. : 1512 b. FG Pin Spec. : 1.5x4(Ring Terminal)</p> <p>3. Cable Spec. : 4C×0.75SQ or 4C×18AWG</p> | PIN No. | Signal | 1 | U | 2 | V | 3 | W | 4 | Ground |
| PIN No. | Signal | | | | | | | | | | | | | | |
| 1 | U | | | | | | | | | | | | | | |
| 2 | V | | | | | | | | | | | | | | |
| 3 | W | | | | | | | | | | | | | | |
| 4 | Ground | | | | | | | | | | | | | | |
| For Power | S Series Brake Cable (Small Capacity) | APCS-P□□□KB | L7SA□□□A L7NHA□□□U L7PA□□□U | All Models of APM-SA APM-SB APM-SC APM-HB SERIES | <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>1</td> <td>BK+</td> </tr> <tr> <td>2</td> <td>BK-</td> </tr> </table> <p>1. Motor Side Connector a. Cap Spec.(2 Position) : 172157-1(AMP) b. Socket Spec. : 170362-1(AMP)</p> <p>2. Drive Side Connector a. Connecting terminal Spec. : 1.5x3(Ring Terminal)</p> <p>3. Cable Spec. : 2C×0.75SQ or 2C×18AWG</p> | PIN No. | Signal | 1 | BK+ | 2 | BK- | | | | |
| PIN No. | Signal | | | | | | | | | | | | | | |
| 1 | BK+ | | | | | | | | | | | | | | |
| 2 | BK- | | | | | | | | | | | | | | |
| For Power | F Series Power Cable (Small Capacity) | APCS-P□□□FS-□ | L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | All Models of APM-FB APM-FC SERIES | <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>1</td> <td>W</td> </tr> <tr> <td>2</td> <td>V</td> </tr> <tr> <td>3</td> <td>U</td> </tr> <tr> <td>4</td> <td>Ground</td> </tr> </table> <p>1. Motor Side Connector a. Plug Spec. : KN5FT04SJ1(JAE) b. Socket Spec. : ST-KN-S-C1B-3500(JAE)</p> <p>2. Drive Side Connector(U, V, W, FG) a. U, V, W Pin Spec. : 1512 b. FG Pin Spec. : 1.5x4(Ring Terminal)</p> <p>3. Cable Spec. : 4C×0.75SQ or 4C×18AWG</p> | PIN No. | Signal | 1 | W | 2 | V | 3 | U | 4 | Ground |
| PIN No. | Signal | | | | | | | | | | | | | | |
| 1 | W | | | | | | | | | | | | | | |
| 2 | V | | | | | | | | | | | | | | |
| 3 | U | | | | | | | | | | | | | | |
| 4 | Ground | | | | | | | | | | | | | | |

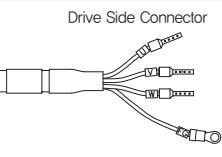
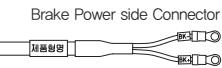
Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

Note2) In case of □ marked product, the connector can draw in a direction of Front(load) / Rear(half load).
(Front Type : No mark, Rear Type : -R)

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| General Cable(N) | N03 | N05 | N10 | N20 |
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

Servo Motor Option

■ Power Cable [200V]

| Type | Product Type | Model Name ^(Note) | Applicable Drive | Applicable Motor | Specifications |
|-----------|---|------------------------------|---|--|---|
| For Power | L Series Power Cable (Small Capacity) | APCS-P□□□LS-□ | L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | All Models of APMC-FAL APMC-FBL APMC-FCL SERIES | <p>Motor Side Connector</p>  <p>Drive Side Connector</p>  <p>1. Motor Side Connector</p> <ol style="list-style-type: none"> Plug Spec. : SM-JN8FT04(Suntone) Socket Spec. : SMS-201(Suntone) <p>2. Drive Side Connector (U,V,W,FG)</p> <ol style="list-style-type: none"> U, V, W Pin Spec. : 1512(Ferrule) FG Pin Spec. : 1.5x4 (Ring Terminal) <p>3. Cable Spec. : 4Cx0.75SQ or 4Cx18AWG</p> <p>4. In case of FAL products, Please install Power Cable first before connecting Encoder Cable.</p> |
| For Power | Brake Cable for Flat Motor (Small Capacity) | APCS-B□□□QS-□ | L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | All Models of APM-FAL APM-FB, FBL APM-FC, FCL SERIES | <p>Motor Side Connector</p>  <p>Brake Power side Connector</p>  <p>1. Motor Side Connector</p> <ol style="list-style-type: none"> Plug Spec. : KN5FT02SJ1 Socket Spec. : ST-KN-S-C1B-3500 <p>2. Drive Side Connector</p> <ol style="list-style-type: none"> Connecting terminal Spec. : 1,5x3(Ring Terminal) <p>3. Cable Spec. : 2C×0.5SQ or 2C×20AWG</p> |
| For Power | Power Cable (Middle Capacity) | APCS-P□□□HS | L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | All Models of APM-SE APM-FE APM-HE SERIES | <p>Motor Side Connector</p>  <p>Drive Side Connector</p>  <p>1. Motor Side Connector</p> <ol style="list-style-type: none"> Plug Spec. : MS3108A20-4S <p>2. Drive Side Connector</p> <ol style="list-style-type: none"> Connecting terminal Spec. : 22x6(Ring Terminal) <p>3. Cable Spec. : 4C×25SQ or 4C×14AWG</p> |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

Note2) In case of □ marked product, the connector can draw in a direction of Front(load) / Rear(half load).

(Front Type : No mark, Rear Type : -R)

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| General Cable(N) | N03 | N05 | N10 | N20 |
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

L7 SERIES SYSTEM

Servo Motor Option

■ Power Cable [200V]

| Type | Product Type | Model Name (Note) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | | | | | |
|-----------|-------------------------------|-------------------|---|--|---|---------|--------|---|---|---|---|---|---|---|--------|---|-----|---|-----|
| For Power | Power Cable (Brake Type) | APCS-P□□□NB | L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | All Models of APM-SE APM-FE SERIES | <p>Motor Side Connector</p> <p>Drive Side Connector</p> <p>Brake Power side Connector</p> <table border="1"> <tr> <th>PIN No.</th> <th>Signal</th> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> <tr> <td>E</td> <td>BK+</td> </tr> <tr> <td>F</td> <td>BK-</td> </tr> </table> <ol style="list-style-type: none"> 1. Motor Side Connector(MS : Military Standard) <ol style="list-style-type: none"> a. Plug Spec. : MS3108A20-15S 2. Drive Side Connector <ol style="list-style-type: none"> a. U, V, W Pin Spec. : 2512 b. Cable Spec. : 4C×2.5SQ or 4C×14AWG c. FG Pin Spec. : 2.5×4(Ring Terminal) 3. Brake Power side Connector <ol style="list-style-type: none"> a. BK Pin Spec. : 1.5×3(Ring Terminal) b. Cable Spec. : 2C×0.75SQ or 2C×18AWG | PIN No. | Signal | A | U | B | V | C | W | D | Ground | E | BK+ | F | BK- |
| PIN No. | Signal | | | | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | | | | |
| E | BK+ | | | | | | | | | | | | | | | | | | |
| F | BK- | | | | | | | | | | | | | | | | | | |
| For Power | Power Cable (Middle Capacity) | APCS-P□□□IS | L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | APM-SF30A SF22D, LF35D SF20G, LF30G SF12M, SF20M LF30M, SG22D LG35D, SG20G LG30G, SG12M SG20M, LG30M FF30A, FF22D FF35D, FF20G FF30G, FF12M FF20M, FF30M FG22D, FG35D FG20G, FG30G FG12M, FG20M FG30M | <p>Motor Side Connector</p> <p>Drive Side Connector</p> <table border="1"> <tr> <th>PIN No.</th> <th>Signal</th> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> <ol style="list-style-type: none"> 1. Motor Side Connector <ol style="list-style-type: none"> a. Plug Spec. : MS3108A22-22S 2. Drive Side Connector <ol style="list-style-type: none"> a. U, V, W Pin Spec. : 2512 b. FG Pin Spec. : 2.5×4(Ring Terminal) 3. Cable Spec. : 4C×2.5SQ or 4C×14AWG | PIN No. | Signal | A | U | B | V | C | W | D | Ground | | | | |
| PIN No. | Signal | | | | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | | | | |
| For Power | Power Cable (Brake Type) | APCS-P□□□PB | L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | APM-SF30A SF22D, LF35D SF20G, LF30G SF12M, SF20M LF30M, FF30A FF22D, FF35D FF20G, FF30G FF12M, FF20M FF30M | <p>Motor Side Connector</p> <p>Drive Side Connector</p> <p>Brake Power side Connector</p> <table border="1"> <tr> <th>PIN No.</th> <th>Signal</th> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> <tr> <td>E</td> <td>BK+</td> </tr> <tr> <td>F</td> <td>BK-</td> </tr> </table> <ol style="list-style-type: none"> 1. Motor Side Connector(MS : Military Standard) <ol style="list-style-type: none"> a. PLUG Spec. : MS3108A24-10S 2. Drive Side Connector <ol style="list-style-type: none"> a. U, V, W Pin Spec. : 2512 b. Cable Spec. : 4C×2.5SQ or 4C×14AWG c. FG Pin Spec. : 2.5×4(Ring Terminal) 3. Brake Power side Connector <ol style="list-style-type: none"> a. BK Pin Spec. : 1.5×3(Ring Terminal) b. Cable Spec. : 2C×0.75S or 2C×18AWG | PIN No. | Signal | A | U | B | V | C | W | D | Ground | E | BK+ | F | BK- |
| PIN No. | Signal | | | | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | | | | |
| E | BK+ | | | | | | | | | | | | | | | | | | |
| F | BK- | | | | | | | | | | | | | | | | | | |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| General Cable(N) | N03 | N05 | N10 | N20 |
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

Servo Motor Option

■ Power Cable [200V]

| Type | Product Type | Model Name ^(Note) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | |
|-----------|-------------------------------|------------------------------|---|--|--|---------|--------|---|---|---|---|---|---|---|--------|
| For Power | Power Cable (Middle Capacity) | APCS-P□□□JS | L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | APM-SF50A SF55D, SF75D SF44G, SF60G SF44M, SG55D SG75D, SG44G SG60G, SG44M FF50A, FF55D FF75D, FF44G FF60G, FF44M FG55D, FG75D FG44G, FG60G FG44M | <p>Motor Side Connector</p> <p>Drive Side Connector</p> <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> <ol style="list-style-type: none"> 1. Motor Side Connector(MS : Military Standard) <ol style="list-style-type: none"> a. Plug Spec. : MS3108A22-22S 2. Drive Side Connector <ol style="list-style-type: none"> a. Connecting terminal Spec. : 6×5(Ring Terminal) 3. Cable Spec. : 4C×6SQ or 4C×10AWG | PIN No. | Signal | A | U | B | V | C | W | D | Ground |
| PIN No. | Signal | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | |
| For Power | Power Cable (Brake Type) | APCS-P□□□LB | L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | APM-SF50A SF55D, SF75D SF44G, SF60G SF44M, FF50A FF50D, FF75D FF44G, FF60G FF40M | <p>Motor Side Connector</p> <p>Drive Side Connector</p> <p>Brake Power side Connector</p> <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> <ol style="list-style-type: none"> 1. Motor Side Connector(MS : Military Standard) <ol style="list-style-type: none"> a. Plug Spec. : MS3108A24-10S 2. Drive Side Connector <ol style="list-style-type: none"> a. Connecting terminal Spec. : 6×5(Ring Terminal) b. 4CX6SQ or 4CX10AWG 3. Brake Power side Connector <ol style="list-style-type: none"> a. Connecting terminal Spec. : 1.5×3(Ring Terminal) b. Cable Spec. : 2C×0.75SQ or 2C×18AWG | PIN No. | Signal | A | U | B | V | C | W | D | Ground |
| PIN No. | Signal | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | |
| For Power | Power Cable (Middle Capacity) | APCS-P□□□MS | L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | APM-SG60M FG60M, SF75G FF75G | <p>Motor Side Connector</p> <p>Drive Side Connector</p> <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> <ol style="list-style-type: none"> 1. Motor Side Connector(MS : Military Standard) <ol style="list-style-type: none"> a. Plug Spec. : MS3108A32-17S 2. Drive Side Connector <ol style="list-style-type: none"> a. Connecting terminal Spec. : 10×5(Ring Terminal) 3. Cable Spec. : 4C×6SQ or 4C×10AWG | PIN No. | Signal | A | U | B | V | C | W | D | Ground |
| PIN No. | Signal | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| General Cable(N) | N03 | N05 | N10 | N20 |
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

L7S Series

L7N Series

L7NH Series

L7P Series

S Series

F Series

MDM Series

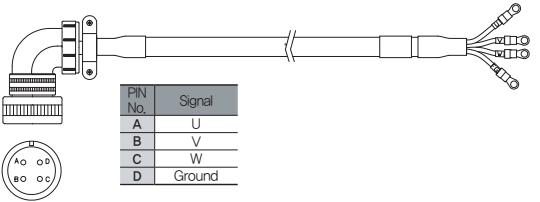
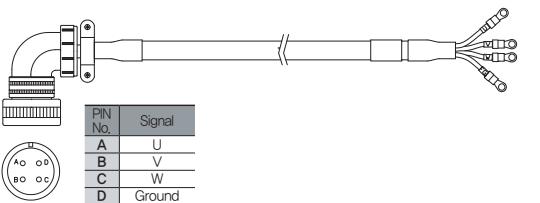
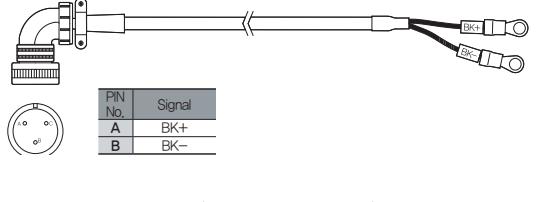
PEGASUS Series

Options

L7 SERIES SYSTEM

Servo Motor Option

■ Power Cable [200V]

| Type | Product Type | Model Name ^(Note1) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | | |
|-----------|-----------------------------|-------------------------------|--|--|---|---------|--------|---|-----|---|-----|---|---|---|--------|--|
| For Power | Power Cable | APCS-P□□□OS | L7NHA□□□U L7PA□□□U | APM-SG85G APM-FG85G APM-SG110D APM-FG110D APM-SG110G APM-FG110G |  <p>Motor Side Connector</p> <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> <p>Drive Side Connector</p> | PIN No. | Signal | A | U | B | V | C | W | D | Ground | <p>1. Motor Side Connector</p> <p>a. Plug Spec. : MS3108A 32-17S</p> <p>2. Drive Side Connector</p> <p>a. Connecting terminal Spec. : 14×6(Ring Terminal)</p> <p>3. Cable Spec. : 4C×16SQ or 4C×5AWG</p> |
| PIN No. | Signal | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | |
| For Power | Power Cable | APCS-P□□□VS | L7NHA□□□U L7PA□□□U | APM-SG150G APM-FG150G |  <p>Motor Side Connector</p> <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> <p>Drive Side Connector</p> | PIN No. | Signal | A | U | B | V | C | W | D | Ground | <p>1. Motor Side Connector (MS: Military Standard)</p> <p>a. Plug Spec. : MS3108A 32-17S</p> <p>2. Drive Side Connector</p> <p>a. Connecting terminal Spec. : 14 x 6(Ring Terminal)</p> <p>3. Power Cable Spec. : 4Cx25SQ or 4C x 3AWG</p> |
| PIN No. | Signal | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | |
| For Power | Power Cable (Brake Type) | APCS-P□□□SB | L7SA□□□A L7SA□□□B L7NA□□□B L7PA□□□U | APM-SG APM-LG APM-FG SERIES |  <p>Motor Side Connector</p> <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>BK+</td> </tr> <tr> <td>B</td> <td>BK-</td> </tr> </table> <p>Drive Side Connector</p> | PIN No. | Signal | A | BK+ | B | BK- | <p>1. Motor Side Connector(MS: Military Standard)</p> <p>a. Plug Spec. : MS3108A 14S-7S</p> <p>2. Drive Side Connector</p> <p>a. Connecting terminal Spec. : 1.5×3(Ring Terminal)</p> <p>3. Cable Spec. : 2C×0.75SQ or 2C×18AWG</p> | | | | |
| PIN No. | Signal | | | | | | | | | | | | | | | |
| A | BK+ | | | | | | | | | | | | | | | |
| B | BK- | | | | | | | | | | | | | | | |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

Note2) In case of 400V products, you can use Robotic Cable only.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

Servo Motor Option

■ Power Cable [400V]

| Type | Product Type | Model Name ^(Note) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | | | | | | |
|-----------|--------------------------|------------------------------|-----------------------------------|--|---|--|---------|--------|---|---|---|---|---|---|---|--------|---|-----|---|-----|
| For Power | Power Cable | APCF-P□□□HS | L7SB□□□B L7NHB□□□U L7PB□□□U | All Models of APM-SEP APM-FEP SERIES | <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> <p>1. Motor Side Connector (MS: Military Standard) a. Plug Spec. : MS3108A 20-4S 2. Drive Side Connector (U,V,W,FG) a. U, V, W Pin Spec. : 1512(Ferrule) b. FG Pin Spec. : 1.5x4(Ring Terminal) 3. Cable Spec. : 4Cx1.5SQ or 4Cx15AWG</p> | | PIN No. | Signal | A | U | B | V | C | W | D | Ground | | | | |
| PIN No. | Signal | | | | | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | | | | | |
| For Power | Power Cable (Brake Type) | APCF-P□□□NB | L7SB□□□B L7NHB□□□U L7PB□□□U | All Models of APM-SEP APM-FEP SERIES | <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> <tr> <td>E</td> <td>BK+</td> </tr> <tr> <td>F</td> <td>BK-</td> </tr> </table> <p>1. Motor Side Connector (MS: Military Standard) a. Plug Spec. : MS3108A 20-15S 2. Drive Side Connector a. U, V, W Pin Spec. : 1512(Ferrule) b. FG Pin Spec. : 1.5 x 4(Ring Terminal) 3. Power Cable Spec. : 4Cx1.5SQ or 4Cx15AWG 4. Brake Power side Connector a. Connecting terminal Spec. : 1.5 x 3(Ring Terminal) 5. Brake Cable Spec. : 2Cx0.75SQ or 2Cx18AWG</p> | | PIN No. | Signal | A | U | B | V | C | W | D | Ground | E | BK+ | F | BK- |
| PIN No. | Signal | | | | | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | | | | | |
| E | BK+ | | | | | | | | | | | | | | | | | | | |
| F | BK- | | | | | | | | | | | | | | | | | | | |
| For Power | Power Cable | APCF-P□□□IS | L7SB□□□B L7NHB□□□U L7PB□□□U | APM-[S/F]FP30A APM-[S/F]FP22D APM-[S/F]FP35D APM-[S/F]FP20G APM-FFP30G APM-[S/F]FP12M APM-[S/F]FP20M APM-[S/F]GP22D APM-[S/F]GP35D APM-[S/F]GP20G APM-FGP30G APM-[S/F]GP12M APM-[S/F]GP20M | <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> <p>1. Motor Side Connector (MS: Military Standard) a. Plug Spec. : MS3108A 22-22S 2. Drive Side Connector (U,V,W,FG) a. U, V, W Pin Spec. : 2512(Ferrule) b. FG Pin Spec. : 2.5x4 (Ring Terminal) 3. Cable Spec. : 4Cx2.5SQ or 4Cx14AWG</p> | | PIN No. | Signal | A | U | B | V | C | W | D | Ground | | | | |
| PIN No. | Signal | | | | | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | | | | | |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

Note2) In case of 400V products, you can use Robotic Cable only.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

L7S Series

L7N Series

L7NH Series

L7P Series

S Series

F Series

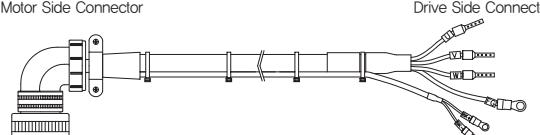
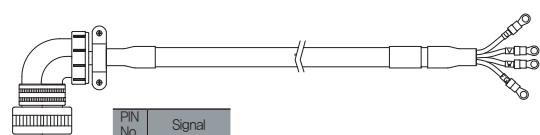
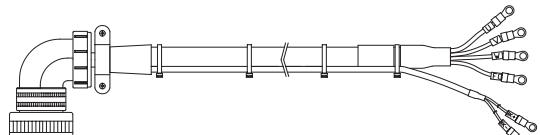
MDM Series

PEGASUS Series

L7 SERIES SYSTEM

Servo Motor Option

■ Power Cable [400V]

| Type | Product Type | Model Name (Note) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | | | | | | |
|-----------|-------------------------------|-------------------|-----------------------------------|--|---|--|---------|--------|---|---|---|---|---|---|---|--------|---|-----|---|-----|
| For Power | Power Cable (Brake Type) | APCF-P□□□PB | L7SB□□□B L7NHB□□□U L7PB□□□U | APM-[S/F]FP30A APM-[S/F]FP22D APM-[S/F]FP35D APM-[S/F]FP20G APM-FFP30G APM-[S/F]FP12M APM-[S/F]FP20M |  <p>1. Motor Side Connector (MS: Military Standard) a. Plug Spec. : MS3108A 24-10S</p> <p>2. Drive Side Connector a. U, V, W Pin Spec. : 2512(Ferrule) b. FG Pin Spec. : 2.5 x 4(Ring Terminal)</p> <p>3. Power Cable Spec. : 4Cx2.5SQ or 4Cx14AWG</p> <p>4. Brake Power side Connector a. Connecting terminal Spec. : 1.5 x 3(Ring Terminal)</p> <p>5. Brake Cable Spec. : 2Cx0.75SQ or 2Cx18AWG</p> | <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> <tr> <td>E</td> <td>BK+</td> </tr> <tr> <td>F</td> <td>BK-</td> </tr> </table> | PIN No. | Signal | A | U | B | V | C | W | D | Ground | E | BK+ | F | BK- |
| PIN No. | Signal | | | | | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | | | | | |
| E | BK+ | | | | | | | | | | | | | | | | | | | |
| F | BK- | | | | | | | | | | | | | | | | | | | |
| For Power | Power Cable (Middle Capacity) | APCF-P□□□JS | L7SB□□□B L7NHB□□□U L7PB□□□U | APM-[S/F]FP50A APM-[S/F]FP50D APM-[S/F]FP75D APM-SFP30G APM-[S/F]FP44G APM-[S/F]FP60G APM-[S/F]FP30M APM-[S/F]FP44M APM-[S/F]GP55D APM-[S/F]GP75D APM-SGP30G APM-[S/F]GP44G APM-[S/F]GP60G APM-[S/F]GP30M APM-[S/F]GP44M |  <p>1. Motor Side Connector (MS: Military Standard) a. Plug Spec. : MS3108A 22-22S</p> <p>2. Drive Side Connector (U,V,W,FG) a. U, V, W Pin Spec. : 4.0x 5(Ring Terminal)</p> <p>3. Cable Spec. : 4Cx4.0SQ or 4Cx11AWG</p> | <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> | PIN No. | Signal | A | U | B | V | C | W | D | Ground | | | | |
| PIN No. | Signal | | | | | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | | | | | |
| For Power | Power Cable (Brake Type) | APCF-P□□□LB | L7SB□□□B L7NHB□□□U L7PB□□□U | APM-[S/F]FP50A APM-[S/F]FP55D APM-[S/F]FP75D APM-SGP30G APM-[S/F]FP44G APM-[S/F]FP60G APM-[S/F]FP30M APM-[S/F]FP44M |  <p>1. Motor Side Connector (MS: Military Standard) a. Plug Spec. : MS3108A 24-10S</p> <p>2. Drive Side Connector a. U, V, W Pin Spec. : 4.0X5(Ring Terminal)</p> <p>3. Power Cable Spec. : 4Cx4.0SQ or 4Cx11AWG</p> <p>4. Brake Power side Connector a. Connecting terminal Spec. : 1.5 x 3(Ring Terminal)</p> <p>5. Brake Cable Spec. : 2Cx0.75SQ or 2Cx18AWG</p> | <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> <tr> <td>E</td> <td>BK+</td> </tr> <tr> <td>F</td> <td>BK-</td> </tr> </table> | PIN No. | Signal | A | U | B | V | C | W | D | Ground | E | BK+ | F | BK- |
| PIN No. | Signal | | | | | | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | | | | | | |
| E | BK+ | | | | | | | | | | | | | | | | | | | |
| F | BK- | | | | | | | | | | | | | | | | | | | |

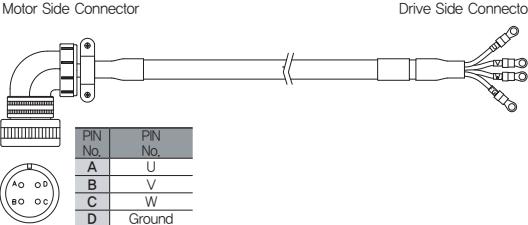
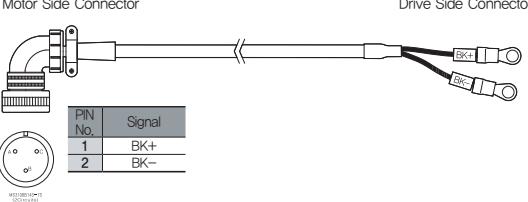
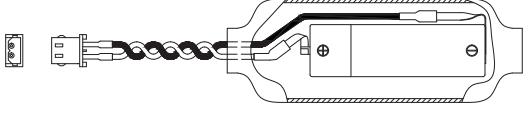
Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

Note2) In case of 400V products, you can use Robotic Cable only.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

Servo Motor Option

■ Power Cable [400V]

| Type | Product Type | Model Name ^(Note1) | Applicable Drive | Applicable Motor | Specifications | | | | | | | | | | |
|---------------------|-------------------------------|-------------------------------|-----------------------------------|---|---|---------|---------|-------|-----|---|-----|---|---|-------|--------|
| For Power | Power Cable (Middle Capacity) | APCF—P□□□MS | L7SB□□□B L7NHB□□□U L7PB□□□U | APM-[S/F]FP75G [S/F]GP110D [S/F]GP85G [S/F]GP110G [S/F]GP150G [S/F]GP60M |  <p>Motor Side Connector</p> <table border="1"> <tr> <td>PIN No.</td> <td>PIN No.</td> </tr> <tr> <td>A</td> <td>U</td> </tr> <tr> <td>B</td> <td>V</td> </tr> <tr> <td>C</td> <td>W</td> </tr> <tr> <td>D</td> <td>Ground</td> </tr> </table> <p>Drive Side Connector</p> <p>1. Motor Side Connector (MS: Military Standard) a. PLUG Spec. : MS3108A 32-17S 2. Drive Side Connector(U,V,W,FG) a. U, V, W Pin Spec. : 10x5(Ring Terminal) 3. Cable Spec. : 4Cx10SQ or 4Cx7AWG</p> | PIN No. | PIN No. | A | U | B | V | C | W | D | Ground |
| PIN No. | PIN No. | | | | | | | | | | | | | | |
| A | U | | | | | | | | | | | | | | |
| B | V | | | | | | | | | | | | | | |
| C | W | | | | | | | | | | | | | | |
| D | Ground | | | | | | | | | | | | | | |
| For Power | Brake Cable (same with 200V) | APCS—P□□□SB | L7SB□□□B L7NHB□□□U L7PB□□□U | All Models of APM-SGP APM-FGP SERIES |  <p>Motor Side Connector</p> <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> </tr> <tr> <td>1</td> <td>BK+</td> </tr> <tr> <td>2</td> <td>BK-</td> </tr> </table> <p>Drive Side Connector</p> <p>1. Motor Side Connector (MS: Military Standard) a. PLUG Spec. : MS3108A 14-17S 2. Drive Side Connector(U,V,W,FG) a. Connecting terminal Spec. : 1.5x3(Ring Terminal) 3. Cable Spec. : 2Cx0.75SQ or 2Cx19AWG</p> | PIN No. | Signal | 1 | BK+ | 2 | BK- | | | | |
| PIN No. | Signal | | | | | | | | | | | | | | |
| 1 | BK+ | | | | | | | | | | | | | | |
| 2 | BK- | | | | | | | | | | | | | | |
| Battery For Encoder | Battery Ass'y | APCS—BATT36 | All L7 Drives for M-tum | All Models of APM-F Series |  <table border="1"> <tr> <td>PIN No.</td> <td>Signal</td> <td>Color</td> </tr> <tr> <td>1</td> <td>+</td> <td>Red</td> </tr> <tr> <td>2</td> <td>-</td> <td>Black</td> </tr> </table> <p>1. PLUG Spec. : 5264-02 (Molex) 2. PLUG Pin Spec. : 5263PBT (Molex) 3. Battery Spec. : ER6V/3.6V, 2000mAh (TOSHIBA)</p> | PIN No. | Signal | Color | 1 | + | Red | 2 | - | Black | |
| PIN No. | Signal | Color | | | | | | | | | | | | | |
| 1 | + | Red | | | | | | | | | | | | | |
| 2 | - | Black | | | | | | | | | | | | | |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

Note2) In case of 400V products, you can use Robotic Cable only.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| General Cable(N) | N03 | N05 | N10 | N20 |
| Robotic Cable(F) | F03 | F05 | F10 | F20 |

L7S Series

L7N Series

L7H Series

L7P Series

S Series

F Series

MDM Series

PEGASUS Series

Options

L7 SERIES SYSTEM

Servo Motor Option

■ DDMotor Signal Cable

| Type | Product type | Model Name(Note1) | Applicable Motor | Specifications | Specifications | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|------------|------------------|-------------------|---|------------------------|--|-----|---------|-----|---------|---|----|----|-----|---|-----|----|---|---|---|----|---|---|----|----|---|---|--------|----|---|---|----|----|---|---|-----|---|---|---|---|---|---|---------|---------|---------|---------|---|---|---|---|---|---|---|---|---|----|----|---|---|----|----|---|---|-----|----|---|---|-----|----|---|---|----|----|-----|-------|--------|--|--|
| For Signal | L7 Encoder Cable | APCS-E□□ZS | L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | All models of DD motor | <p>D.D SERVO ENCODER CABLE</p> <table border="1"> <tr> <td>No.</td> <td>Encoder</td> <td>No.</td> <td>Encoder</td> </tr> <tr> <td>1</td> <td>MA</td> <td>10</td> <td>+5V</td> </tr> <tr> <td>2</td> <td>SLO</td> <td>11</td> <td>-</td> </tr> <tr> <td>3</td> <td>-</td> <td>12</td> <td>-</td> </tr> <tr> <td>4</td> <td>OV</td> <td>13</td> <td>-</td> </tr> <tr> <td>5</td> <td>Shield</td> <td>14</td> <td>-</td> </tr> <tr> <td>6</td> <td>MA</td> <td>15</td> <td>-</td> </tr> <tr> <td>7</td> <td>SLO</td> <td>-</td> <td>-</td> </tr> <tr> <td>8</td> <td>-</td> <td>-</td> <td>-</td> </tr> </table> <p>ENCODER CONNECTOR</p> <p>Cable Bushing</p> <p>Motor Connector</p> <p>Biss Serial Encoder</p> <p>Encoder Cable Connector</p> <p>Driver Connector</p> <table border="1"> <tr> <td>PIN NO.</td> <td>Encoder</td> <td>PIN NO.</td> <td>Encoder</td> </tr> <tr> <td>1</td> <td>-</td> <td>6</td> <td>-</td> </tr> <tr> <td>2</td> <td>-</td> <td>7</td> <td>-</td> </tr> <tr> <td>3</td> <td>MA</td> <td>10</td> <td>-</td> </tr> <tr> <td>4</td> <td>MA</td> <td>11</td> <td>-</td> </tr> <tr> <td>5</td> <td>SLO</td> <td>12</td> <td>-</td> </tr> <tr> <td>6</td> <td>SLO</td> <td>13</td> <td>-</td> </tr> <tr> <td>7</td> <td>OV</td> <td>14</td> <td>+5V</td> </tr> <tr> <td>Plate</td> <td colspan="3">SHIELD</td> </tr> </table> | No. | Encoder | No. | Encoder | 1 | MA | 10 | +5V | 2 | SLO | 11 | - | 3 | - | 12 | - | 4 | OV | 13 | - | 5 | Shield | 14 | - | 6 | MA | 15 | - | 7 | SLO | - | - | 8 | - | - | - | PIN NO. | Encoder | PIN NO. | Encoder | 1 | - | 6 | - | 2 | - | 7 | - | 3 | MA | 10 | - | 4 | MA | 11 | - | 5 | SLO | 12 | - | 6 | SLO | 13 | - | 7 | OV | 14 | +5V | Plate | SHIELD | | |
| No. | Encoder | No. | Encoder | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | MA | 10 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | SLO | 11 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | - | 12 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | OV | 13 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | Shield | 14 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | MA | 15 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | SLO | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | - | - | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| PIN NO. | Encoder | PIN NO. | Encoder | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | - | 6 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | - | 7 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | MA | 10 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | MA | 11 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | SLO | 12 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | SLO | 13 | - | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | OV | 14 | +5V | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Plate | SHIELD | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

■ DDMotor Power Cable

| Type | Product type | Model Name(Note1) | Applicable Motor | Specifications | Specifications | | | | | | | | | | | | | | | | | | | | |
|------------|------------------|-------------------|---|---|---|------|------------------|---------|------------|-------|---|---|-----|--|---|---|-------|--|---|---|-------|--|--------|---|-------|
| For Signal | L7 Power Cable | APCS-P□□DYS | L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | DB03D DB06D DB09D DC06D DC12D DC18D DD12D DD22D DD34D DE40D DE60D | <p>1. Motor Side Connector</p> <p>a. PLUG Spec. : NJC-24-4-ADF(Female connector)</p> <p>2. Drive Side Connector</p> <p>a. U, V, W Pin PG Pin Spec. : UA-F2012(Seoil) (Motor side connector)</p> <p>b. FG Spec. : 1.5×4</p> <p>3. Cable Spec. : 4C×1.5SQ, LAPP Cable(P/N : 00257001)</p> <p>Drive Side Connector</p> <table border="1"> <tr> <td>Item</td> <td>Lead Wire Signal</td> <td>Pin NO.</td> <td>Line color</td> </tr> <tr> <td>Motor</td> <td>U</td> <td>1</td> <td>Red</td> </tr> <tr> <td></td> <td>V</td> <td>2</td> <td>White</td> </tr> <tr> <td></td> <td>W</td> <td>3</td> <td>Black</td> </tr> <tr> <td></td> <td>Ground</td> <td>4</td> <td>Green</td> </tr> </table> | Item | Lead Wire Signal | Pin NO. | Line color | Motor | U | 1 | Red | | V | 2 | White | | W | 3 | Black | | Ground | 4 | Green |
| Item | Lead Wire Signal | Pin NO. | Line color | | | | | | | | | | | | | | | | | | | | | | |
| Motor | U | 1 | Red | | | | | | | | | | | | | | | | | | | | | | |
| | V | 2 | White | | | | | | | | | | | | | | | | | | | | | | |
| | W | 3 | Black | | | | | | | | | | | | | | | | | | | | | | |
| | Ground | 4 | Green | | | | | | | | | | | | | | | | | | | | | | |
| For Signal | L7 Power Cable | APCS-P□□DZS | L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U | DFA1G DFA6G | <p>1. Motor Side Connector</p> <p>a. PLUG Spec. : NJC-24-4-ADF(Female connector)</p> <p>2. Drive Side Connector</p> <p>a. U, V, W Pin PG Pin Spec. : UA-F2012(Seoil) (Motor side connector)</p> <p>b. FG Spec. : 2.5×4</p> <p>3. Cable Spec. : 4C×2.5SQ, LAPP Cable(P/N : 00257011)</p> <p>Drive side connector</p> <table border="1"> <tr> <td>Item</td> <td>Lead Wire Signal</td> <td>Pin NO.</td> <td>Line color</td> </tr> <tr> <td>Motor</td> <td>U</td> <td>1</td> <td>Red</td> </tr> <tr> <td></td> <td>V</td> <td>2</td> <td>White</td> </tr> <tr> <td></td> <td>W</td> <td>3</td> <td>Black</td> </tr> <tr> <td></td> <td>Ground</td> <td>4</td> <td>Green</td> </tr> </table> | Item | Lead Wire Signal | Pin NO. | Line color | Motor | U | 1 | Red | | V | 2 | White | | W | 3 | Black | | Ground | 4 | Green |
| Item | Lead Wire Signal | Pin NO. | Line color | | | | | | | | | | | | | | | | | | | | | | |
| Motor | U | 1 | Red | | | | | | | | | | | | | | | | | | | | | | |
| | V | 2 | White | | | | | | | | | | | | | | | | | | | | | | |
| | W | 3 | Black | | | | | | | | | | | | | | | | | | | | | | |
| | Ground | 4 | Green | | | | | | | | | | | | | | | | | | | | | | |

Note1) □□□ of Model Name indicates the kind and length of cable. And the declaration is as below.

Note2) In Case of DD Motor, we don't supply power cable for robotic cable.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| Robotic Cable(F) | F03 | F05 | F10 | F20 |
| General Cable(N) | N03 | N05 | N10 | N20 |

Servo Drive Option

■ Signal Cable

| Type | Product type | Model Name ^(Note1) | Applicable Motor | Specifications | |
|------------|--------------|-------------------------------|---------------------------|--|--|
| T/B | CN1 T/B | APC-VSCN1T -□□ | L7S□□□□B L7PA□□□U | <p>1. Extended CN1 T/B for VS/L7S</p> <p>2. Available Cable Length : 0.5[m], 1[m], 1.5[m], 2[m], 3[m]</p> | |
| | CN1 T/B | APCS-L7NCN1T -□□ | L7NA□□□B L7NH□□□U | <p>1. Extended CN1 T/B for L7N</p> <p>2. Available Cable Length : 0.5[m], 1[m], 1.5[m], 2[m]</p> | |
| For Signal | CN1 Cable | APC-CN1□□A | L7S SERIES L7P SERIES | <p>[Upper Controller] [Drive Connection Side CN1]</p> <p>Indicates Pin No</p> <p>1. Drive Side Connection(CN1)</p> <ul style="list-style-type: none"> a. Case Spec. : 10350-52A0-008(3M) b. Connector Spec. : 10150-3000VE(3M) c. Cable Spec. : 20276-SB 25P(AWG28) | |
| For Signal | CN1 Cabl | APCS-CN1□□A | L7N SERIES L7NH SERIES | <p>[Upper Controller] [Drive Connection Side CN1]</p> <p>Indicates Pin No</p> <p>1. Drive Side Connection(CN1)</p> <ul style="list-style-type: none"> a. Case Spec. : 10320-52A0-008(3M) b. Connector Spec. : 10120-3000VE(3M) c. Cable Spec. : ROW-SB0.1C×20C(AWG28) | |

Note1) □□ of Model Name indicates the kind and length of cable And the designation is as below. CN1 cable : 1m, 2m, 3m and 5m are available.

| Cable Length(m) | 3 | 5 | 10 | 20 |
|------------------|-----|-----|-----|-----|
| Robotic Cable(F) | N03 | N05 | N10 | N20 |
| General Cable(N) | F03 | F05 | F10 | F20 |

*APC-VSCN1T

*APCS-L7NCN1T

| Cable Length(m) | 0.5 | 1 | 1.5 | 2 | 3 | Cable Length(m) | 0.5 | 1 | 1.5 | 2 | 3 |
|-----------------|------|----|-----|----|----|-----------------|------|----|-----|----|----|
| Declaration | None | 01 | 015 | 02 | 03 | Declaration | None | 01 | 015 | 02 | 03 |

L7S Series

L7N Series

L7NH Series
L7P Series

S Series
F Series

MDM Series

PEGASUS Series

Options

L7 SERIES SYSTEM

Servo Drive Option

L7 Pin Map

L7S

| NO | PIN Function |
|----|--------------|----|--------------|----|--------------|----|--------------|----|--------------|
| 1 | TRQCOM | 11 | PR+ | 21 | SPD3 | 31 | /BO | 41 | RDY |
| 2 | | 12 | PR- | 22 | SPD2 | 32 | AO | 42 | |
| 3 | | 13 | | 23 | SPD1 | 33 | /AO | 43 | ZSPD |
| 4 | ZO | 14 | ALO2 | 24 | GND24 | 34 | +12VA | 44 | BRAKE |
| 5 | /ZO | 15 | ALO1 | 25 | GND24 | 35 | -12VA | 45 | INPOS |
| 6 | | 16 | ALO0 | 26 | | 36 | SG | 46 | DIR |
| 7 | | 17 | ALMRST | 27 | SPDCOM | 37 | GND | 47 | SVON |
| 8 | GND | 18 | EMG | 28 | MINIY1 | 38 | ALARM+ | 48 | STOP |
| 9 | PF+ | 19 | CWLIM | 29 | MINIY2 | 39 | ALARM- | 49 | PULCOM |
| 10 | PF- | 20 | CCWLIM | 30 | BO | 40 | RDY+ | 50 | +24V IN |

L7P

| NO | PIN Function |
|----|--------------|----|--------------|----|--------------|----|--------------|----|--------------|
| 1 | AO | 11 | +24V IN | 21 | +24V IN | 31 | PF+ | 41 | INPOS1+ |
| 2 | /AO | 12 | SVON | 22 | HOME | 32 | PF- | 42 | INPOS1- |
| 3 | BO | 13 | POT | 23 | H-START | 33 | PR+ | 43 | ORG+ |
| 4 | /BO | 14 | NOT | 24 | ISEL0 | 34 | PR- | 44 | ORG- |
| 5 | ZO | 15 | A-RST | 25 | ISEL1 | 35 | ALARM+ | 45 | EOS+ |
| 6 | /ZO | 16 | START | 26 | ISEL2 | 36 | ALARM- | 46 | EOS- |
| 7 | A-TLMT | 17 | STOP | 27 | ISEL3 | 37 | RDY+ | 47 | TGON+ |
| 8 | AGND | 18 | REGT | 28 | ISEL4 | 38 | RDY- | 48 | TGON- |
| 9 | A-OVR | 19 | EMG | 29 | ISEL5 | 39 | BRAKE+ | 49 | TLMT+ |
| 10 | AGND | 20 | | 30 | PULCOM | 40 | BRAKE- | 50 | TLMT- |

L7N

| NO | PIN Function | NO | PIN Function |
|----|--------------|----|--------------|
| 1 | BREAK+ | 11 | HOME |
| 2 | BREAK- | 12 | ALMRST |
| 3 | ALARM+ | 13 | PCON |
| 4 | ALARM- | 14 | GAIN2 |
| 5 | | 15 | |
| 6 | +24V IN | 16 | |
| 7 | N-OT | 17 | READY+ |
| 8 | P-OT | 18 | READY- |
| 9 | PROBE1 | 19 | ZSPD+ |
| 10 | PROBE2 | 20 | ZSPD- |

L7NH

| NO | PIN Function | NO | PIN Function |
|----|--------------|----|--------------|
| 1 | BREAK+ | 11 | POT |
| 2 | BREAK- | 12 | NOT |
| 3 | RDY+ | 13 | PCON |
| 4 | RDY- | 14 | GAIN2 |
| 5 | AGND | 15 | A-TLMT |
| 6 | +24V IN | 16 | |
| 7 | HOME | 17 | RDY+ |
| 8 | STOP | 18 | RDY- |
| 9 | PCL | 19 | ZSPD+ |
| 10 | NCL | 20 | ZSPD- |

Signal Cable / Connector

| Type | Product type | Model Name ^(Note1) | Applicable Motor | Specifications | |
|------------|---------------------|-------------------------------|-------------------------|---|--|
| For Signal | Communication Cable | APC-CN5L7U | All Models of L7 SERIES | [PC – USB Port]  [Servo Drive – CN5]  1. PC Side Connector : USB A Plug 2. Drive Side Connector(CN5) : Mini USB 5P Plug 3. Electric Requirements Spec : Double Shielded, Twisted Pair, EMI-filter attached type (Ex. : KU-AMB518, SANWA) 4. Only 1.8m length of cable is available to use | |

Servo Drive Option

Connector

| Type | Product Type | Model Name ^(Note1) | Applicable Drive | Specifications | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|------|-------------------------------------|-------------------------------|-------------------------|--|---|-------------|--------------|---|--------------|--------|---|-------------|--------------|---|-------------|------|---|--------------|------------|---|--------------|-------|---|-------------|-------------|---|--------------|-------|--|-------|--------|
| CN | CN1 Connector | APC-CN1NNA | L7S□□□B L7PA□□□U | 1. Case Spec. : 10350-52A0-008(3M) 2. Connector Spec. : 10150-3000VE(3M) | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| CN | CN1 Connector | APC-CN2NNA | L7NA□□□B L7NH□□□U | 1. Case Spec. : 10320-52A0-008(3M) 2. Connector Spec. : 10120-3000VE(3M) | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| CN | CN2 Connector | APC-CN3NNA | All Models of L7 SERIES | 1. Case Spec. : 10314-52A0-008(3M) 2. Connector Spec. : 10114-3000VE(3M) | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| CN | CN3 CN4 EtherCAT Connector | APCS-CN4NNA | L7NA□□□B L7NH□□□U | RJ-45 PLUG (8 Pins) <table border="1"> <caption>PIN No., Signal, Color</caption> <tr><td>1</td><td>TX/RX0 Plus</td><td>White/Orange</td></tr> <tr><td>2</td><td>TX/RX0 Minus</td><td>Orange</td></tr> <tr><td>3</td><td>TX/RX1 Plus</td><td>White/Orange</td></tr> <tr><td>4</td><td>TX/RX2 Plus</td><td>Blue</td></tr> <tr><td>5</td><td>TX/RX2 Minus</td><td>White/Blue</td></tr> <tr><td>6</td><td>TX/RX1 Minus</td><td>Green</td></tr> <tr><td>7</td><td>TX/RX3 Plus</td><td>White/Brown</td></tr> <tr><td>8</td><td>TX/RX3 Minus</td><td>Brown</td></tr> <tr><td></td><td>Plate</td><td>SHILDE</td></tr> </table> <p>Note) EtherCAT use only 4wires(1, 2, 3, 6)</p> | 1 | TX/RX0 Plus | White/Orange | 2 | TX/RX0 Minus | Orange | 3 | TX/RX1 Plus | White/Orange | 4 | TX/RX2 Plus | Blue | 5 | TX/RX2 Minus | White/Blue | 6 | TX/RX1 Minus | Green | 7 | TX/RX3 Plus | White/Brown | 8 | TX/RX3 Minus | Brown | | Plate | SHILDE |
| 1 | TX/RX0 Plus | White/Orange | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | TX/RX0 Minus | Orange | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | TX/RX1 Plus | White/Orange | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | TX/RX2 Plus | Blue | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 5 | TX/RX2 Minus | White/Blue | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 6 | TX/RX1 Minus | Green | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 7 | TX/RX3 Plus | White/Brown | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 8 | TX/RX3 Minus | Brown | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | Plate | SHILDE | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| CN | STO Cable | APCS-STO□□A | L7NA□□□B L7NH□□□U | 1. Cable Length : Only 0.3[m], 1[m], 3[m] of Cable is available to use. 2. Connector Model Name : APSC-ST000A * Caution : During assembly of connector, It can be broken easily without guaranty of LS Mecapion. | | | | | | | | | | | | | | | | | | | | | | | | | | | |

Note1) □□ of Model Name indicates the kind and length of cable. And the declaration is as below.

*APCS-STO□□A

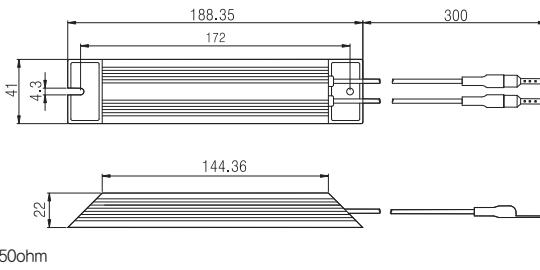
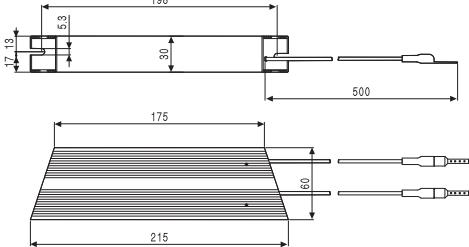
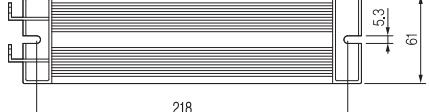
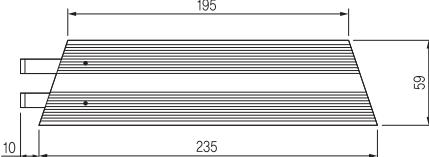
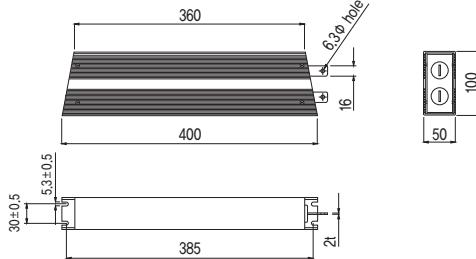
| | | | |
|-----------------|-----|----|----|
| Cable Length(m) | 0.3 | 1 | 3 |
| Declaration | 03 | 10 | 30 |

L7 SERIES SYSTEM

Other Options

■ 200V Braking Resistor

* Option braking resistors are selectable items for user's need.

| Type | Product Type | Model Name ^(Note1) | Applicable Drive | Specifications |
|----------|------------------|---|----------------------------------|---|
| Resistor | Braking Resistor | APCS-140R50 50Ω/140W | L7□A001□ L7□A002□ L7□A004□ |  <p>IRH 140W 50ohm</p> |
| Resistor | Braking Resistor | APCS-300R30 30Ω/300W | L7□A008□ L7□A010□ |  <p>IRV 300W 30ohm</p> |
| Resistor | Braking Resistor | APC-600R30 15Ω/1200W (30Ω/600*2P) | L7□A020□ |  |
| | | APC-600R30 10Ω/1800W (30Ω/600*3P) | L7□A035□ |  <p>IRV 600S 30ohm IRV 600S 28ohm</p> <p>* L7□A020□ – 2pcs * L7□A050□ – 4pcs (Parallel Connection) L7□A075□ L7□A035□ – 3pcs (Parallel Connection) (Parallel Connection)</p> <p>Note) IRV 600S 30ohm and 600S 28ohm have the same external dimensions.</p> |
| | | APC-600R28 7Ω/2400W (28Ω/600*4P) | L7□A050□ L7□A075□ | |
| Resistor | Braking Resistor | APCS-2000R3.3 3.3Ω/2000W | L7□A150□ |  <p>IRM2000-3.3Ω</p> |

Note1) L7 Series 100W~7.5kW has the internal basic braking resistor. If the machine requires short deceleration time frequently, refer to table above and apply the appropriate braking resistor.

Other Options

■ 400V Braking Resistor

* Option braking resistors are selectable items for user's need.

| Type | Product Type | Model Name (Note1) | Applicable Drive | Specifications |
|----------|------------------|---|----------------------|--|
| Resistor | Braking Resistor | APCS-300R82 82Ω/300W | L7□B010□ | <p>IRV 300W 82ohm</p> |
| Resistor | Braking Resistor | APCS-600R140 70Ω/1200W (140Ω/600W*2P) | L7□B020□ L7□B035□ | <p>IRV 600W 140ohm</p> |
| Resistor | Braking Resistor | APCS-600R75 25Ω/1800W (75Ω/600W*3P) | L7□B050□ L7□B075□ | <p>IRV 600W 75ohm (3PCS Parallel connection)</p> |
| Resistor | Braking Resistor | APCS-2000R13.4 13.4Ω/2000W | L7□B150□ | <p>IRM 2000W 13.4ohm</p> |

Note1) L7 Series 100W~7.5kW has the internal basic braking resistor. If the machine requires short deceleration time frequently, refer to table above and apply the appropriate braking resistor.

L7S Series

L7N Series

L7NH Series
L7P Series

S Series
F Series

MDM Series

PEGASUS Series
Options

L7 SERIES SYSTEM

Servo Drive Option

Noise Filter

| Type | Product Type | Model Name | Applicable Drive | Specifications |
|-----------------------------|-------------------|--|--|----------------|
| Resistor Noise Filter | APCS-TB6-B010LB/E | L7□A 001□ L7□A 002□ L7□A 004□ L7□A 008□ L7□A 010□ L7□B 010□ | L7□A 001□ L7□A 002□ L7□A 004□ L7□A 008□ L7□A 010□ L7□B 010□ | |
| | | L7□B 020□ L7□B 035□ | | |
| | | L7□A 020□ L7□A 035□ L7□B 050□ | | |
| | APCS-TB6-B040AS | L7□A 050□ L7□B 075□ | L7□A 050□ L7□B 075□ | |
| | APCS-TB6-B060LAS | L7□B 150□ | L7□B 150□ | |

Contents

■ Integrated Servo System

PEGASUS Series

Integrated Servo System (EtherCAT)

- Servo Drive Designation _ 116
- Product Feature _ 117
- External Dimensions _ 120



L7S Series

L7N Series

L7P Series

S Series

F Series

MDM Series

Options

PEGASUS Series

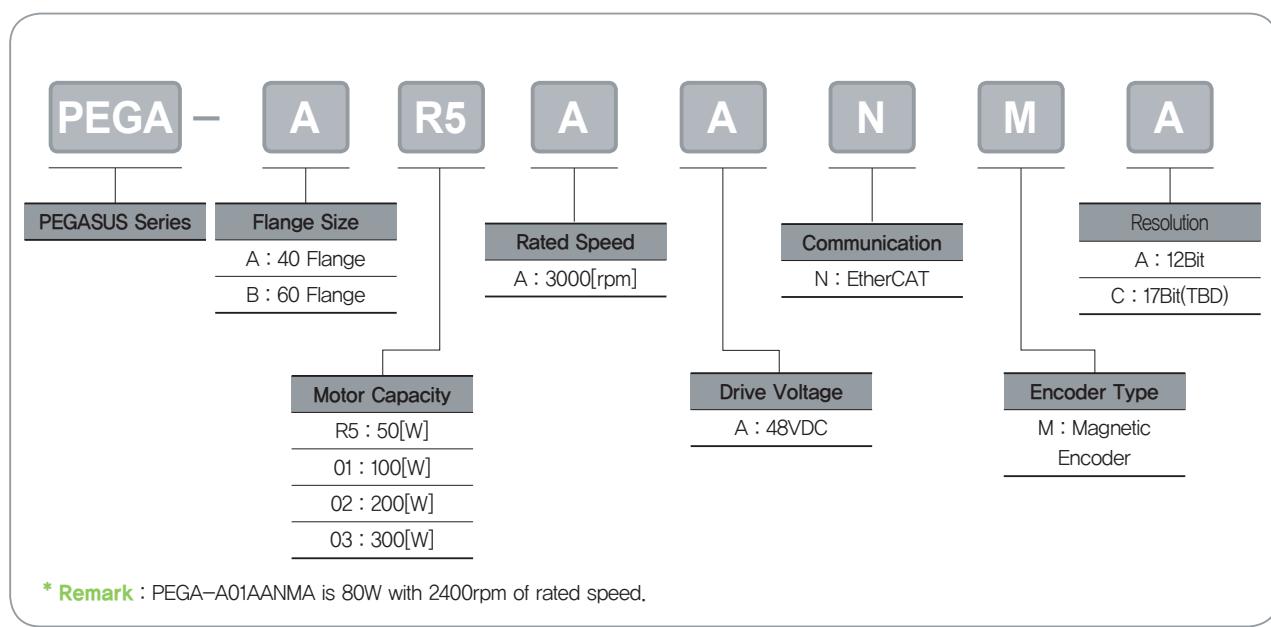
L7 SERIES SYSTEM

Integrated Servo System (EtherCAT)

| PEGASUS Series



■ Servo Drive Designation



PEGASUS Series

Characteristic

● Enhanced efficiency integrated servo system

- Cost effective from installation by integrated system of motor, encoder cable and drive
- Maximization for useful space when installed at limited and small space
- High effectiveness for application of multi axis because there is no limitation for space of installation

● Real-time control through EtherCAT

- High speed, Real-time capability and Synchronization mechanism
- Improved EtherCAT communication speed
- Supporting CoE, EoE and FoE

Identifying the Part of PEGASUS Series



① Input / Output Signal Connector (CN1)

- This Connector is for Sequence Input / Output Signals

② EtherCAT Communication Output Port (OUT)

③ Status LED

- It Indicates the current state of Ether CAT Communication

④ Power Connector (CN3)

⑤ USB Connector (CN5, Mini B type)

- This Connector is to Communicate With a PC

⑥ Node Address Setting Switch

- This Switch is to set the node address of the drive You can set the node addresses from 0 to 15

⑦ EtherCAT Communication Input Port (IN)

⑧ Safety Connector (CN2)

- This Connector connects Safety Devices

L7S Series

L7N Series

L7NH Series

L7P Series

S Series

F Series

MDM Series

Options

PEGASUS Series

L7 SERIES SYSTEM

Specifications of PEGASUS Series

■ Rated Values of Servo Drive

| Rated values for servo drive | <input type="checkbox"/> 40 50W | <input type="checkbox"/> 40 100W | <input type="checkbox"/> 60 100W | <input type="checkbox"/> 60 200W | <input type="checkbox"/> 60 300W |
|----------------------------------|---------------------------------|----------------------------------|----------------------------------|----------------------------------|----------------------------------|
| Continuous output current [Arms] | 1.77 | 2.38 | 3.62 | 5 | 6.8 |
| Maximum output current [Arms] | 3.54 | 3.57 | 7.24 | 10 | 13.6 |
| Input voltage | DC 48V ~ DC 60V | | | | |

■ Basic Specifications

| Category | | | Details |
|---|---|--|--|
| Use conditions | Control method | PWM controlled sine wave current driving method | |
| | Operating temperature / storage temperature | 0~+40[°C] / -20~ +60[°C] | |
| | Operating humidity / storage humidity | Below 80% RH / Below 90% RH (no freeze or condensation) | |
| | Vibration-/impact-resistance | TBD | |
| | Degree of protection / degree of pollution | TBD | |
| | Altitude | 1000 m or lower | |
| | Other | To be free from electrostatic noise, strong electrolysis, or radiation. | |
| Performance | Speed variation | Load variation | At 0 to 100% load: ±3% (at rated speed) |
| | | Voltage variation | Rated voltage ± 10%: 0% (at rated speed) |
| | | Temperature variation | 25°C: ± 0.1% or less (at rated speed) |
| Input/output signal | Input signal | | Input voltage range: DC 12 V – DC 30 V The 4-channel input signal can be assigned to 12 functions: POT, NOT, HOME, STOP, PCON, GAIN2, PCL, NCL, PROBE1, PROB2, EMG, and ARST. |
| | Output signal | | Rated voltage and current: DC 24 V ± 10%, 120 [mA] The 2-channel output signal can be assigned to 11 functions: BRAKE, ALARM, RDY, ZSPD, INPOS1, TLMT, VLMT, INSPD, WARN, TGON, and INPOS2. |
| Analog Monitor | | | Number of channels: 1 Output voltage range: ±4V Angular resolution: 12 bits Stabilization time: 15 us |
| USB communication | Connecting device | PC or USB storage medium | |
| | Communication standard | Conform to the USB 2.0 Full Speed Standard. | |
| | Function | Firmware download, parameter setting, adjustment, auxiliary functions, and parameter copy function. | |
| Dynamic brake (three-phase short-circuit) | | Activates when servo alarm, servo OFF, or Emergency stop (POT, NOT and EMG) is input. | |
| Protection functions | | Overcurrent, overload, current limit, overheat, overvoltage, undervoltage, overspeed, encoder error, position follow error, etc. | |
| Auxiliary functions | | Gain adjustment, alarm history, JOG drive, programmed JOG drive, etc. | |
| Safety functions | Input | STO1 and STO2 | |
| | Compatible standard | TBD | |

Specifications of PEGASUS Series

EtherCAT Communication Specification

| Category | | Details |
|------------------------|-----|---|
| Communication standard | FoE | Firmware download |
| | EoE | Parameter setting, adjustment, auxiliary functions, and parameter copy through UDP. |
| | CoE | IEC 61158 Type12, IEC 61800-7 CiA 402 drive profile |
| Physical layer | | 100BASE-TX (IEEE802.3) |
| Connector | | RJ45 x 2 |
| Distance | | Within 100 m between nodes |
| DC (Distributed Clock) | | Sync by DC mode |
| LED Display | | L/A0(Link/Act IN) L/A1(Link/Act OUT) RUN ERR |
| CiA402 drive Profile | | Supports CSP, CSV, CST, PP, PV, PT, and HM Modes. |

Motor Specification

| Model | Unit | SAR5A-8 | SA01A-8 | SB01A-6 | SB02A-9 | SB03A-9 |
|---------------|---|--------------------------|---------|---------|---------|---------|
| Frame Size | [mm] | 40 | 40 | 60 | 60 | 60 |
| Rated Power | [W] | 50 | 80 | 100 | 200 | 300 |
| Rated Torque | [N m] | 0.16 | 0.32 | 0.32 | 0.64 | 0.95 |
| | [Kgf cm] | 1.62 | 3.25 | 3.25 | 6.5 | 9.74 |
| Rated Speed | [rpm] | 3,000 | 2,400 | 3,000 | 3,000 | 3,000 |
| Inertia | [gf cm s ²] | 0.02 | 0.0435 | 0.114 | 0.186 | 0.328 |
| | [Kg m ² x 10 ⁻⁴] | 0.02 | 0.0426 | 0.116 | 0.182 | 0.321 |
| Rated Voltage | [Vdc] | Input Power : 48VDC | | | | |
| Encoder Type | - | Magnetic Encoder (12bit) | | | | |

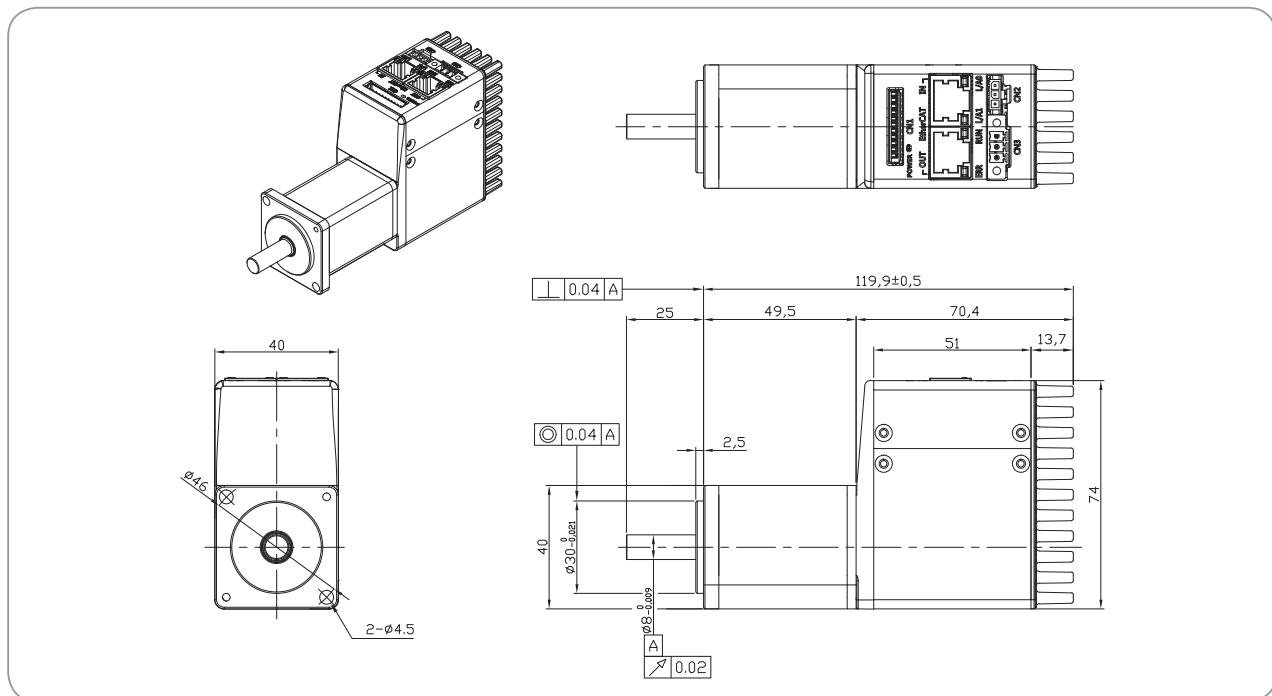
Note1) SA01A-8 can be operated at 3000rpm(100w) with 60Vdc of input power(instead of 48Vdc)

L7 SERIES SYSTEM

External Dimensions of PEGASUS Series

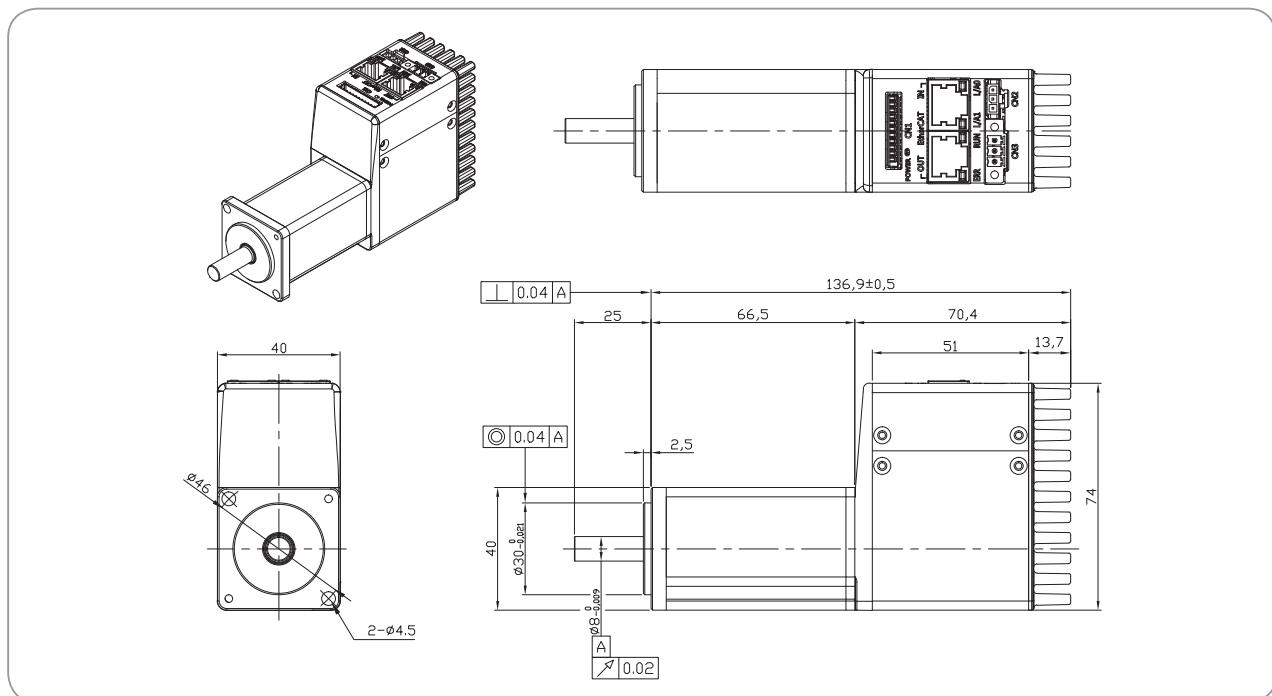
■ PEGA-AR5A

* Unit [mm]



■ PEGA-A01A

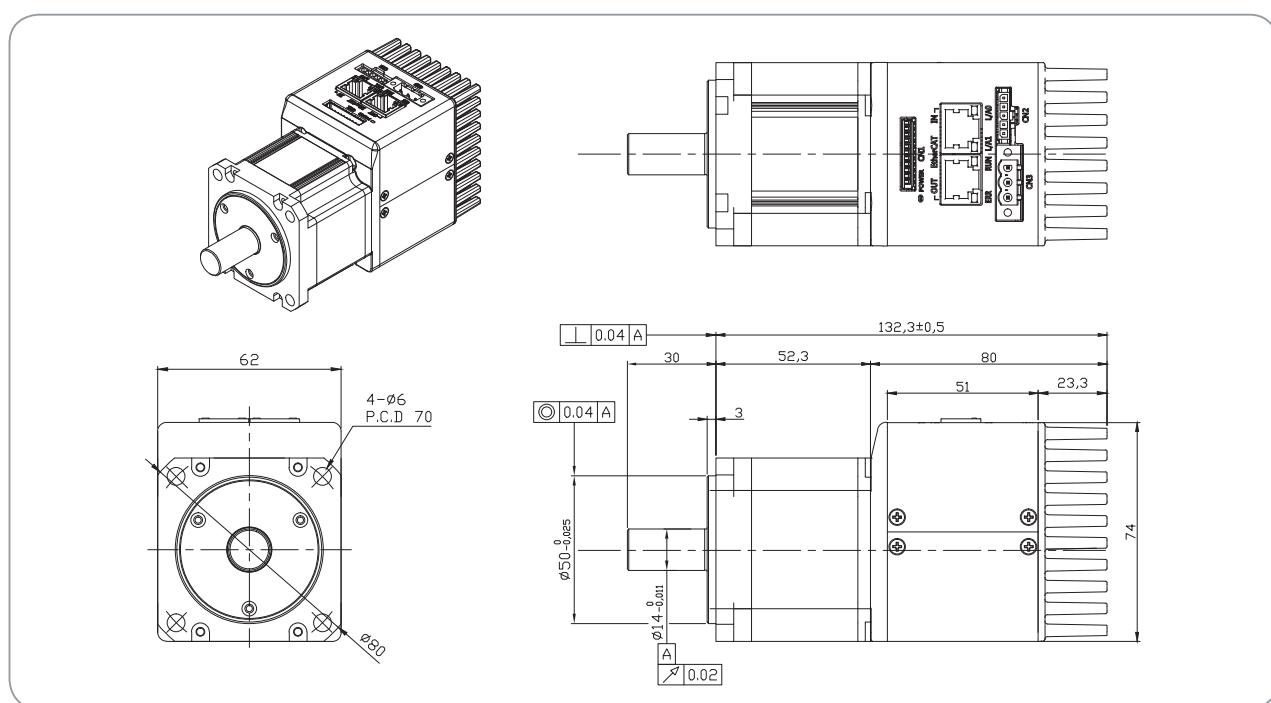
*Unit [mm]



External Dimensions of PEGASUS Series

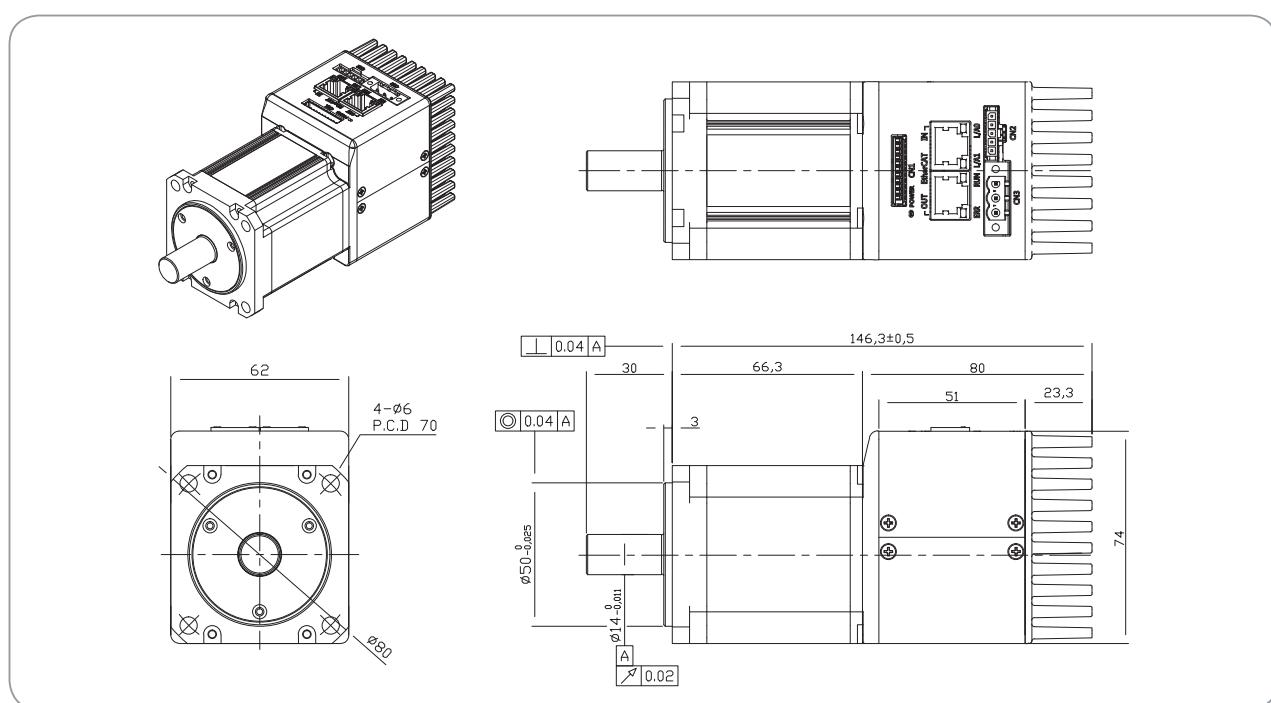
■ PEGA-B01A

* Unit [mm]



■ PEGA-B02A

* Unit [mm]



L7S Series

L7N Series

L7NH Series

L7P Series

F Series

MDM Series

Options

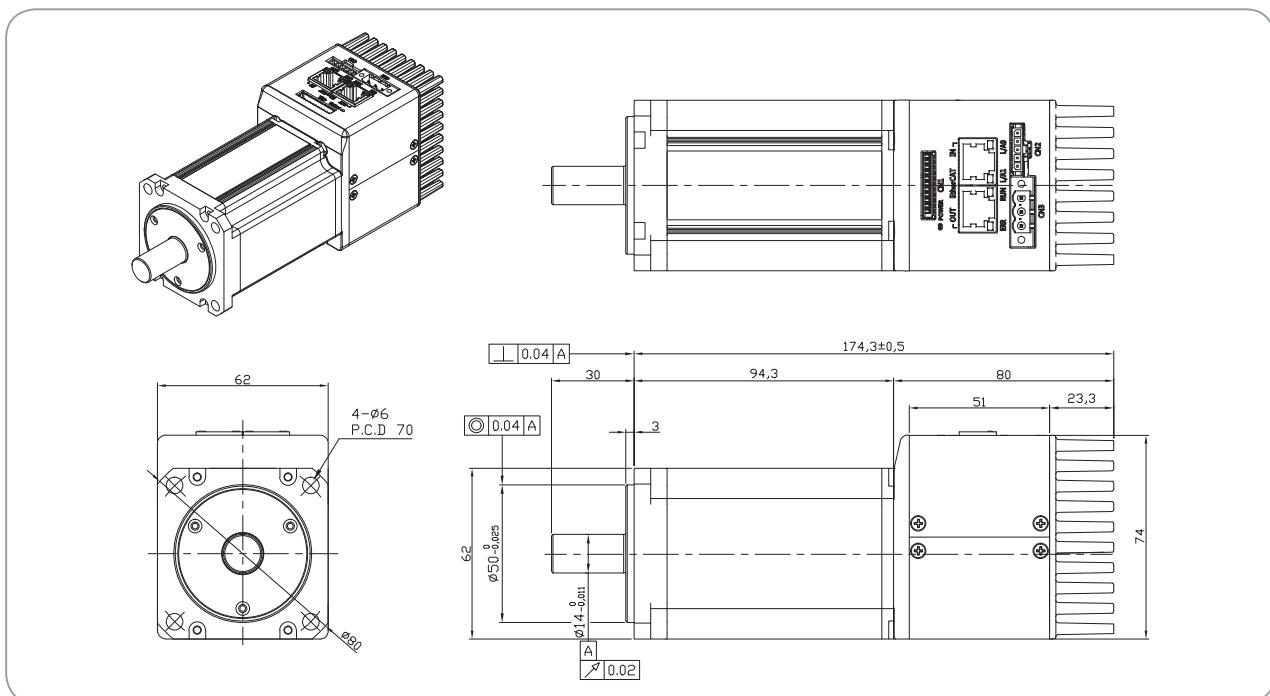
PEGASUS Series

L7 SERIES SYSTEM

External Dimensions of PEGASUS Series

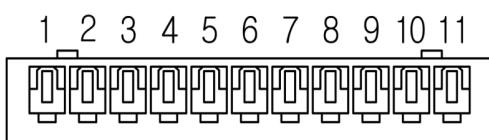
■ PEGA-B03A

* Unit [mm]



■ Accessory Kit

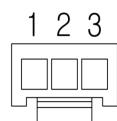
CN1 : I/O Connector



51004-1100 (MOLEX)

| Pin Number | Direction | Name | Signals | Descriptions |
|------------|-----------|----------|-----------------------|------------------------------|
| 1 | VCC | +24V | +24V INPUT | +24V Vcc Input |
| 2 | Input | POT | Positive Over-Traverl | Limit Sensor Input |
| 3 | Input | NOT | Negative Over Traverl | |
| 4 | Input | HOME | Home Sensor | Home Sensor Input for Homing |
| 5 | Input | STOP | Stop Input | Stop Command Input |
| 6 | Output | BRAKE+ | BRAKE | Output Brake Control Signal |
| 7 | Output | BRAKE- | | |
| 8 | Output | ALARM+ | Alarm Output | Servo Alarm Output |
| 9 | Output | ALARM- | | |
| 10 | Output | MONITOR1 | Analog Monitor | Analog Monitor Output(0V~5V) |
| 11 | GND | AGND | AGND(0V) | Analog Signal Graound |

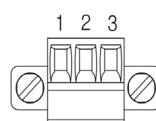
CN2 : Safe Torque Off Connector



43645-3 (MOLEX)

| Pin Number | Name | Descriptions |
|------------|--------|------------------------------------|
| 1 | HWBB1 | Safe Torque Off(STO) input signals |
| 2 | HWBB2 | |
| 3 | COMMON | DC 24V GND |

CN3 : Power Connector



MC_1.5-3-STF-3.5
(PHOENIX CONTACT)

| Pin Number | Name | Descriptions |
|------------|-------------|--------------|
| 1 | FG | Frame Ground |
| 2 | N(DC 0V) | DC 0V GND |
| 3 | VCC(DC 48V) | DC 48V input |

MEMO



MEMO



MEMO



MEMO



MEMO



MEMO

